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Reflected-Scene Impostors for Realistic
Reflections at Interactive Rates

Reflections—a difficult problem


- Every reflector is a portal onto a world which is as rich as the directly observed scene and which has complex image formation laws

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Prior work—vast


Ray tracing	Image-Based Rendering
Feed-forward reflection rendering	Approximation of reflected scene



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Problem of rendering reflections

- Compute
 - Intersection with reflector
 - Reflected ray
 - Intersection with reflected scene
 - antialiasing




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Problem of rendering reflections

- Compute
 - Intersection with reflector
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 - antialiasing

“OpenGL”


???



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Reflected-scene approximation

- Reflected scene replaced with approx. that provides
 - Fast intersection with ray
 - Antialiasing



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Reflected-scene approximation

- Example: environment mapped reflections
 - Reflected scene infinitely far away
 - Straight forward intersection with ray
 - Antialiasing computed in 2D (mipmapping)



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Reflected-scene approximation

- Example: environment mapped reflections
 - Reflected scene infinitely far away
 - Straight forward intersection with ray
 - Antialiasing computed in 2D (mipmapping)
 - Drastic approximation, incorrect results close to the reflector



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Our approach

- Approximate reflected scene with impostors
 - Considerable prior work on impostors
 - Reflector surface prevents desired viewpoint from getting too close to the impostor
 - Reflection distortion hides impostor artifacts



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Impostor requirements

- Impostor has to provide
 - Fast construction
 - Fast intersection with ray
 - Antialiasing



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Results: billboard impostors



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Results: depth image impostors



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Billboard impostors


- Replace reflected object with billboard
- Higher order reflections
 - Reflective billboards (normal mapped quads)



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Billboard impostors


- Impostor has to provide
 - Fast construction **YES**
 - Fast intersection with ray **YES**
 - Antialiasing **YES**



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Pixel algorithm


- For D diffuse, R reflective billboards, and maximum reflection order K
 - Compute reflected ray r
 - For reflection order 1 to K
 - Intersect with $(D+R-1)$ billboards
 - If no intersection
 - return $EM(r)$
 - Else if intersection with diffuse billboard DB_i
 - return $DB_i(r)$
 - Else if intersection with reflective billboard DB_j
 - $r = DB_j(r)$



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Pixel algorithm

- For D diffuse, R reflective billboards, and maximum reflection order K
 - Compute reflected ray r
 - For reflection order 1 to K
 - Intersect with $(D+R-1)$ billboards
 - If no intersect
 - return $EM(r)$
 - Else if intersect **$O(K*(D+R))$**
 - return $DB_i(r)$
 - Else if intersection with reflective billboard DB_j
 - $r = DB_j(r)$




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Example: 4 teapots




- $D = 1, R = 4,$
 $D+(R-1)+D = 5$
intersections / pix
- 12 second order reflections
- 40fps




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Example: table scene




- $D = 2, R = 2,$
 $D+(R-1)+D = 5$
intersections / pix
- 2 second order reflections
- 33 fps




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Example: table scene





- $D = 2, R = 2,$
 $D+(R-1)+D = 5$
intersections / pix
- 2 second order reflections
- 33 fps



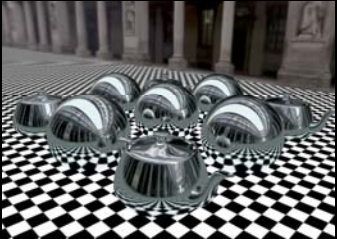
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Example: table scene





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Example: pushing-it scene




- $D = 2, R = 9,$
 $D+(R-1)+D = 11$
intersections / pix
- 72 second order reflections
- 11 fps




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Example: pushing-it scene





- $D = 2, R = 9,$
 $D+(R-1)+D = 11$
intersections / pix
- 72 second order reflections
- 6 fps



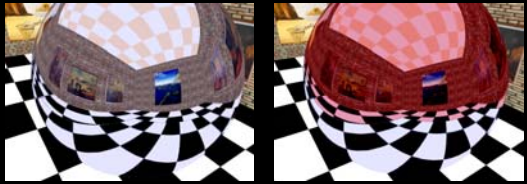
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Example: pushing-it scene





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Problem

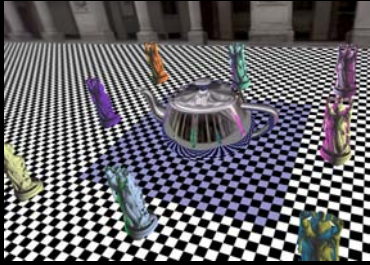


Transition from impostor to environment map (red in left image) is discontinuous.



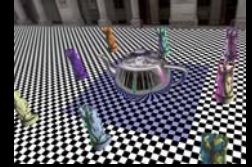
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Solution: ray morphing



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Solution: ray morphing



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Solution

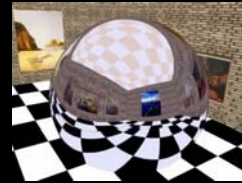


Left—continuous transition. Right—morph region (green), environment map (red).



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Ray morphing



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Attenuation w/ distance



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Fresnel



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Combined effects



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Animation and materials



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Comparison to env. mapping



Environment
mapping

Our method



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Billboard limitations

- No support for objects very close to the reflector
- Limited accuracy
 - Flat reflection
 - Lack of motion parallax



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Depth image impostors

- Impostor has to provide
 - Fast construction YES
 - Fast intersection with ray ???
 - Antialiasing YES



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Depth image—ray intersection


Epipolar-like constraints: intersection computed as 1D search
Still too many steps along epipolar segment



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

Simplified Rotated Depth Maps

Pre-rotate depth map.
All rays ever needed project to rows.
Pre-simplify rows.



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Simplified Rotated Depth Maps





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SRDM construction cost



<i>Number of segments</i>	8	16	32	64
<i>Construction time [ms]</i>	210	300	480	980

Rigid body transformations, color updates, and reflector updates do not require reconstruction.



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Depth image impostor results

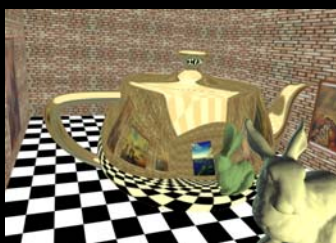

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Depth image impostor results




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Depth image impostor results

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Depth image impostor results



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Depth image impostor results



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Depth image impostor results



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SRDM under-sampling



One rotated depth map every 20°, 10°, 3°, and 2°, respectively.



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Depth image impostor results



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Conclusions

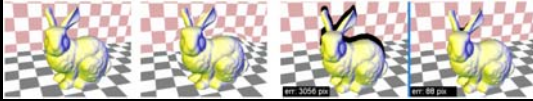
- The reflected-impostor approach works
 - Fast, realistic
 - Increased modeling effort
- Rendering reflections reduced to the lesser problem of rendering w/ impostors



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Future work

- Other types of impostors
 - occlusion-resistant



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Future work

- Other types of impostors
- Other BRDFs
- Self-reflections
- Constructing the SRDMs on the GPU



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- Funding & equipment
 - NSF, Intel, Microsoft, Computer Science Purdue, Visualization Laboratory Purdue
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