



Light Transport

CS535

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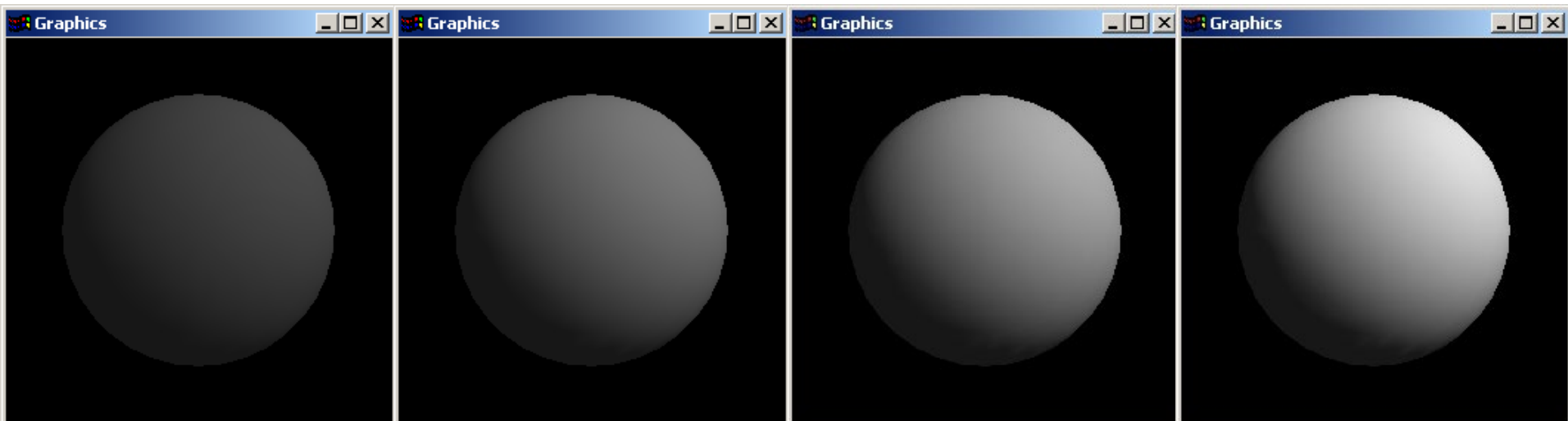
Topics

- Local and Global Illumination Models
- Helmholtz Reciprocity
- Dual Photography/Light Transport in Real-World



Diffuse Lighting

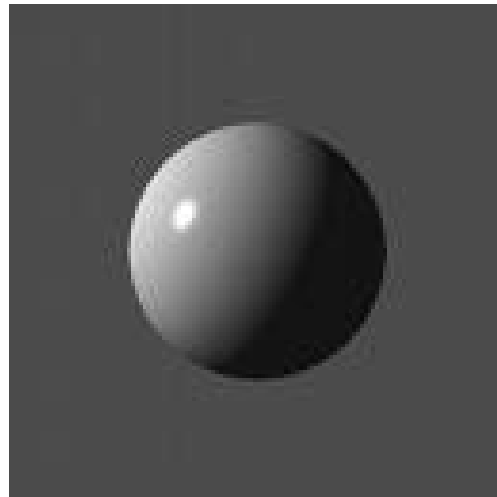
- A.k.a. Lambertian illumination
- A fraction of light is radiated in every direction
- Intensity varies with cosine of the angle with normal





Specular Lighting

- Shiny surfaces reflect predominantly in a particular direction, creating *highlights*
- Where the highlights appear depends on the viewer's position





Global Illumination

- Ray tracing





Conclusion

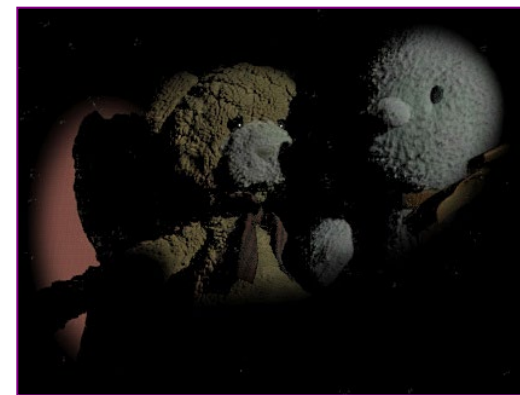
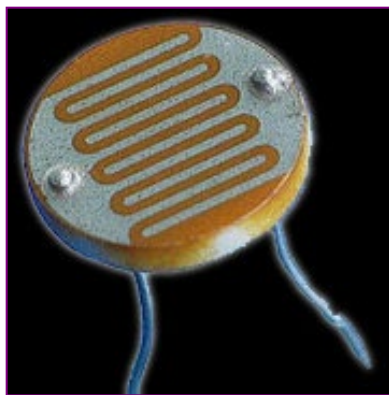
- Modeling illumination is hard
- “Undoing” physically-observed illumination in order to discover the underlying geometry is even harder
- Insight: let’s sample it and “re-apply” it!



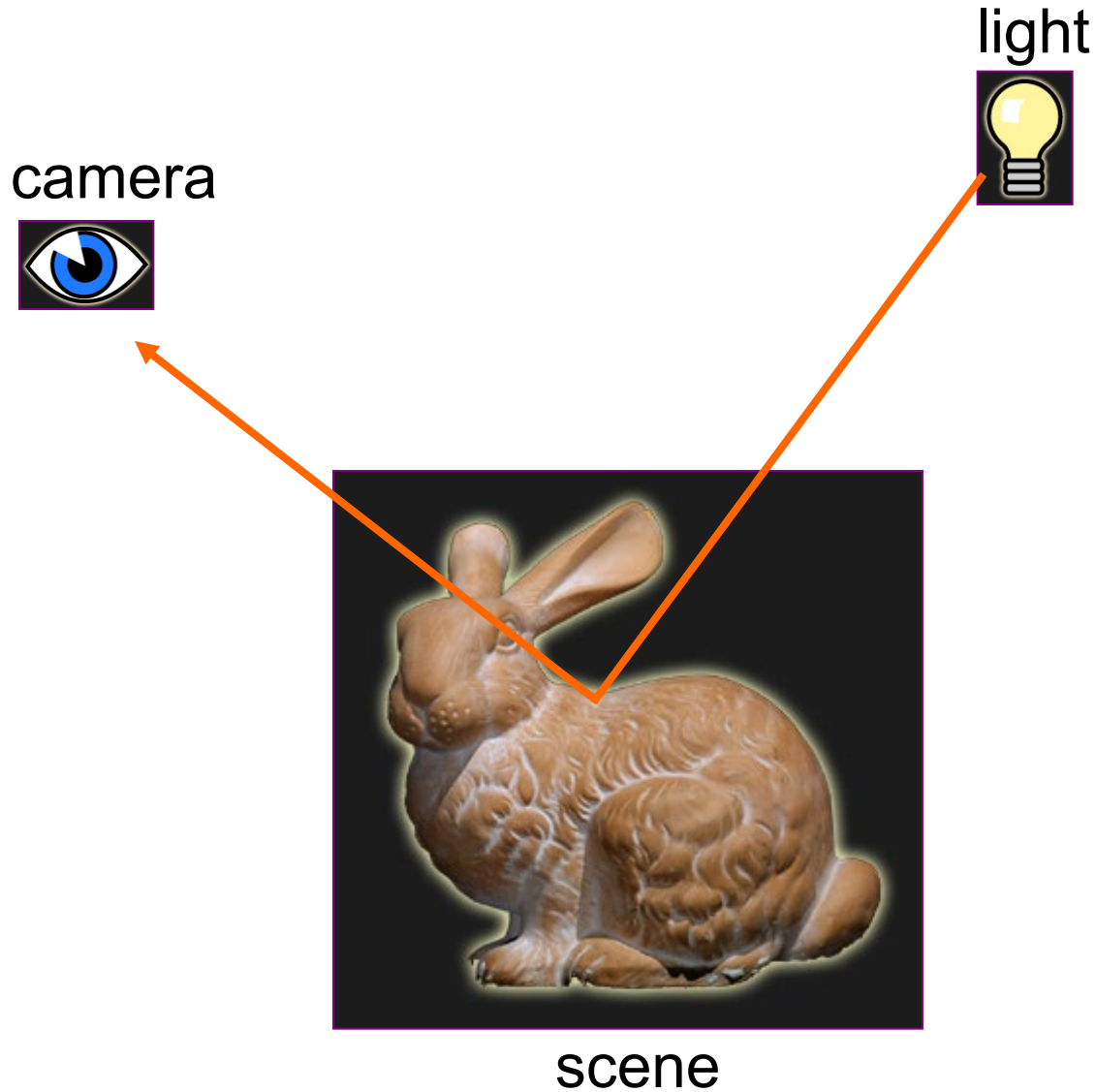
Dual Photography

Sen et al., SIGGRAPH 2005

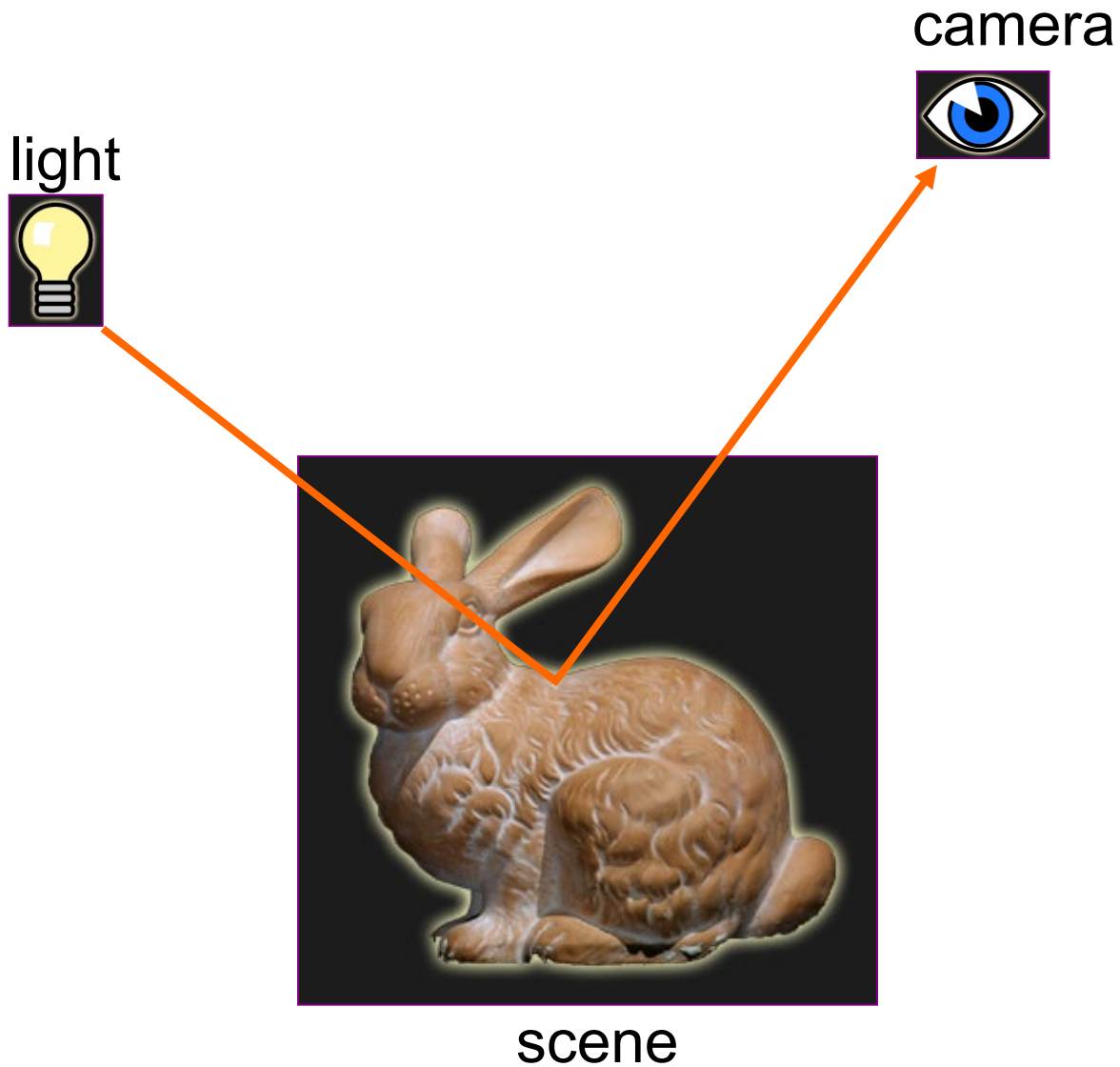
(slides courtesy of M. Levoy)



Helmholtz Reciprocity



Helmholtz Reciprocity



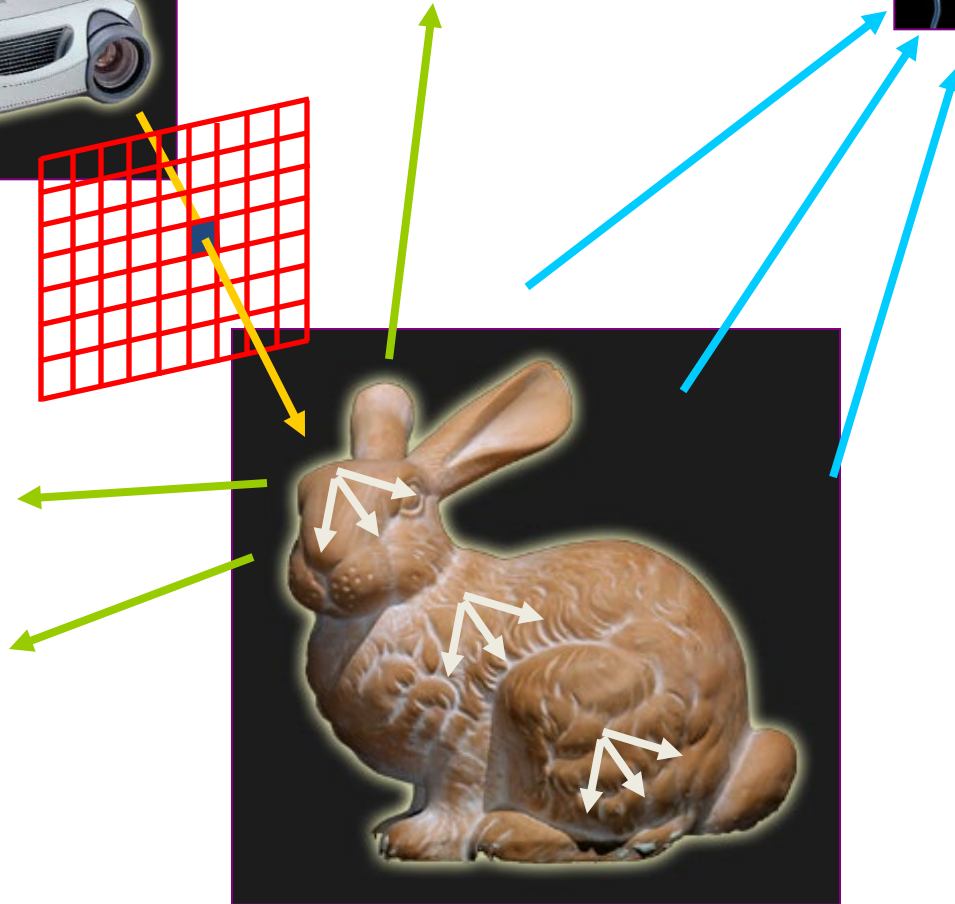
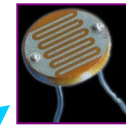
Measuring transport along a set of paths



projector



photocell

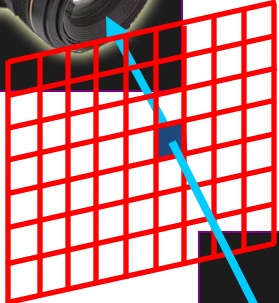


scene

Reversing the paths



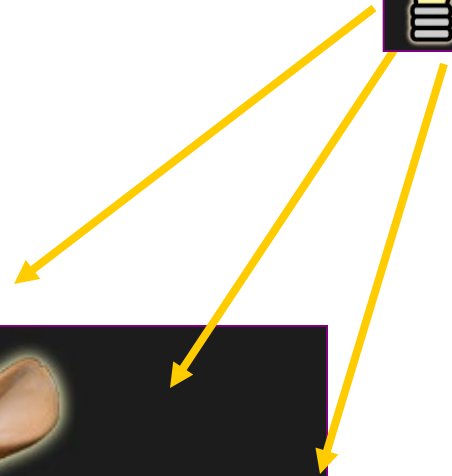
camera



point light



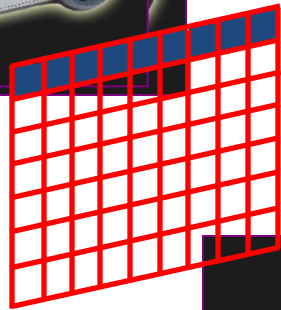
scene



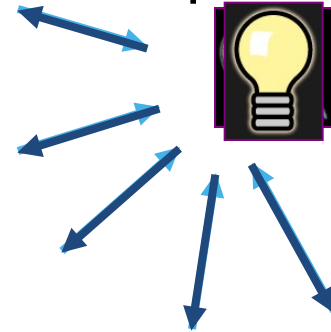
Forming a dual photograph



“dual” camera
projector



“dual” light
projector



scene





Forming a dual photograph

“dual” camera

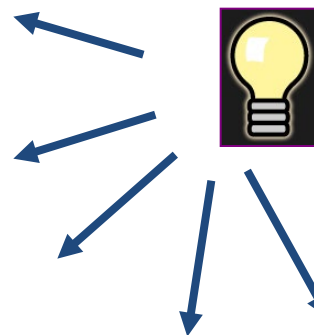


image of scene



scene

“dual” light





Physical demonstration

- light replaced with projector
- camera replaced with photocell
- projector scanned across the scene



conventional photograph,
with light coming from right



dual photograph,
as seen from projector's position
and as illuminated from photocell's position



Related imaging methods

- time-of-flight scanner
 - if they return reflectance as well as range
 - but their light source and sensor are typically coaxial
- scanning electron microscope



Velcro® at 35x magnification,
Museum of Science, Boston

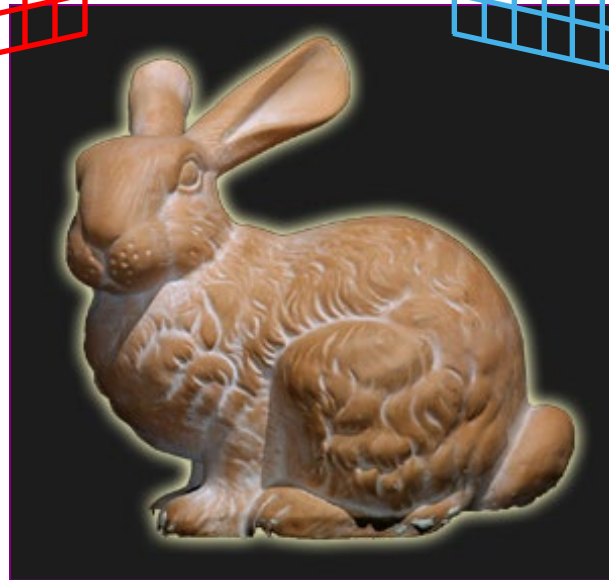
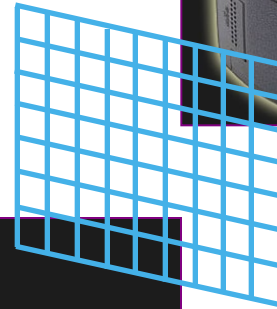
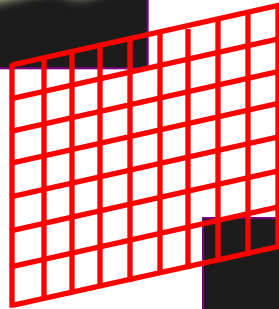
The 4D transport matrix



projector



photocell

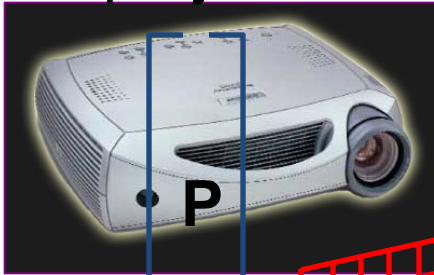


scene

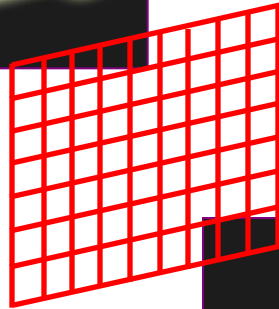
The 4D transport matrix



projector



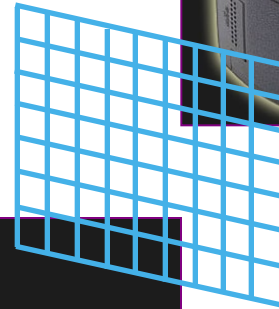
$pq \times 1$



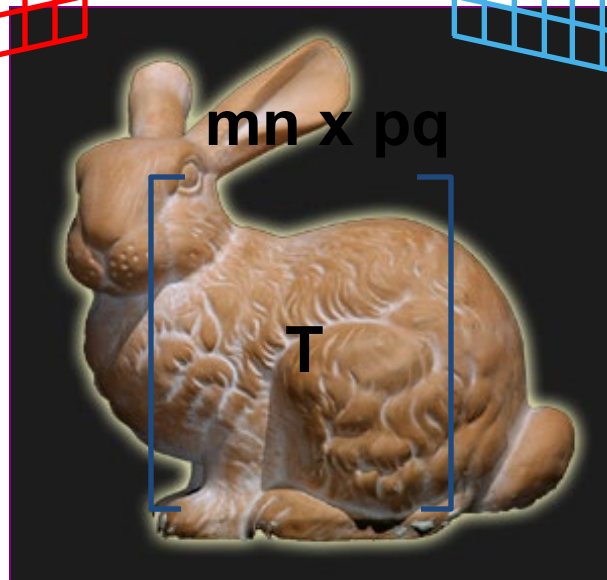
camera



$mn \times 1$



$mn \times pq$



scene

The 4D transport matrix



$$\begin{array}{c} \left[\begin{array}{c} \mathbf{C} \\ \hline \end{array} \right] \\ mn \times 1 \end{array} = \begin{array}{c} mn \times pq \\ \left[\begin{array}{c} \mathbf{T} \\ \hline \end{array} \right] \end{array} \begin{array}{c} \left[\begin{array}{c} \mathbf{P} \\ \hline \end{array} \right] \\ pq \times 1 \end{array}$$

The 4D transport matrix



$$\begin{array}{c} \left[\begin{array}{c} \mathbf{C} \end{array} \right] \\ mn \times 1 \end{array} = \begin{array}{c} \left[\begin{array}{c} \text{orange bar} \end{array} \right] \\ mn \times pq \end{array} \mathbf{T} \begin{array}{c} \left[\begin{array}{c} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{array} \right] \\ pq \times 1 \end{array}$$

The 4D transport matrix



$$\begin{array}{c} \left[\begin{array}{c} \mathbf{C} \end{array} \right] \\ mn \times 1 \end{array} = \begin{array}{c} mn \times pq \\ \left[\begin{array}{c} \text{light orange bar} \\ \text{orange bar} \end{array} \right] \mathbf{T} \end{array} \begin{array}{c} \left[\begin{array}{c} 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{array} \right] \\ pq \times 1 \end{array}$$

The 4D transport matrix



$$\begin{array}{c} \left[\begin{array}{c} \mathbf{C} \end{array} \right] \\ mn \times 1 \end{array} = \begin{array}{c} mn \times pq \\ \left[\begin{array}{c} \text{orange bar} \\ \text{orange bar} \\ \text{orange bar} \end{array} \right] \mathbf{T} \end{array} \begin{array}{c} \left[\begin{array}{c} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{array} \right] \\ pq \times 1 \end{array}$$

The 4D transport matrix



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The 4D transport matrix



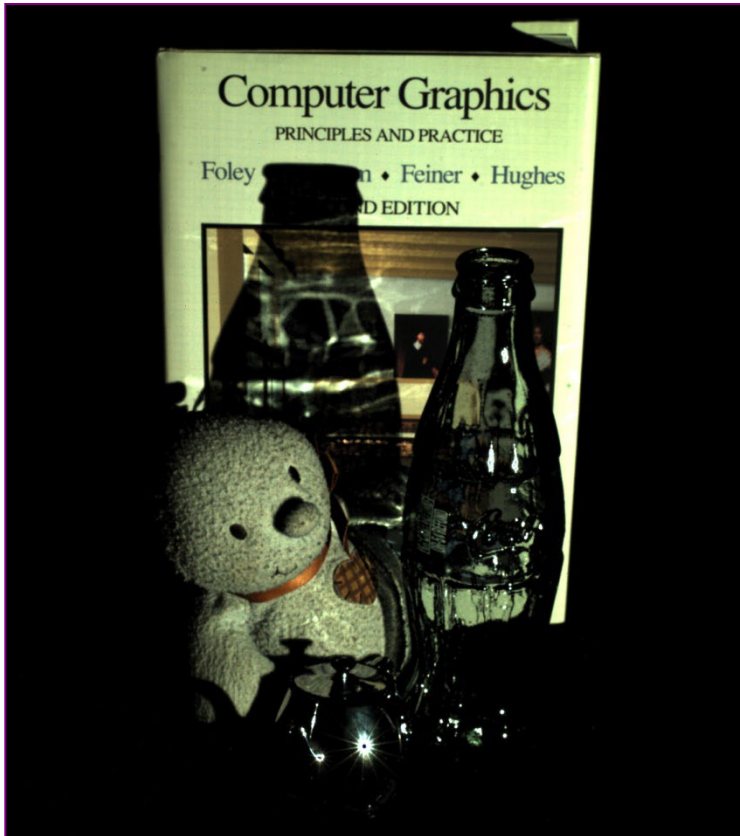
$$\begin{array}{c} \left[\begin{array}{c} \mathbf{C} \end{array} \right] \\ mn \times 1 \end{array} = \begin{array}{c} mn \times pq \\ \left[\begin{array}{c} \mathbf{T} \end{array} \right] \end{array} \begin{array}{c} \left[\begin{array}{c} \mathbf{P} \end{array} \right] \\ pq \times 1 \end{array}$$

applying Helmholtz reciprocity...

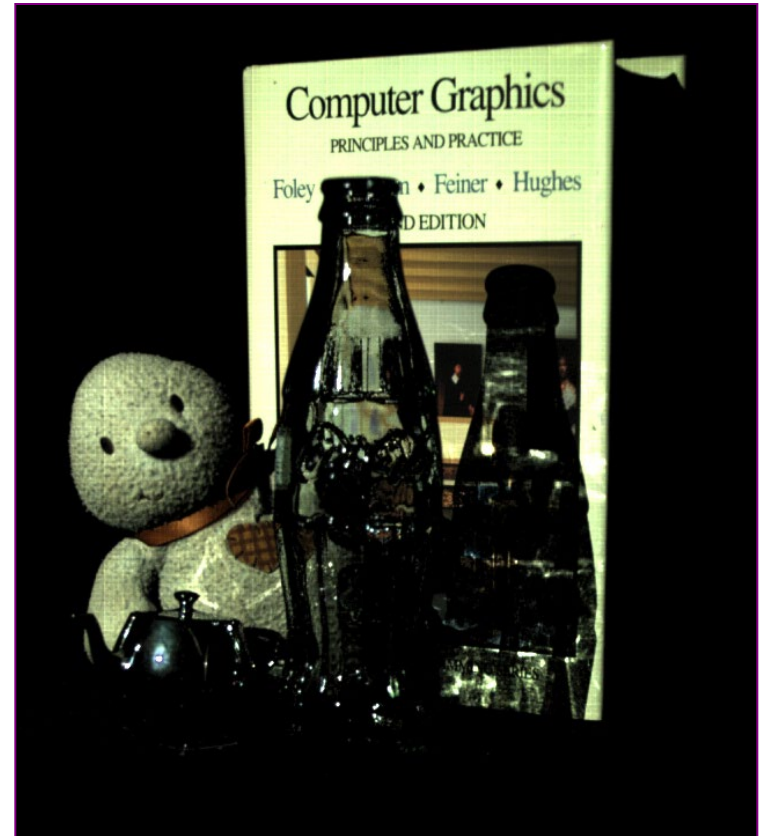
$$\begin{array}{c} \left[\begin{array}{c} \mathbf{C}' \end{array} \right] \\ pq \times 1 \end{array} = \begin{array}{c} pq \times mn \\ \left[\begin{array}{c} \mathbf{T}^T \end{array} \right] \end{array} \begin{array}{c} \left[\begin{array}{c} \mathbf{P}' \end{array} \right] \\ mn \times 1 \end{array}$$



Example



conventional photograph
with light coming from right



dual photograph
as seen from projector's position

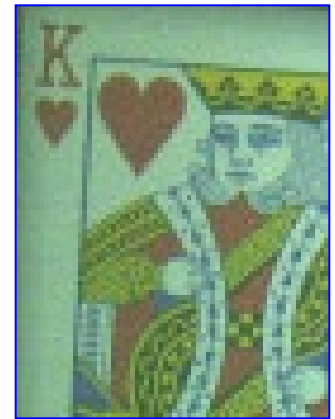
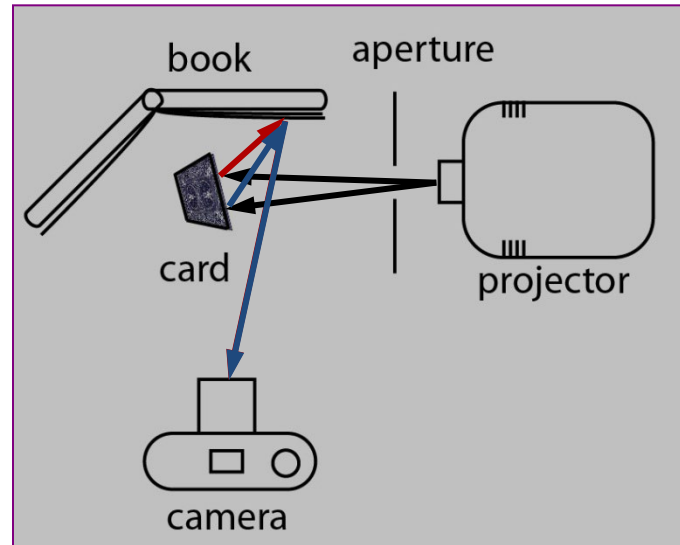
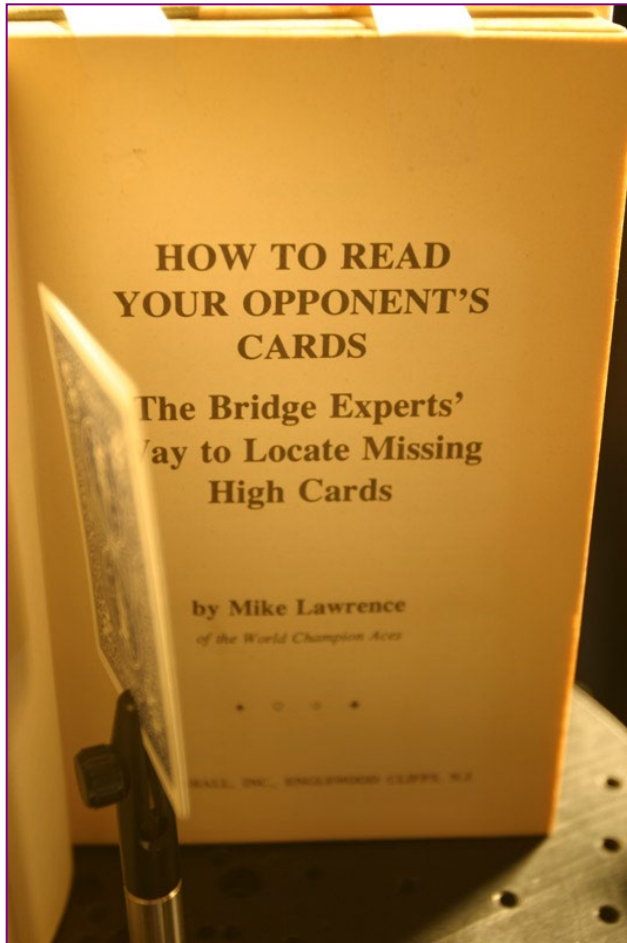


Properties of the transport matrix

- little inter-reflection
→ sparse matrix
- many inter-reflections
→ dense matrix
- convex object
→ diagonal matrix
- concave object
→ full matrix

Can we create a dual photograph entirely from diffuse reflections?

Dual photography from diffuse reflections



the camera's view



Relighting



Paul Debevec's
Light Stage 3

- subject captured under multiple lights
- one light at a time, so subject must hold still
- point lights are used, so can't relight with cast shadows



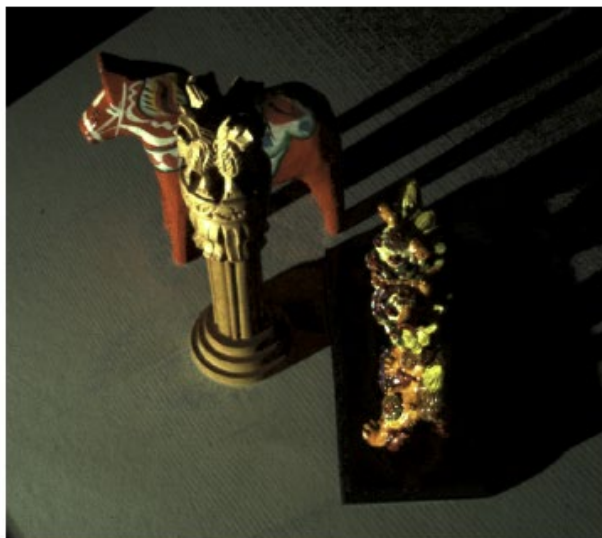
Relighting



With Dual Photography...



Relighting



With Dual
Photography...



Relighting



(a)



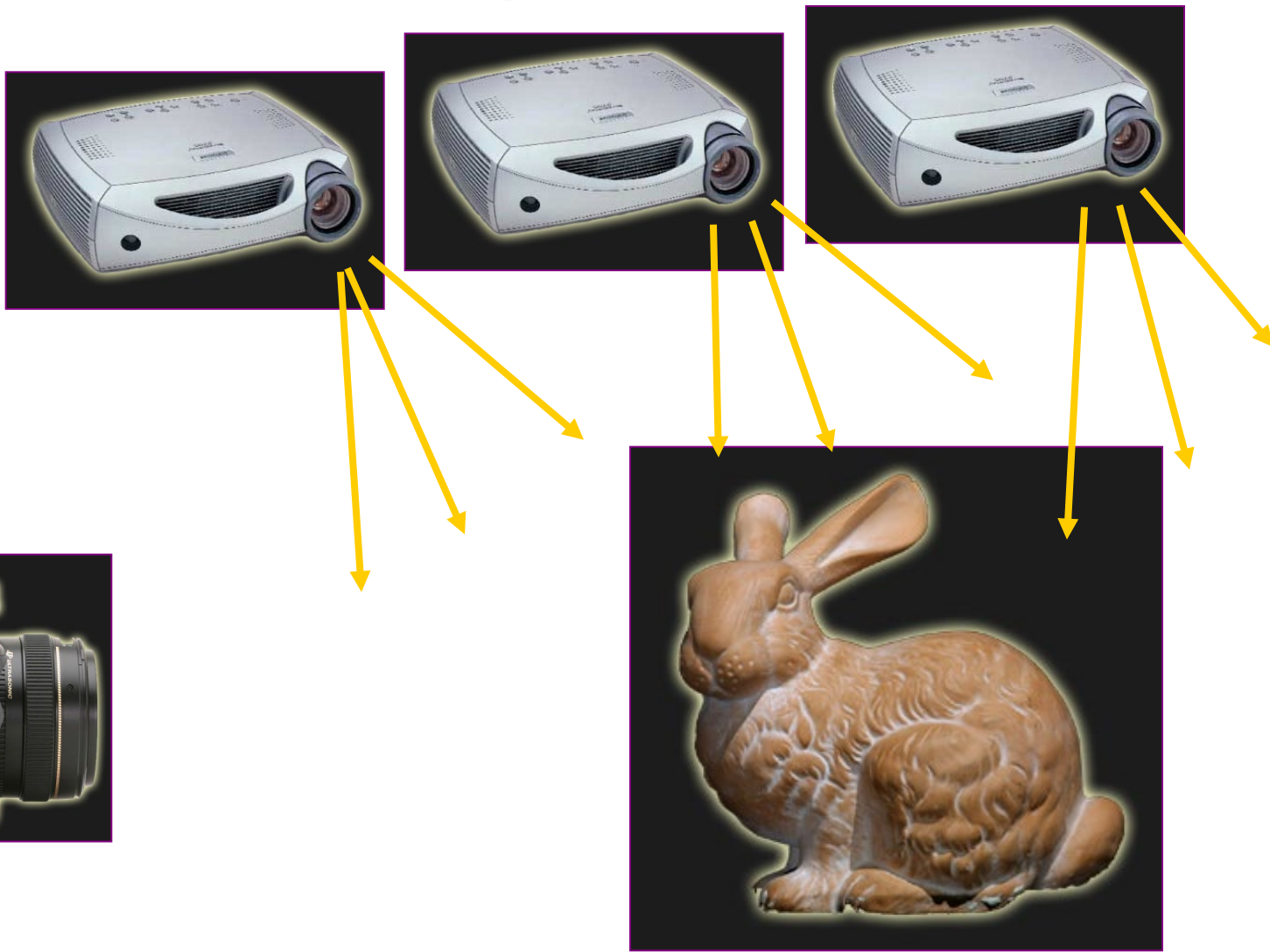
(b)



With Dual
Photography...

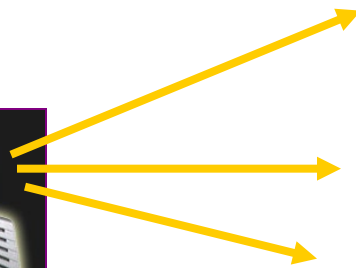


The 6D transport matrix





The 6D transport matrix



The advantage of dual photography



- capture of a scene as illuminated by different lights cannot be parallelized
- capture of a scene as viewed by different cameras can be parallelized

Measuring the 6D transport matrix



projector



camera array



scene



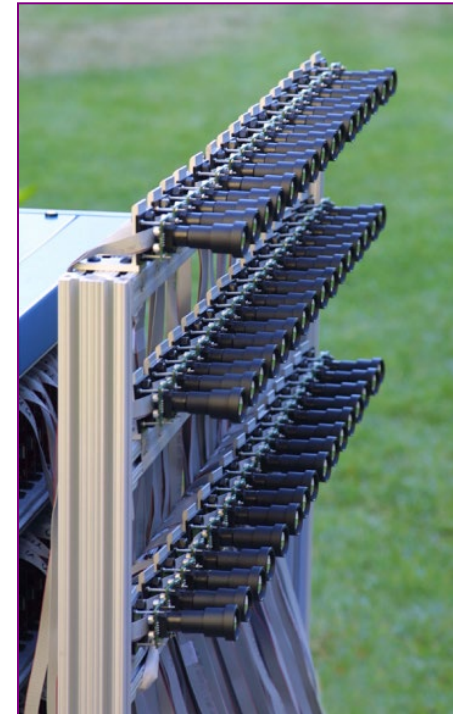
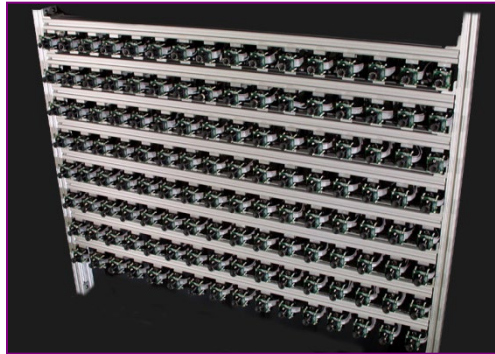
Relighting with complex illumination



projector



camera array



scene

$$\begin{matrix} & & pq \times mn \times uv \\ \left[\begin{matrix} C' \end{matrix} \right] & = & \left[\begin{matrix} T^T \end{matrix} \right] \left[\begin{matrix} P' \end{matrix} \right] \\ pq \times 1 & & mn \times uv \times 1 \end{matrix}$$

- step 1: measure 6D transport matrix T
- step 2: capture a 4D light field
- step 3: relight scene using captured light field

Running time

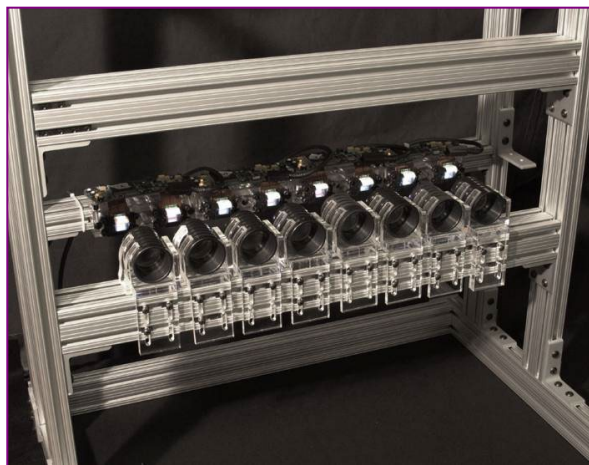


- the different rays within a projector can in fact be parallelized to some extent
- this parallelism can be discovered using a coarse-to-fine adaptive scan
- can measure a 6D transport matrix in 5 minutes

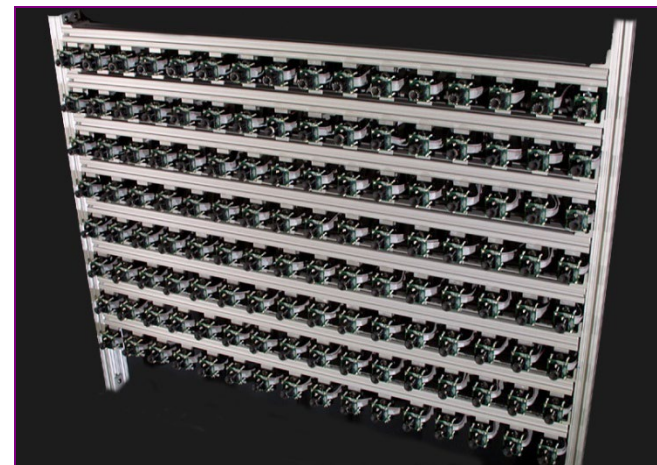
Can we measure an 8D transport matrix?



projector array



camera array



scene