



CS63500

Capturing, Modeling, and Rendering 3D Structures

Daniel G. Aliaga

Department of Computer Science

<http://www.cs.purdue.edu/cgvlab>

Purdue University

<http://www.cs.purdue.edu/homes/aliaga>



- Topic:
 - Covers fundamental problems and challenges encountered when capturing, modeling, and rendering 3D structures and objects.
 - Covers material in computer graphics, computer vision, and visualization
- Goal:
 - To bring students up to speed in latest methods (research)
 - To enable students to develop new and improved approaches

Syllabus

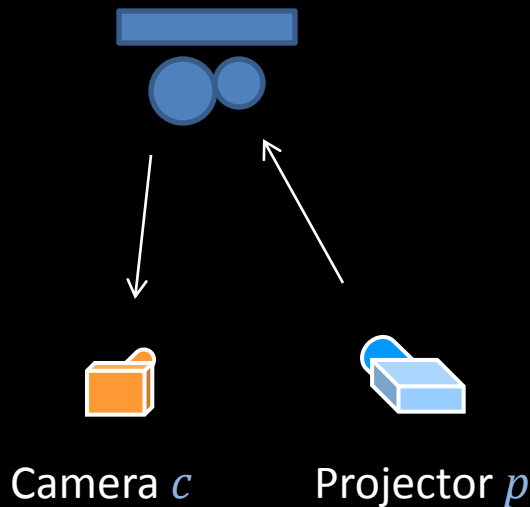


- Applied Optimization
 - Least squares, simulated annealing, MCMC, neural networks, etc.
- Light-Transport based Methods
- Geometry and Image-based Acquisition
- Deep Learning Based Reconstruction
- Computational Images and Displays
- 3D Printing
- ...and more!

Light Transport Based Methods



- Can encode light (or projector) to camera “transport” in a large matrix T



$$\begin{bmatrix} c \end{bmatrix} = \begin{bmatrix} T \end{bmatrix} \begin{bmatrix} p \end{bmatrix}$$

As seen from camera...



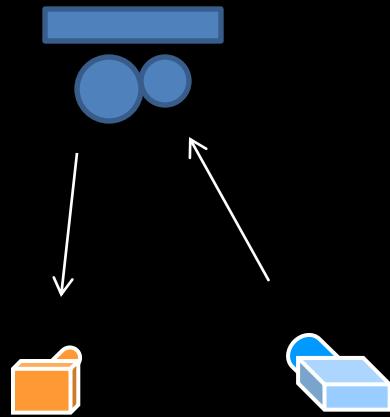
$$\begin{bmatrix} p \end{bmatrix} = \begin{bmatrix} T^t \end{bmatrix} \begin{bmatrix} c \end{bmatrix}$$

As seen from projector!!!

Light Transport Based Methods

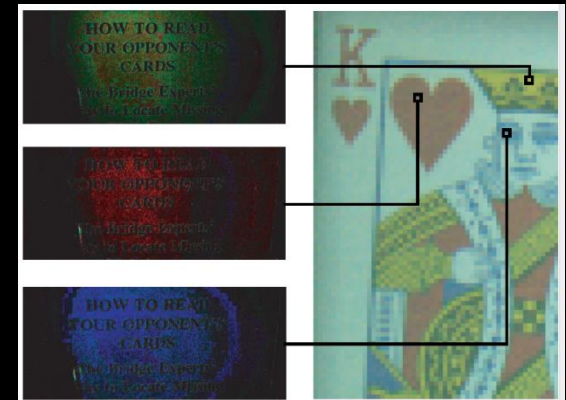
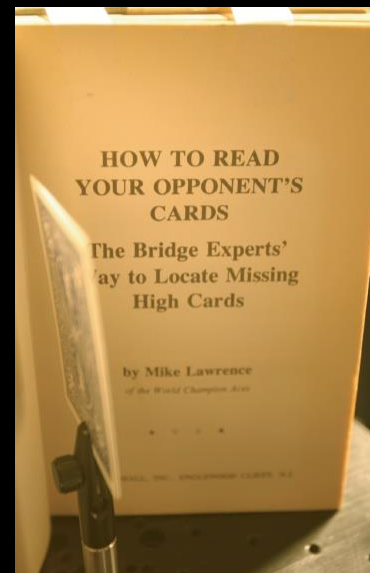


- Can encode light (or projector) to camera “transport” in a large matrix T



Camera c

Projector p



$$\begin{bmatrix} c \end{bmatrix} = \begin{bmatrix} T \end{bmatrix} \begin{bmatrix} p \end{bmatrix}$$

$$\begin{bmatrix} p \end{bmatrix} = \begin{bmatrix} T^t \end{bmatrix} \begin{bmatrix} c \end{bmatrix}$$

As seen from camera...

As seen from projector!!!

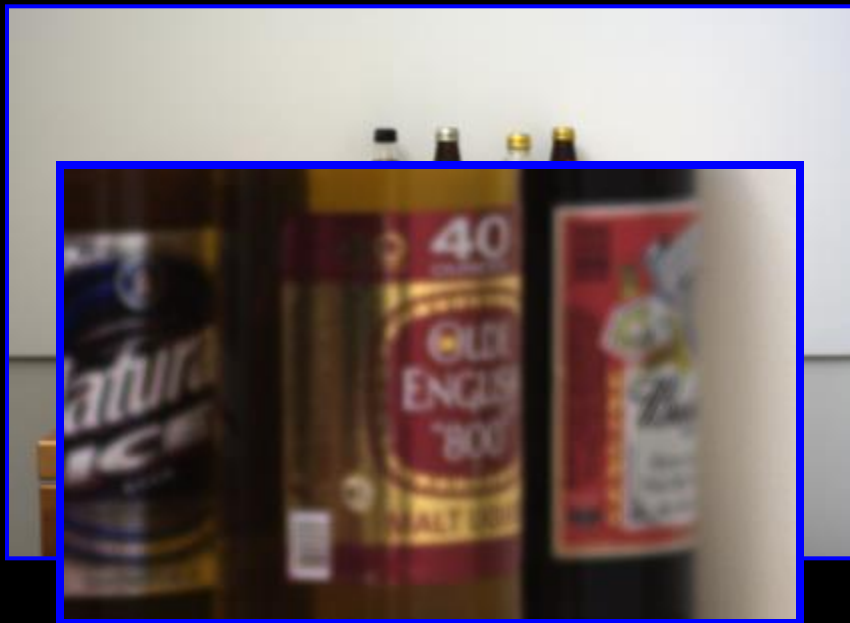
Output #1: Depth map



Single input image:



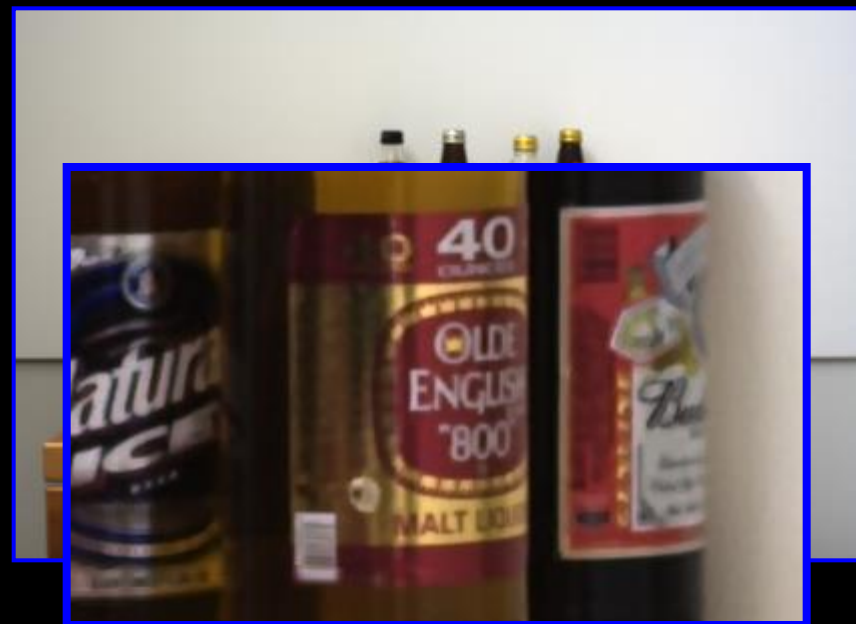
Single input image:



Output #1: Depth map



Output #2: All-focused image



Light in Slow Motion

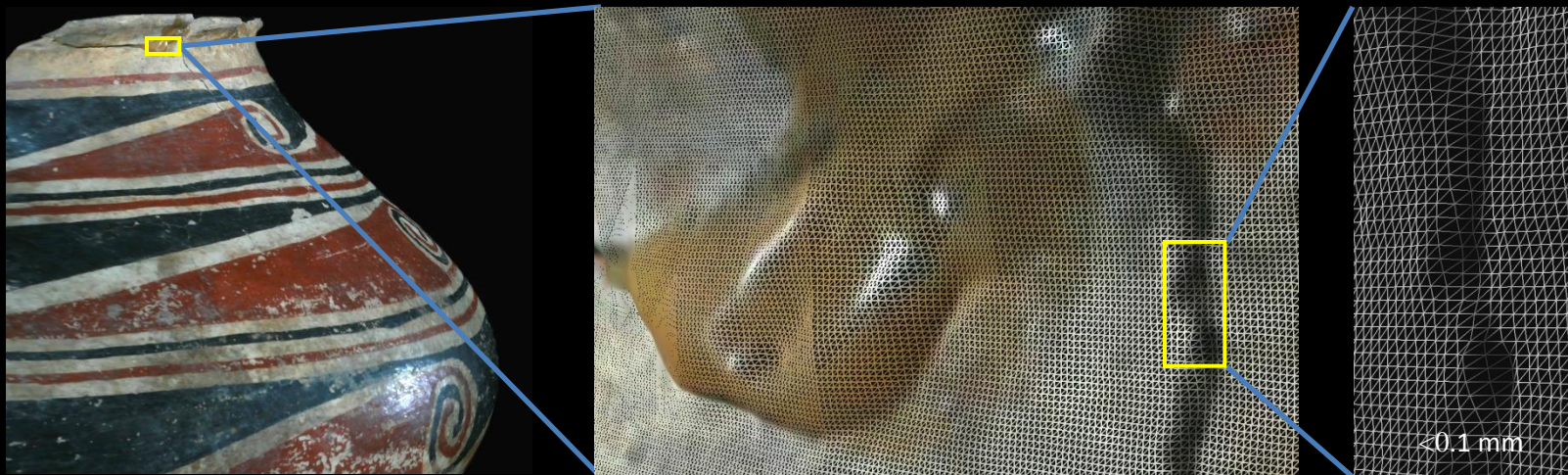


- https://www.youtube.com/watch?v=Y_9vd4HWIVA

Photogeometric Acquisition



To provide an easy-to-use and high-resolution acquisition platform for deployment



Deblurring and Precorrection (to prevent blurring)



- Some approaches:
 - Inverse Filter
 - Wiener Filter
 - Lucy Richardson
 - And more!

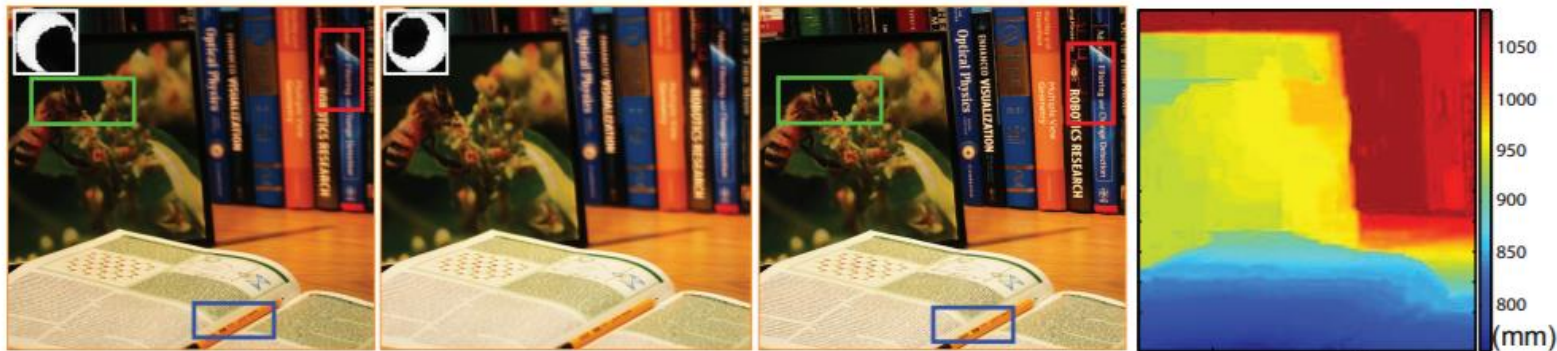
Build your own coded aperture



Voila!



Coded Aperture Deblurring



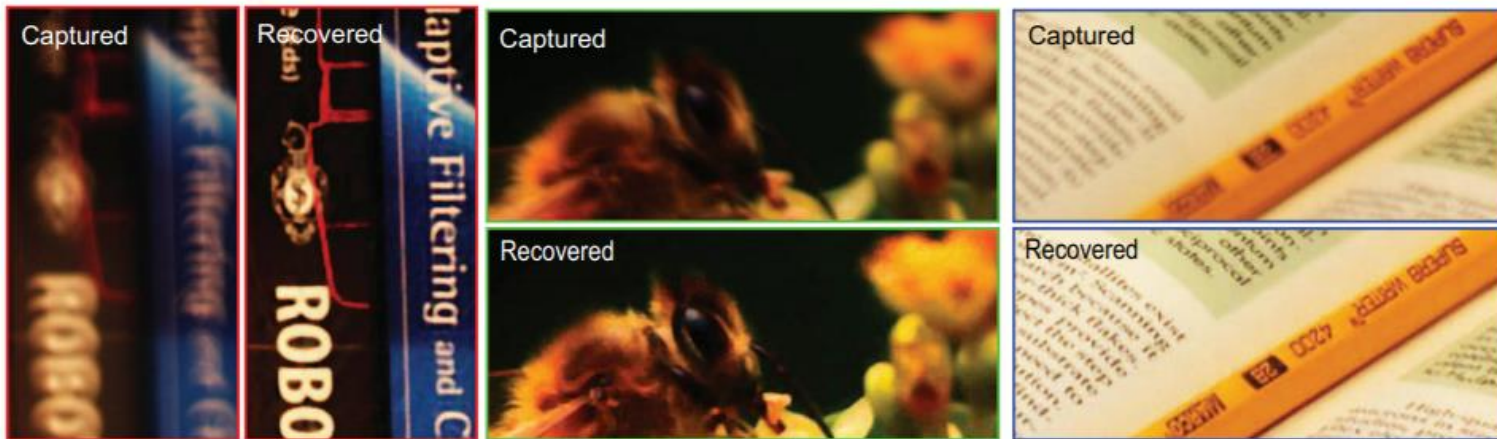
(a) Captured Image 1

(b) Captured Image 2

(c) All-focused Image

(d) Estimated Depth Map

(e) Close-Ups





Rectified Crop



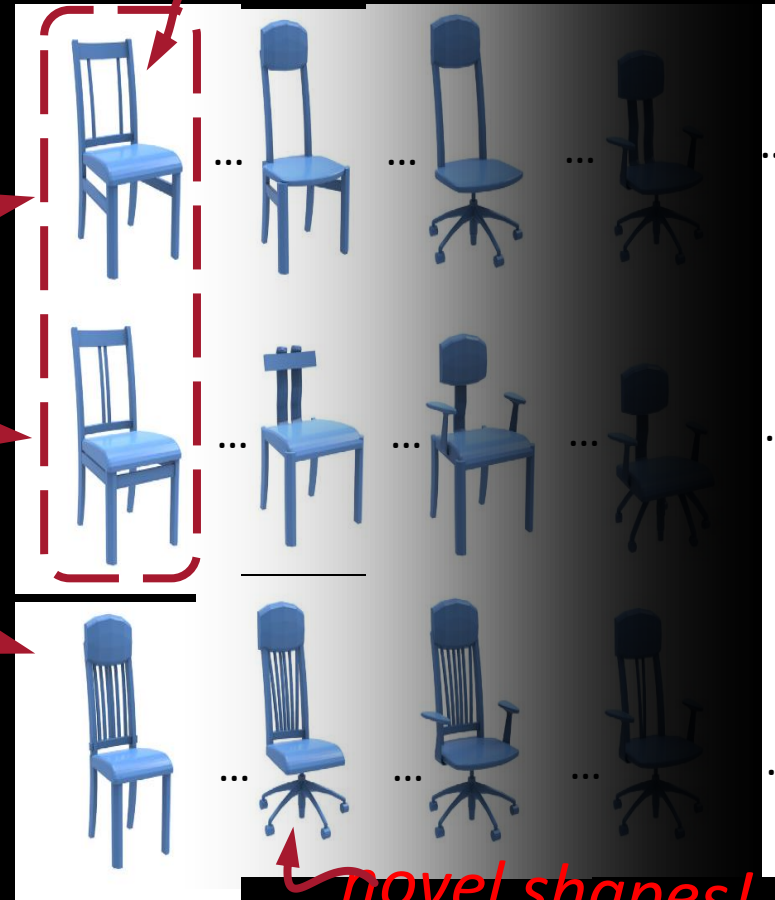
Deblurred Result

Structure Aware Modeling

topology changes!!

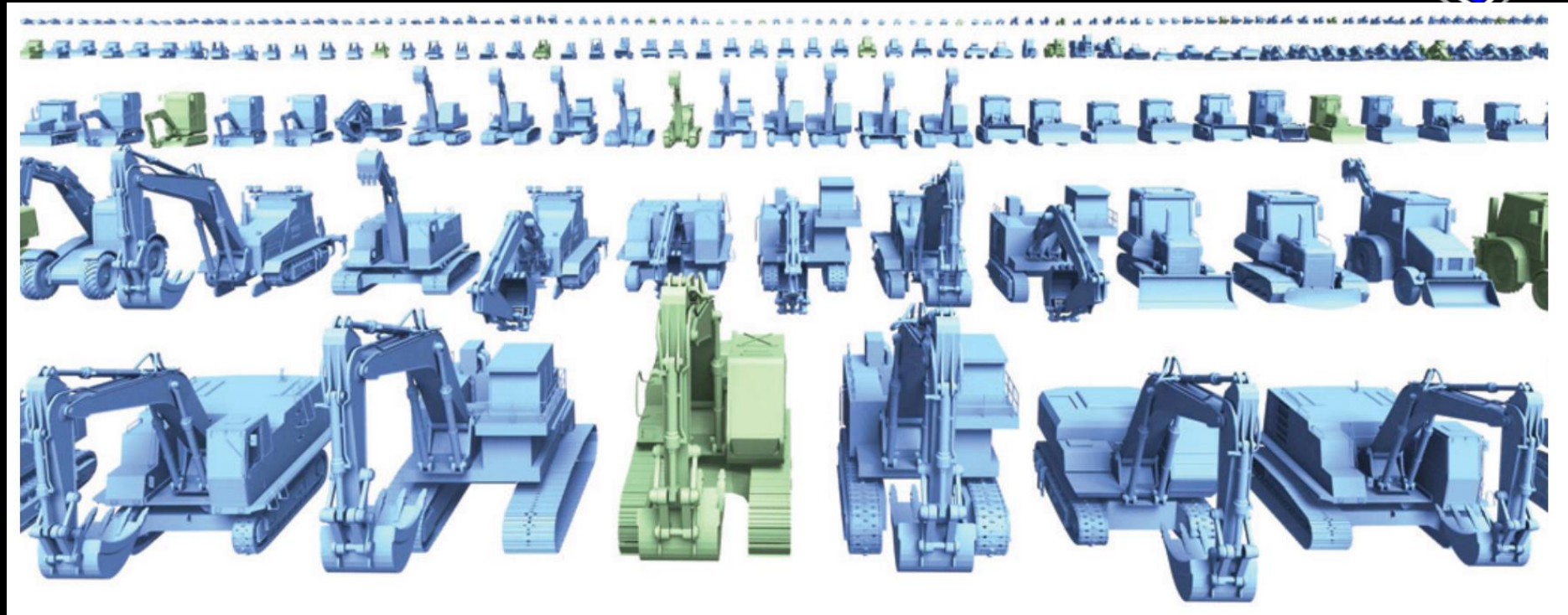


- Continuous shape blending



novel shapes!

Structure Aware Modeling: Probabilistic synthesis

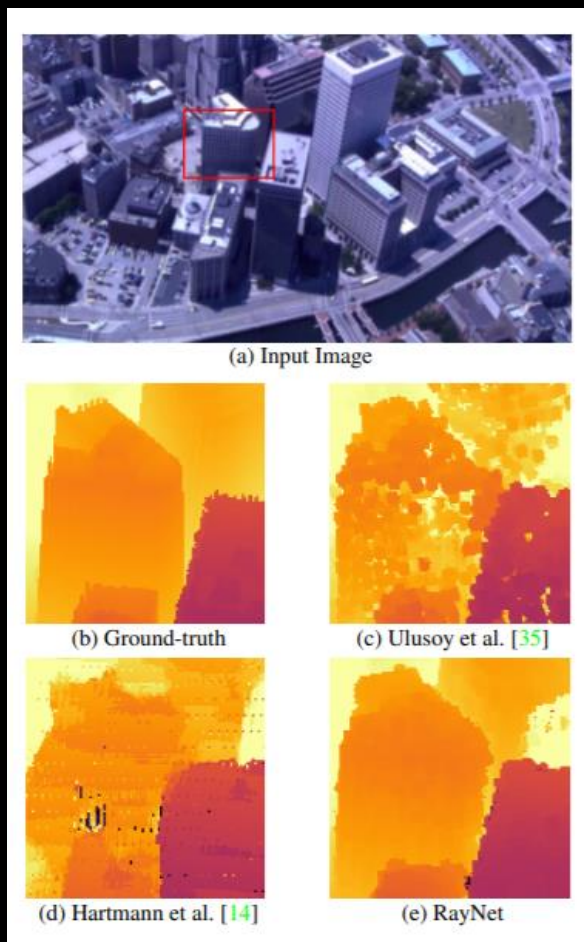


Green models are from the training set; blue ones are synthesis results

Deep Learning and 3D Reconstruction



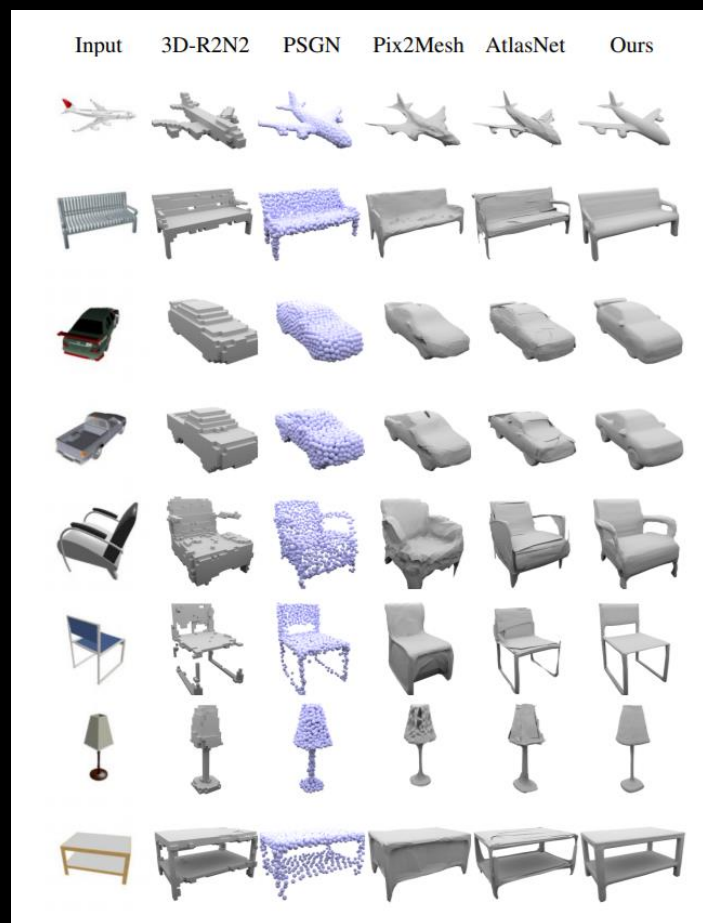
- RayNet: volumetric 3D reconstruction



Deep Learning and 3D Reconstruction



- OccNet: occupancy-based reconstruction



Deep Learning and 3D Reconstruction



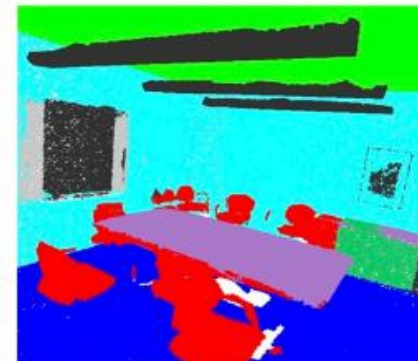
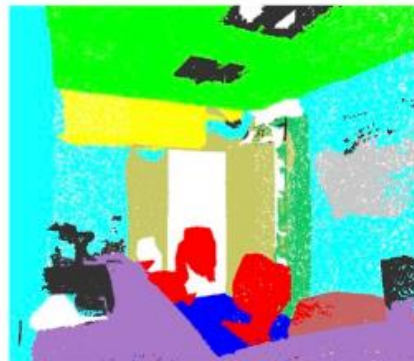
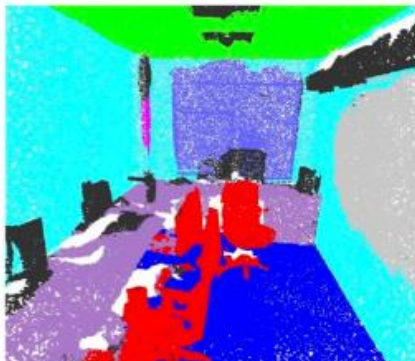
- Semantic Segmentation

Semantic Segmentation Results

Input



Output

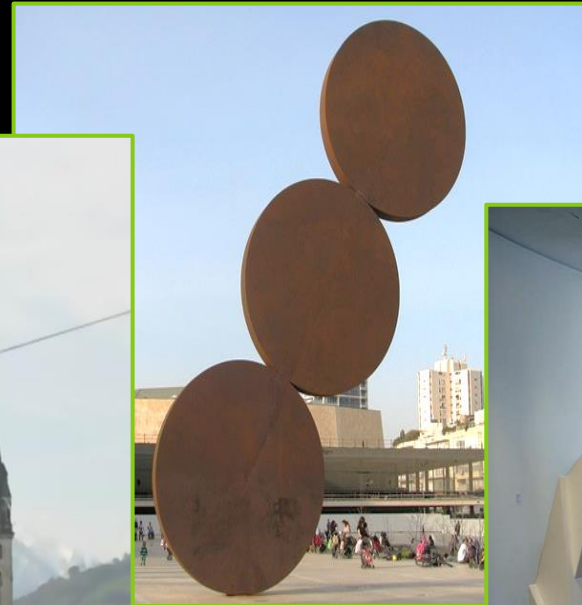


Computational Displays



- <http://gl.ict.usc.edu/Research/3DDisplay/>

3D Printing: Self Standing



3D Printing: Self Standing



- Automatic balancing
 - Stability & shape preservation
 - Inner carving & shape deformation





Questions?



Come to CS635 in the Spring!

or email aliaga@purdue.edu...