



CS635

# Deep Visual Computing:

Deep Single Image Reconstruction  
and more

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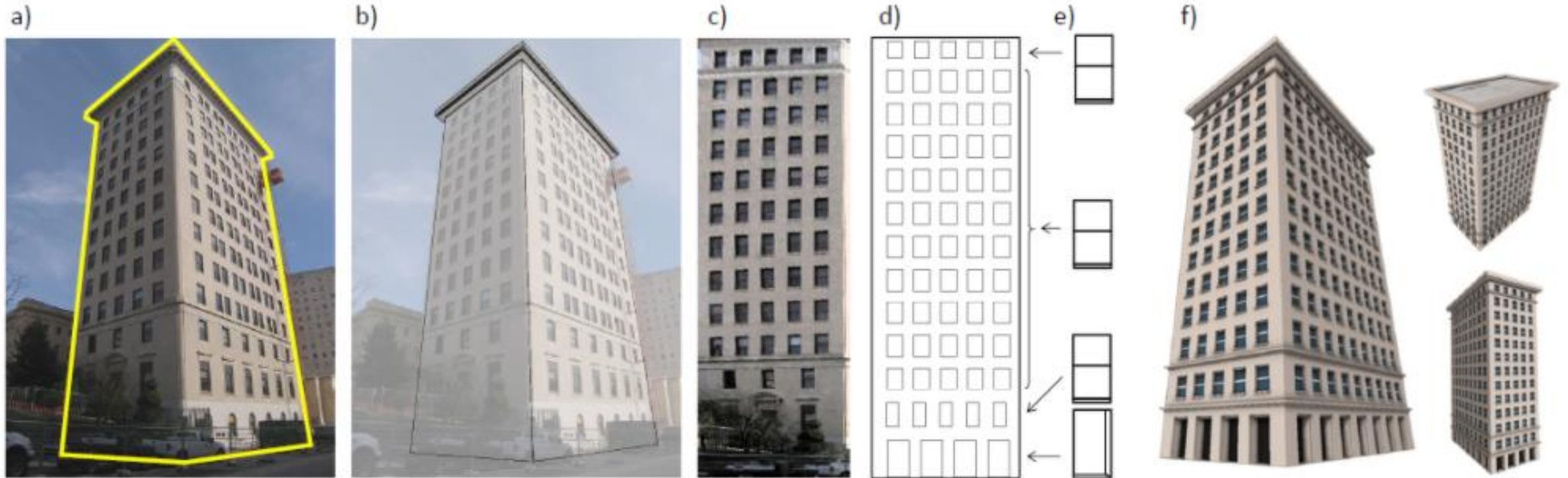
Spring 2025

# Topics

- Single image -> 3D model
- Single image -> code fragment
- Single image -> better single image



# Procedural Modeling of a Building from a Single Image



# Deep Mesh Reconstruction from Single RGB Images via Topology Modification Networks

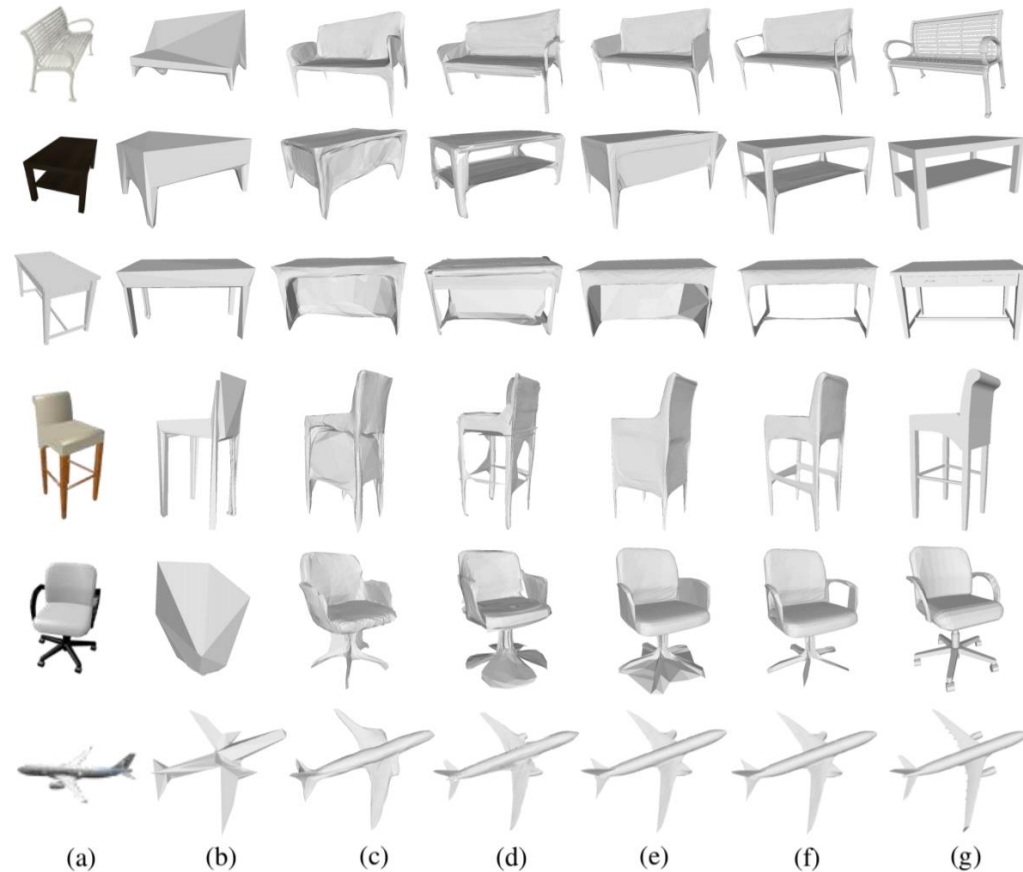


Figure 4. Qualitative results. (a) Input image; (b) N3MR; (c) Pixel2Mesh; (d) AtlasNet-25; (e) Baseline; (f) Ours; (g) Ground truth.

# CSGNET

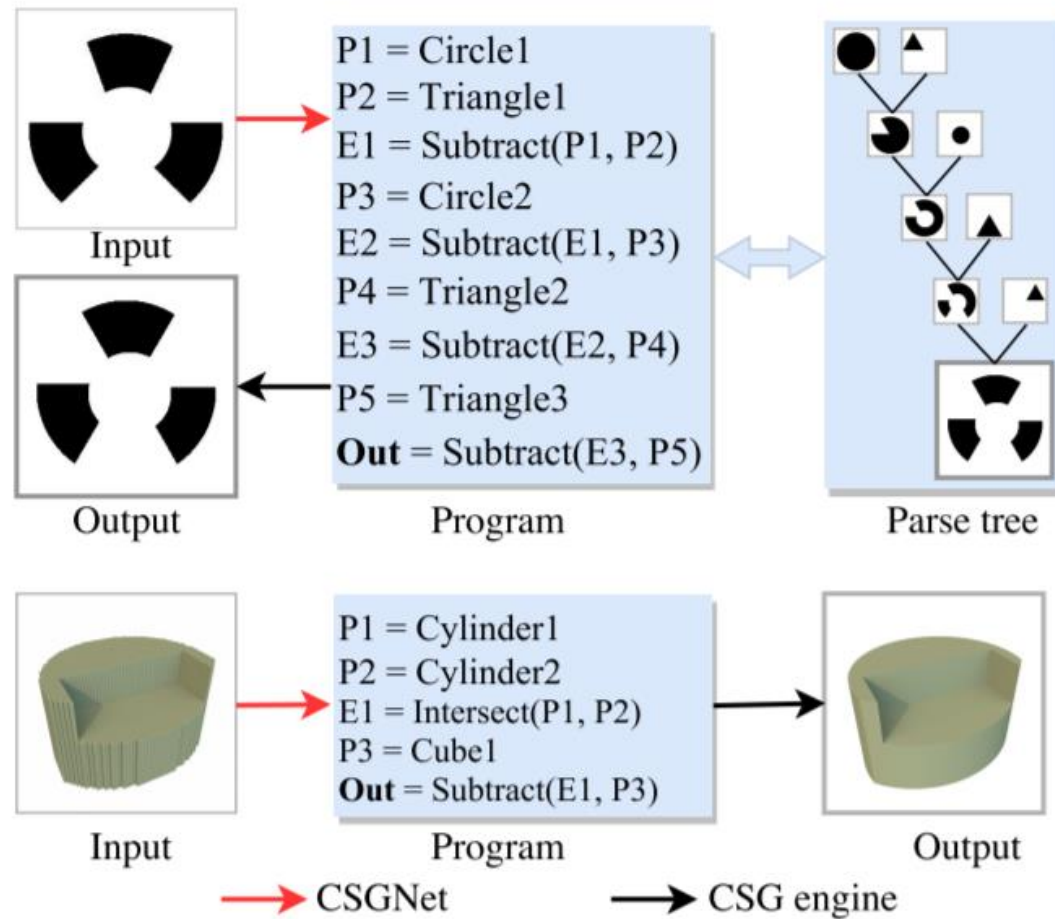


Figure 1. **Our shape parser produces a compact program that generates an input 2D or 3D shape.** On top is an input image of 2D shape, its program and the underlying parse tree where primitives are combined with boolean operations. On the bottom is an input voxelized 3D shape, the induced program, and the resulting shape from its execution.

# Learning to Describe Scenes with Programs



(a) Input image



(sphere, small, metal,  
green, x=2, y=2, z=0) ...

(b) Object parsing  
& group detection

```
for(i<3)
  for(j<3-i)
    sphere(pos=(1+i,1+j,0),
           color=6-j)
for(i<4)
  cylinder(pos=(3,3,i),
           color=7)
cylinder(pos=(4,2,0),
         color=3)
```

(c) Program



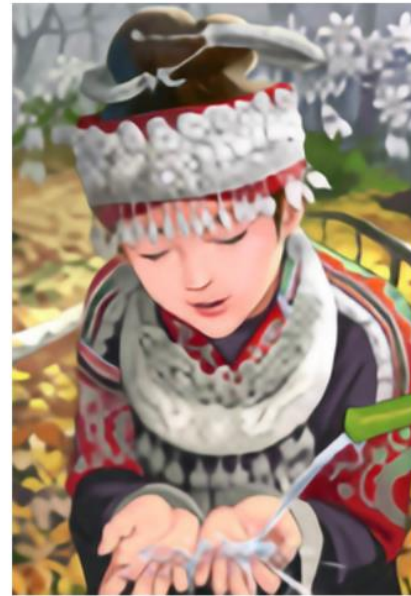
# Deep Learning for Single Image Super-Resolution: A Brief Review



(a) HR



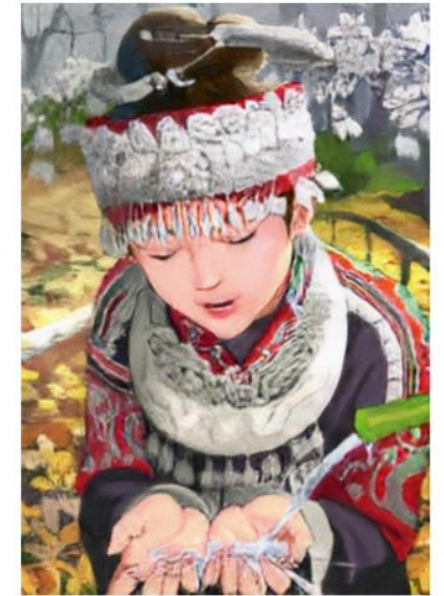
(b)  
bicubic(21.59dB/0.6423)



(c)  
SRResNet(23.53dB/0.7832)



(d)  
SRGAN(21.15dB/0.6868)



(e) SRCNN(20.88dB/0.6002)

Figure 12: Visual comparisons between the MSE, MSE + GAN and MAE +GAN + Contextual Loss (The authors of [68] and [116] released their results.) We can see that the perceptual loss leads to a lower PSNR/SSIM but a better visual quality.

# Fast Separation of Direct and Global Images Using High Frequency Illumination



- [http://www1.cs.columbia.edu/CAVE/publications/pdfs/Krishnan\\_TOG06.pdf](http://www1.cs.columbia.edu/CAVE/publications/pdfs/Krishnan_TOG06.pdf)





# HDR From Single Image

- [https://cave.cs.columbia.edu/Statics/publications/pdfs/Nayar CVPR00\\_2.pdf](https://cave.cs.columbia.edu/Statics/publications/pdfs/Nayar_CVPR00_2.pdf)

# Learning Single Camera Depth Estimation using Dual-Pixels



- <https://arxiv.org/abs/1904.05822>

<https://www.youtube.com/watch?v=zem03fZWLRQ>

Starting at beginning...

# Deep Depth Completion of a Single RGB-D Image



- <https://deepcompletion.cs.princeton.edu/>

# Depth Anything

- <https://depth-anything.github.io/>





# Learning View Priors for Single-view 3D Reconstruction



- [http://hiroharu-kato.com/projects\\_en/view\\_prior\\_learning.html](http://hiroharu-kato.com/projects_en/view_prior_learning.html)
- <https://arxiv.org/abs/1811.10719>



# Transformable Bottleneck Networks

- <https://kyleolsz.github.io/TB-Networks/>

(includes video)

- Also:

<https://www.youtube.com/watch?v=zem03fZWLRQ>

Starting at 11:10...