



CS635

Hough and Radon Transform

Daniel G. Aliaga

Spring 2025



Hough and Radon Transform

- Hough is more well known for shape detection
- Radon is more well known in medical tomography
- However, the two are very related and can help with 2D to 3D inference



Mappings

- Forward/Writing paradigm: a data point in the source space maps onto data points in the destination space
 - > Hough Transform although in a discrete setting;
 - > initialize function $P(p)$ to zero. For each point x in the input image determine its contribution, weighted by $K(x; p)$, to each of the points in $P(p)$ and update $P(p)$
 - > if the input data is sparse, the Hough transform is compact in computation time
- Reverse/Reading paradigm: a data point in the destination space is obtained from the data in the source space
 - > Radon Transform but in a continuous setting;
 - > for each p , collect all the values of $I(x)$, apply the template weights $K(x; p)$, and sum everything
 - > if we have only a viewpoints in parameter space, then the Radon paradigm is preferred

Hough Transform

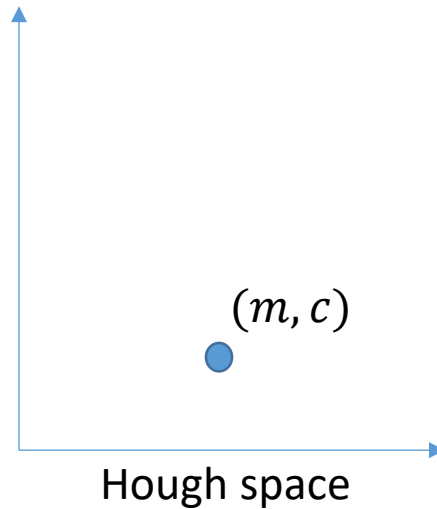
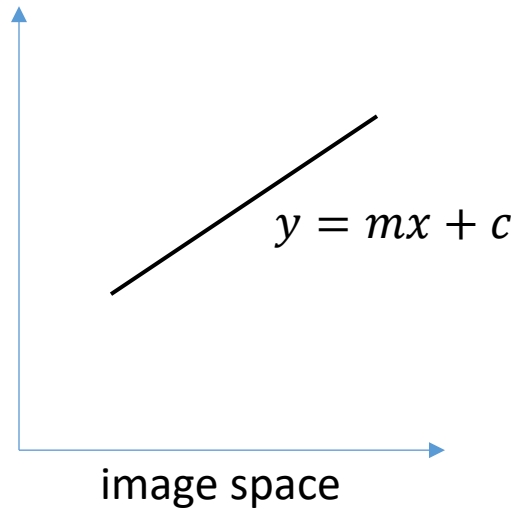


- Patented in 1962 by Paul V.C. Hough
 - Compact 5 page patent
 - BTW, Hough was awarded another patent in 2006 (44 years later!)



Hough Transform

- A line in source image I becomes a (discrete) point in destination space

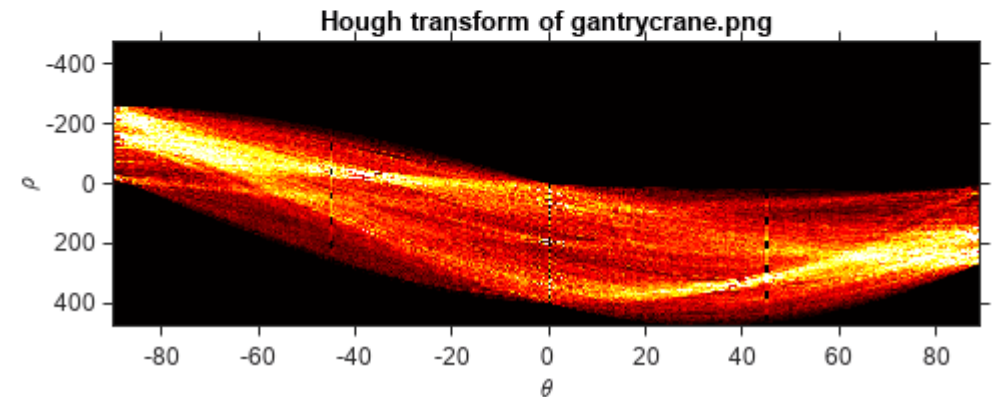
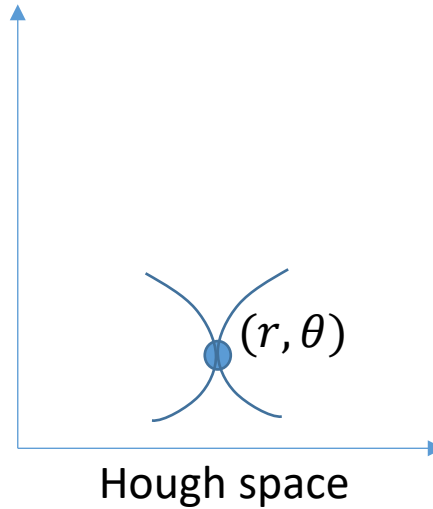
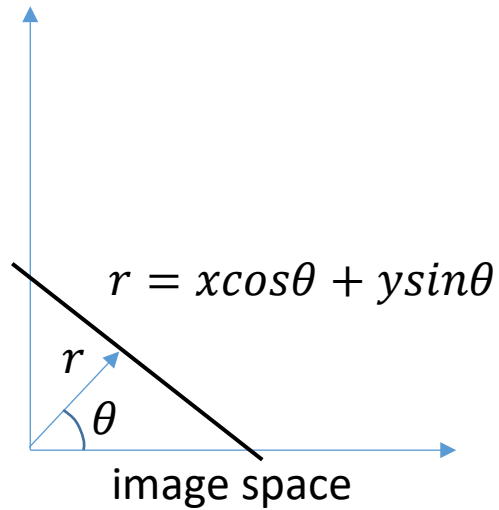


(bad for vertical lines)



Hough Transform

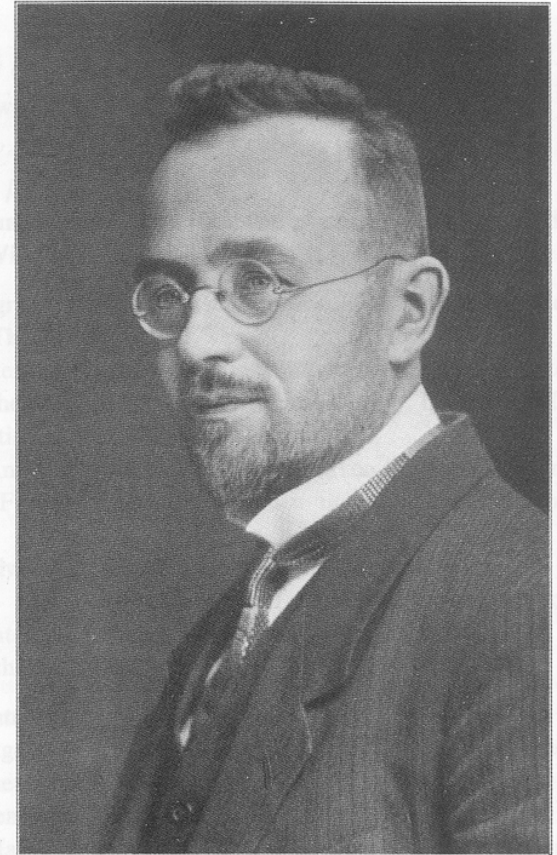
- A line in source image I becomes a (discrete) point in destination space





Radon Transform

- Johann Karl August Radon
- Born in Děčín (Austrian monarchy, now North Bohemia, CZ) in 1887
- Austrian mathematician living in Vienna
- Discovered the transform and its inversion in 1917 as pure theoretical result
- No practical applications during his life
- Died in 1956 in Vienna

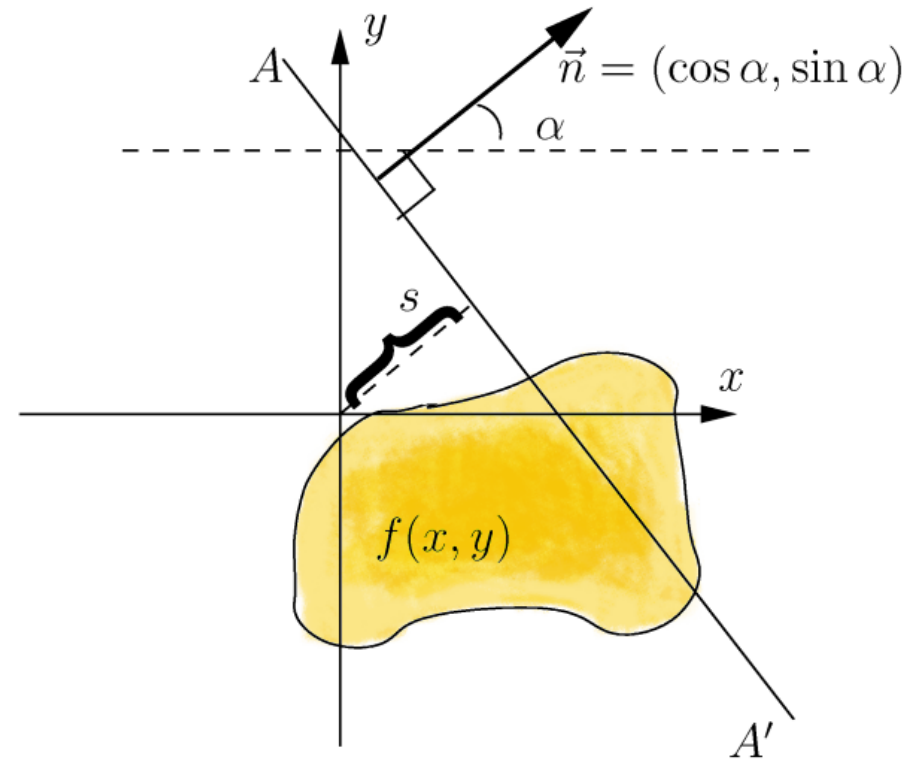


J. K. Radon



Radon Transform

- Input space coordinates x, y
- Input function $f(x, y)$
- Output space coordinates α, s
- Output function $F(\alpha, s)$



[Images: J. Kukal, 2009]



RT and IRT

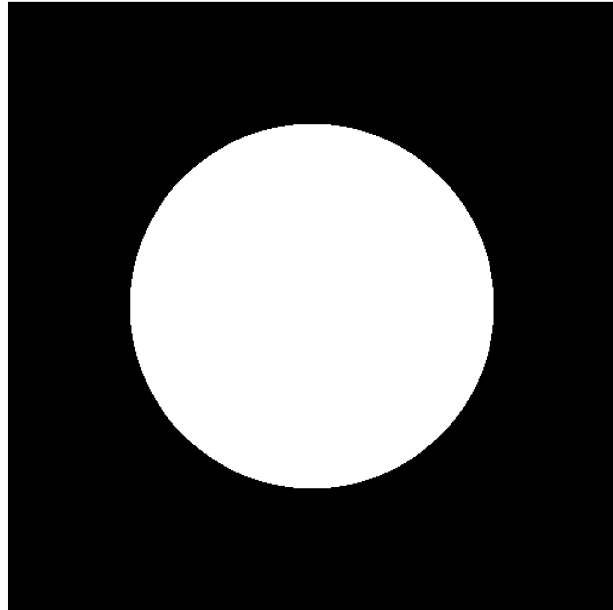
- Radon Transform

$$F(\alpha, s) = \int_{-\infty}^{+\infty} f(t \sin \alpha + s \cos \alpha, -t \cos \alpha + s \sin \alpha) dt$$

- Inverse Radon Transform

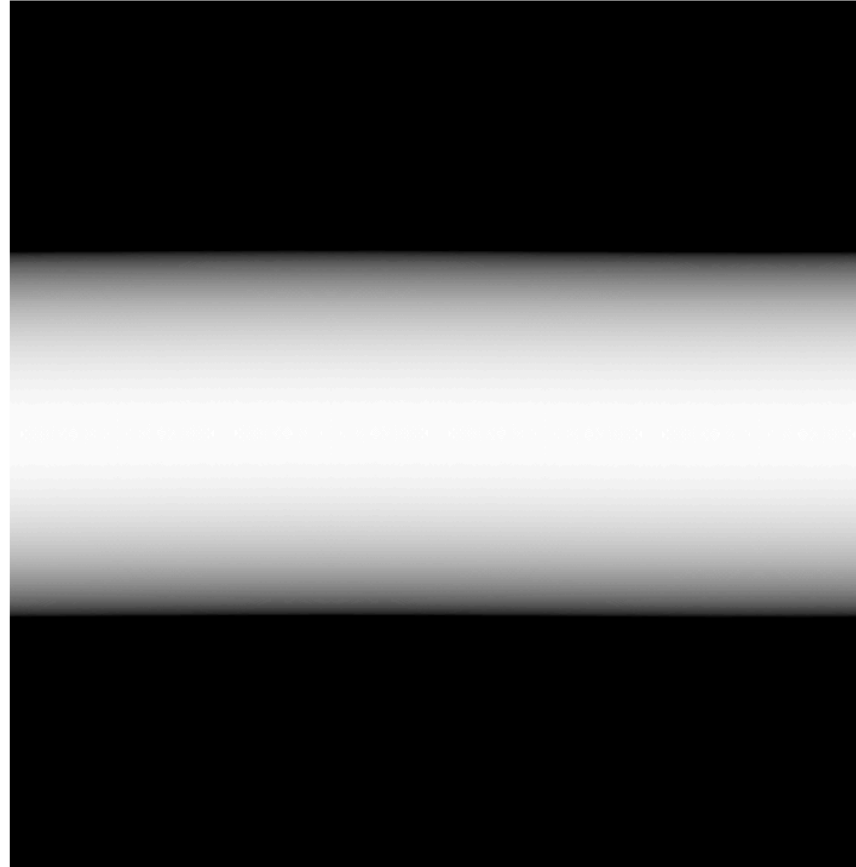
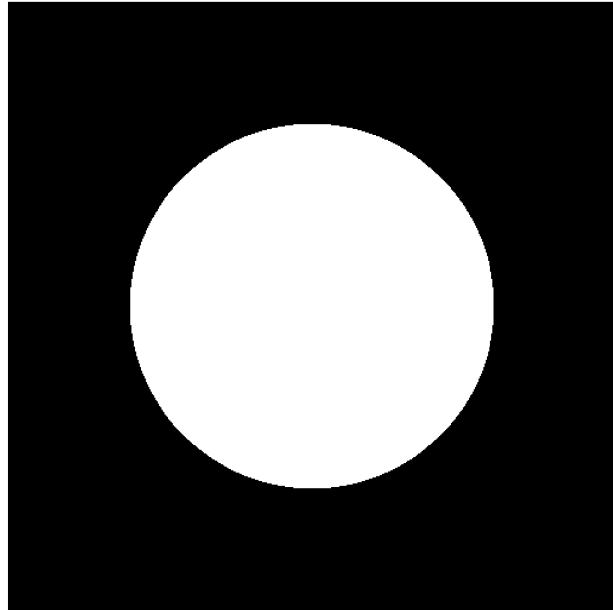
$$f(x, y) = \int_0^{2\pi} F(\alpha, x \cos \alpha + y \sin \alpha) d\alpha$$

Full circle in RT



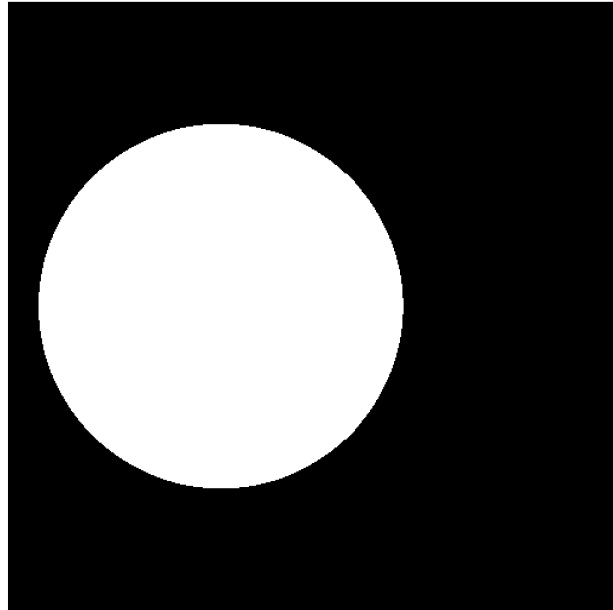
[Images: J. Kukal, 2009]

Full circle in RT



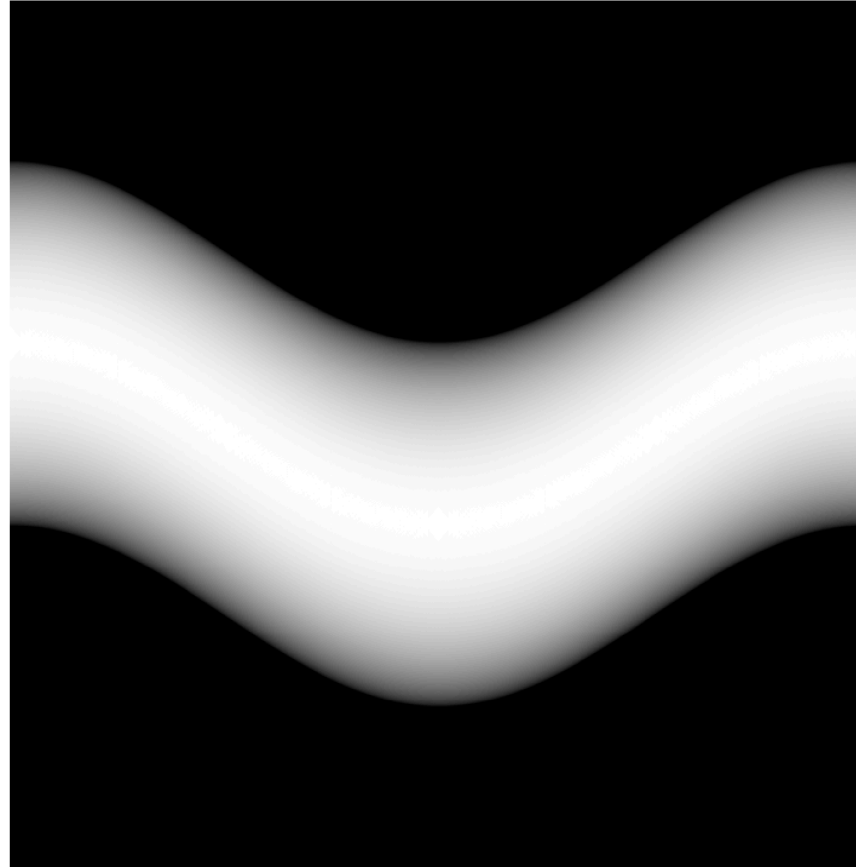
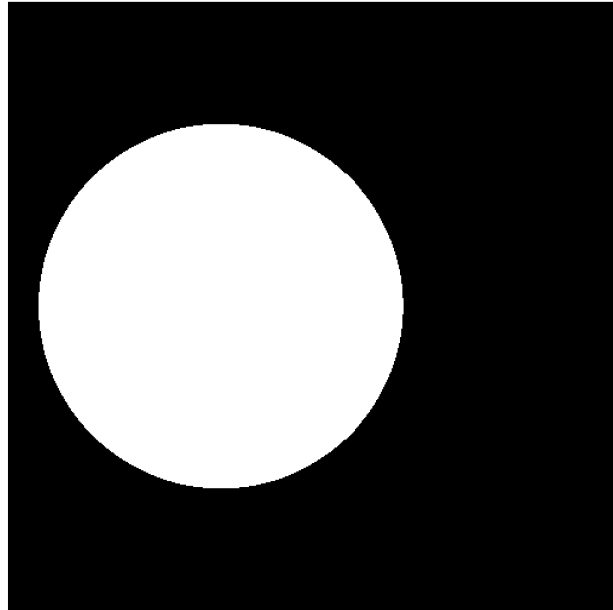
[Images: J. Kukal, 2009]

Shifted full circle in RT



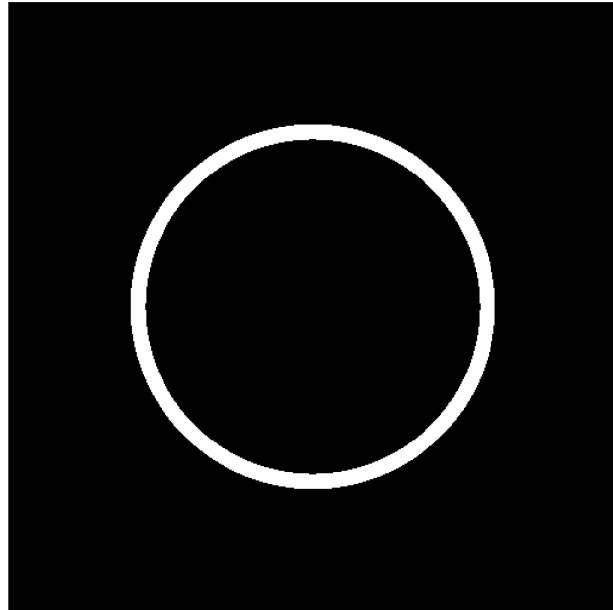
[Images: J. Kukal, 2009]

Shifted full circle in RT



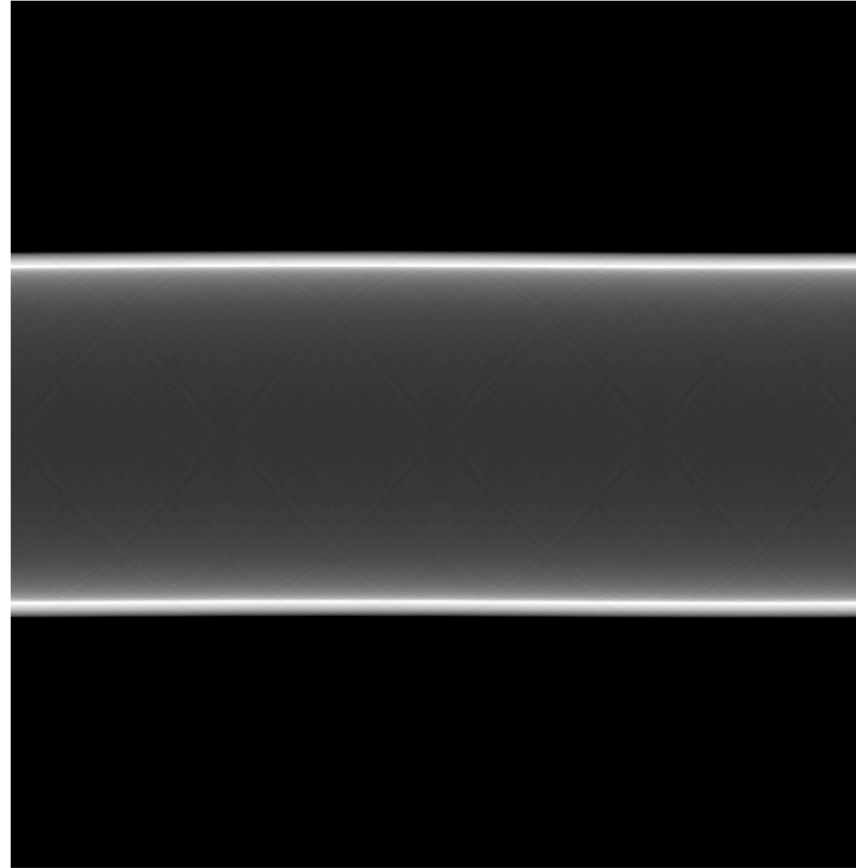
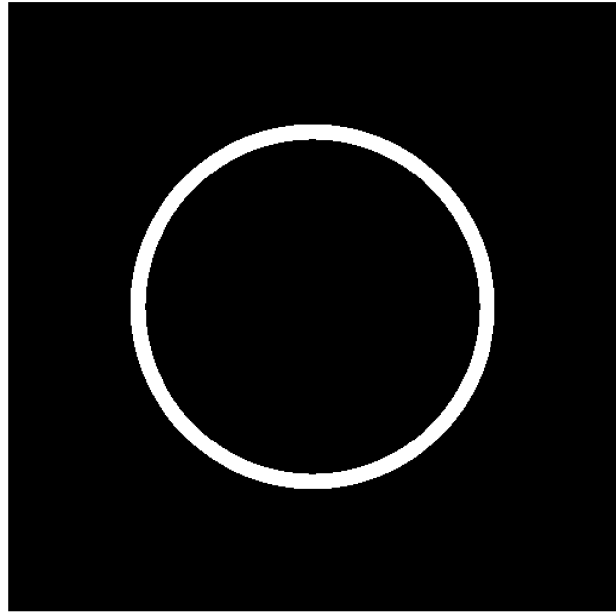
[Images: J. Kukal, 2009]

Empty circle in RT



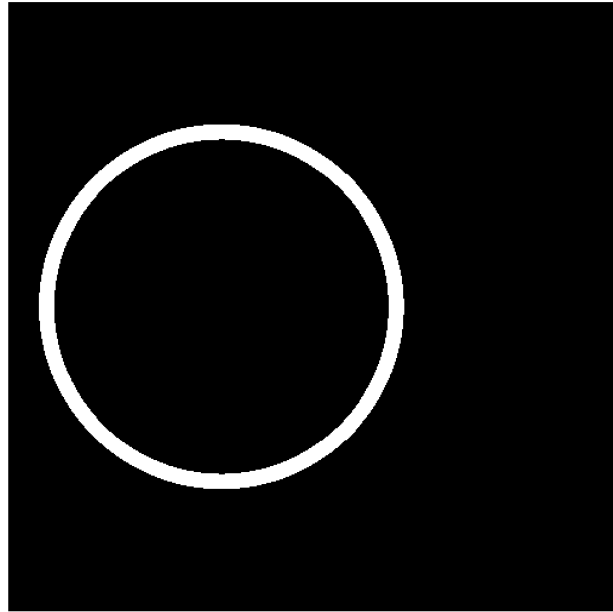
[Images: J. Kukal, 2009]

Empty circle in RT



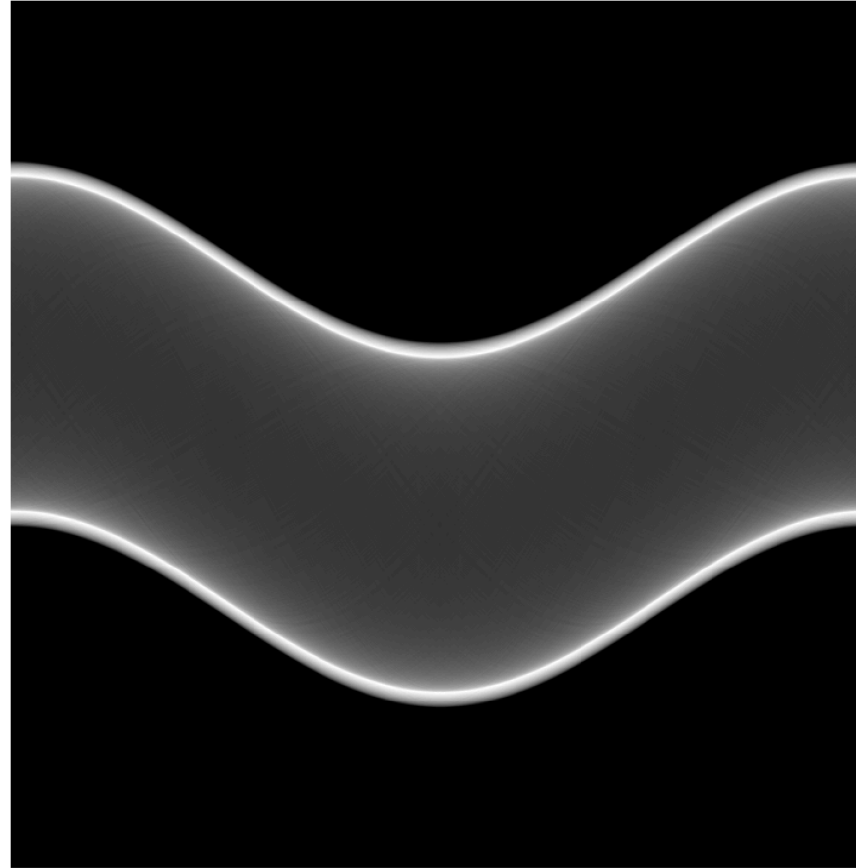
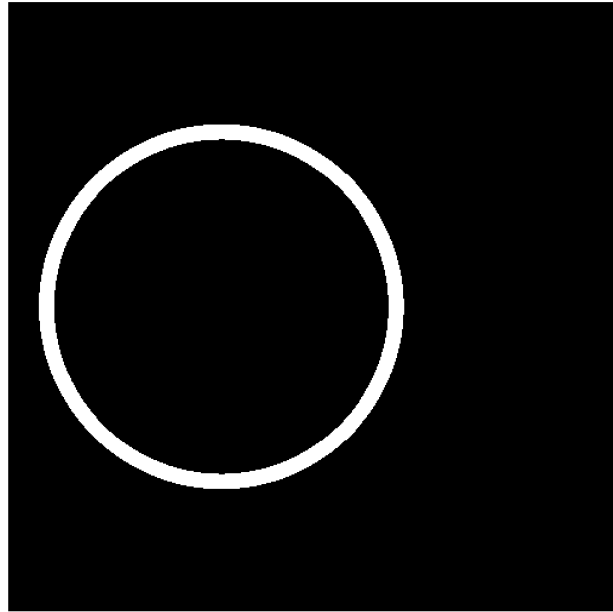
[Images: J. Kukal, 2009]

Shifted empty circle in RT



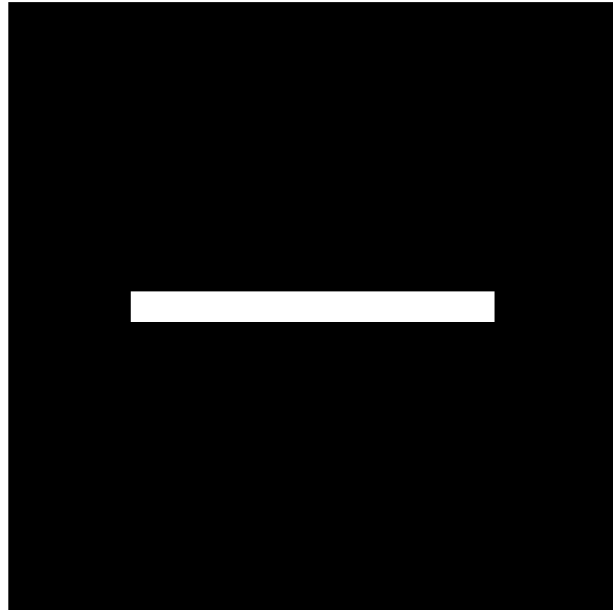
[Images: J. Kukal, 2009]

Shifted empty circle in RT



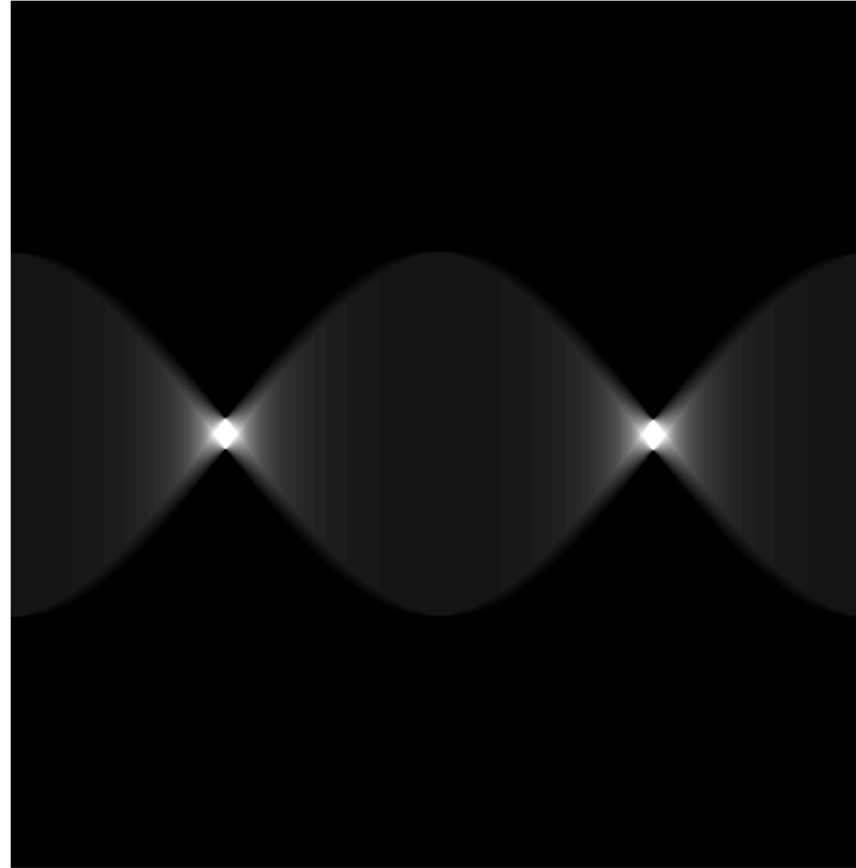
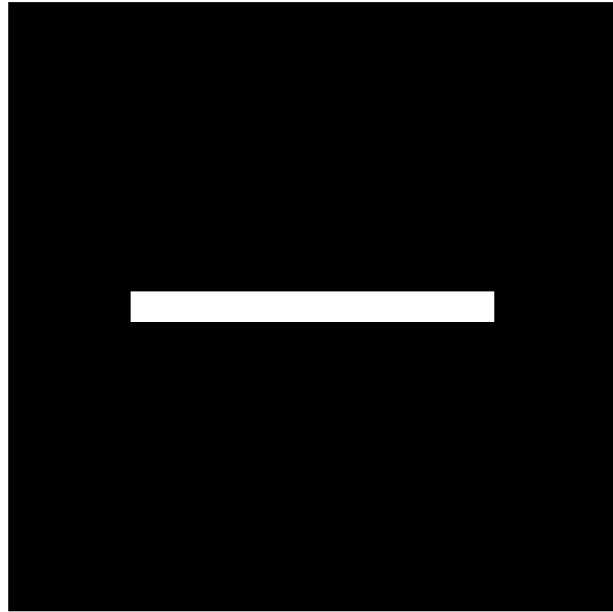
[Images: J. Kukal, 2009]

Thin stick in RT



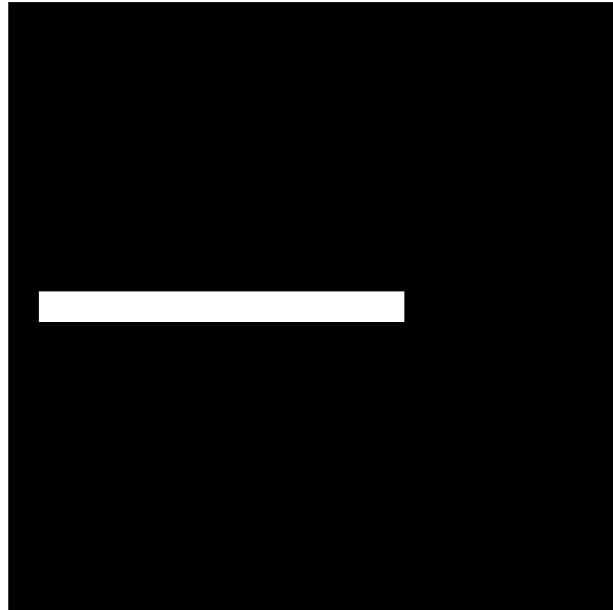
[Images: J. Kukal, 2009]

Thin stick in RT



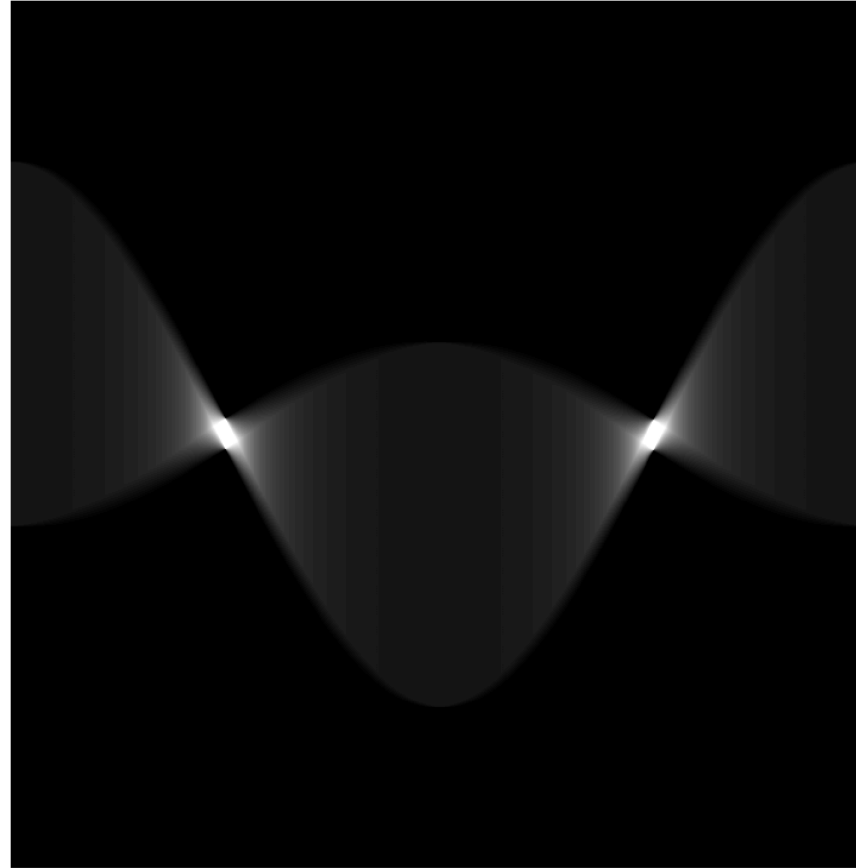
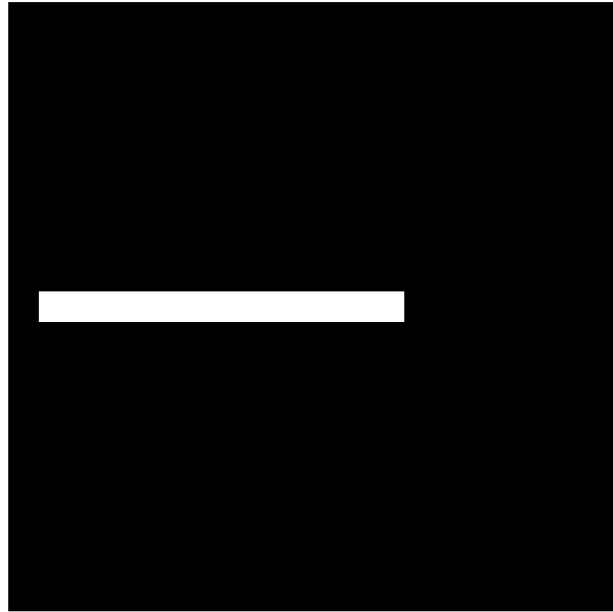
[Images: J. Kukul, 2009]

Shifted thin stick in RT



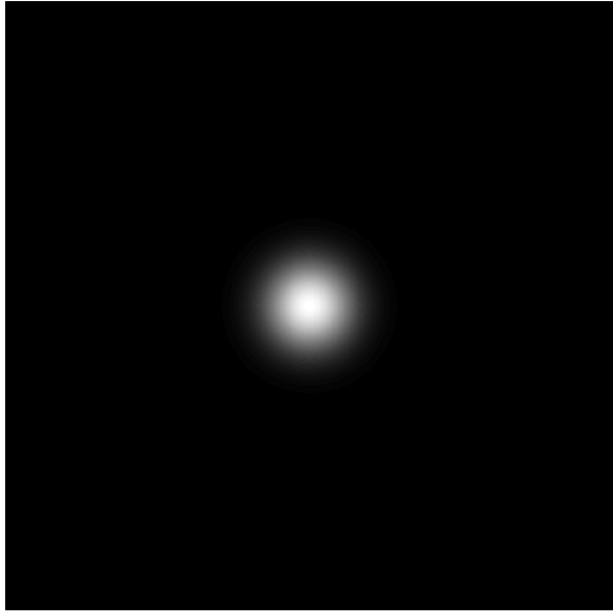
[Images: J. Kukal, 2009]

Shifted thin stick in RT



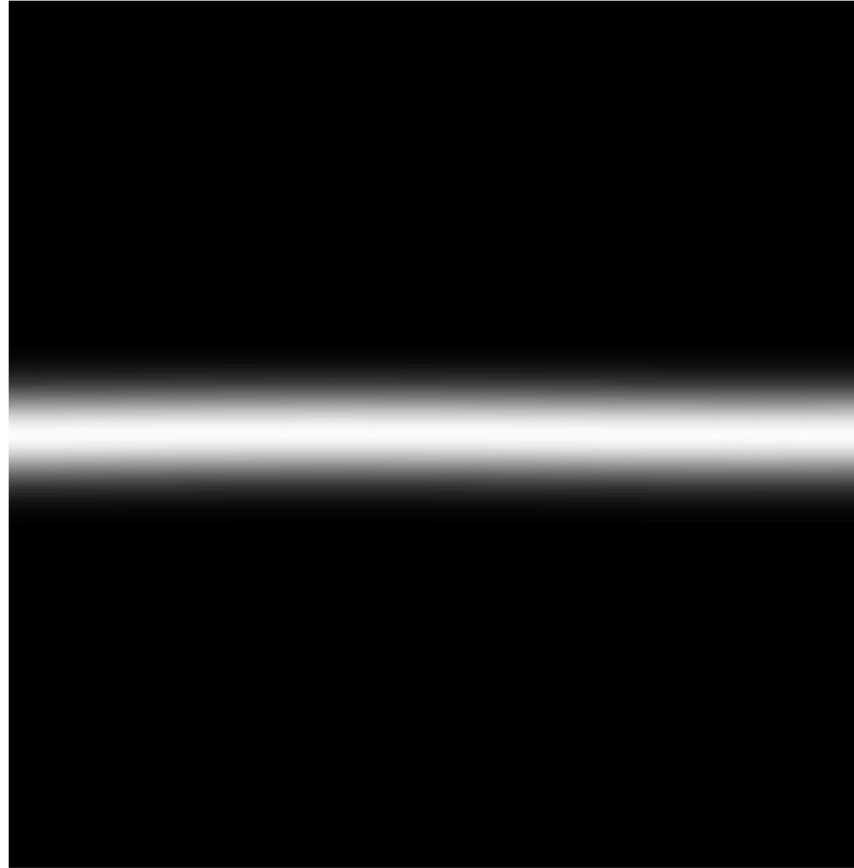
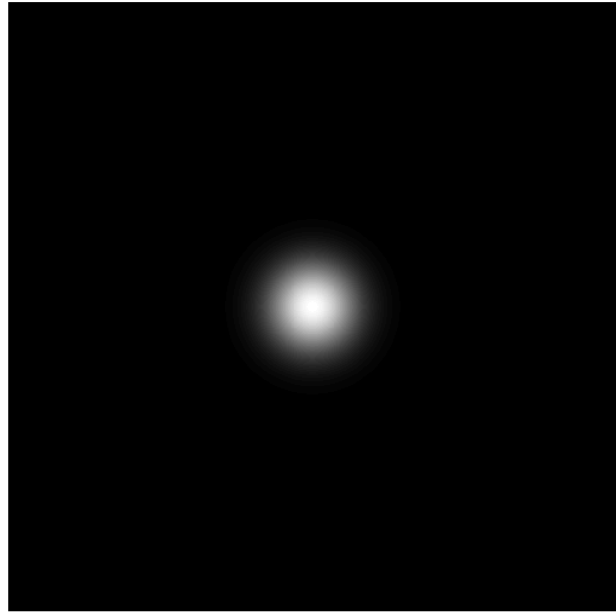
[Images: J. Kukal, 2009]

2D Gaussian in RT



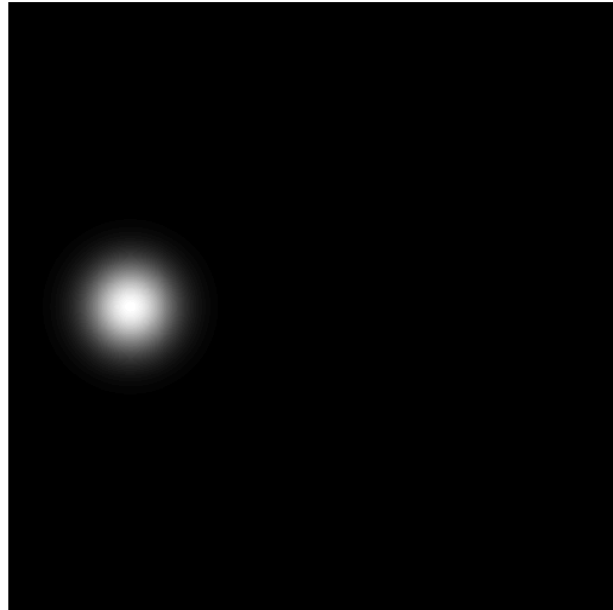
[Images: J. Kukul, 2009]

2D Gaussian in RT



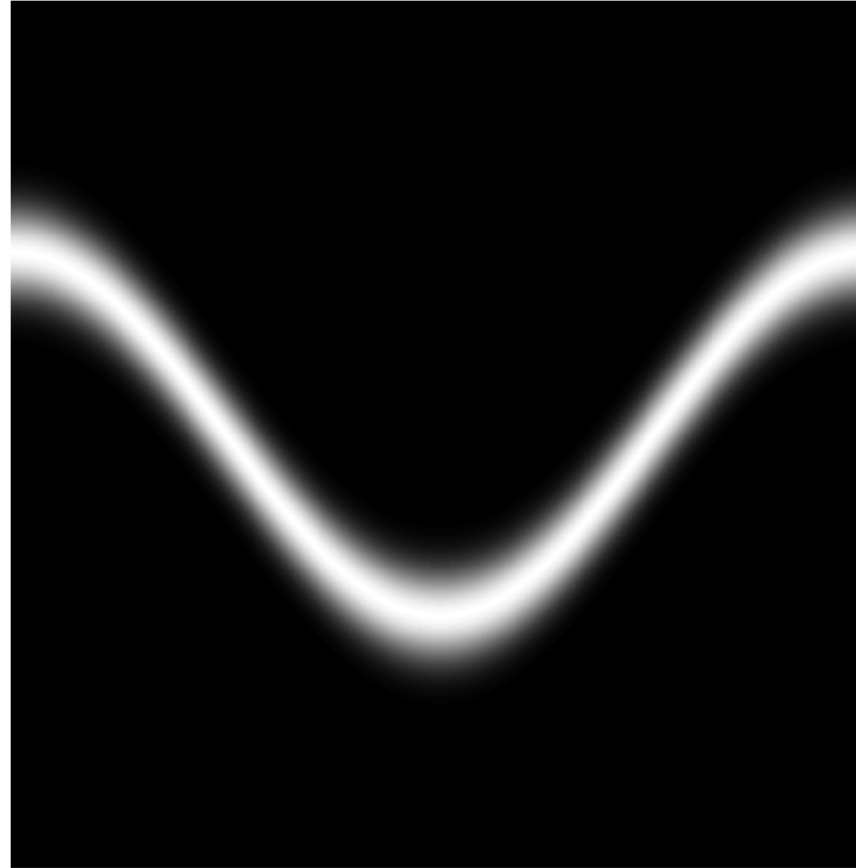
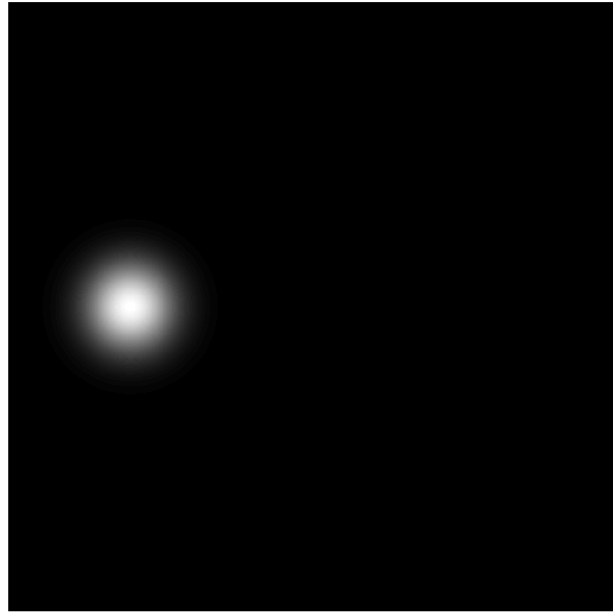
[Images: J. Kukal, 2009]

Shifted 2D Gaussian in RT



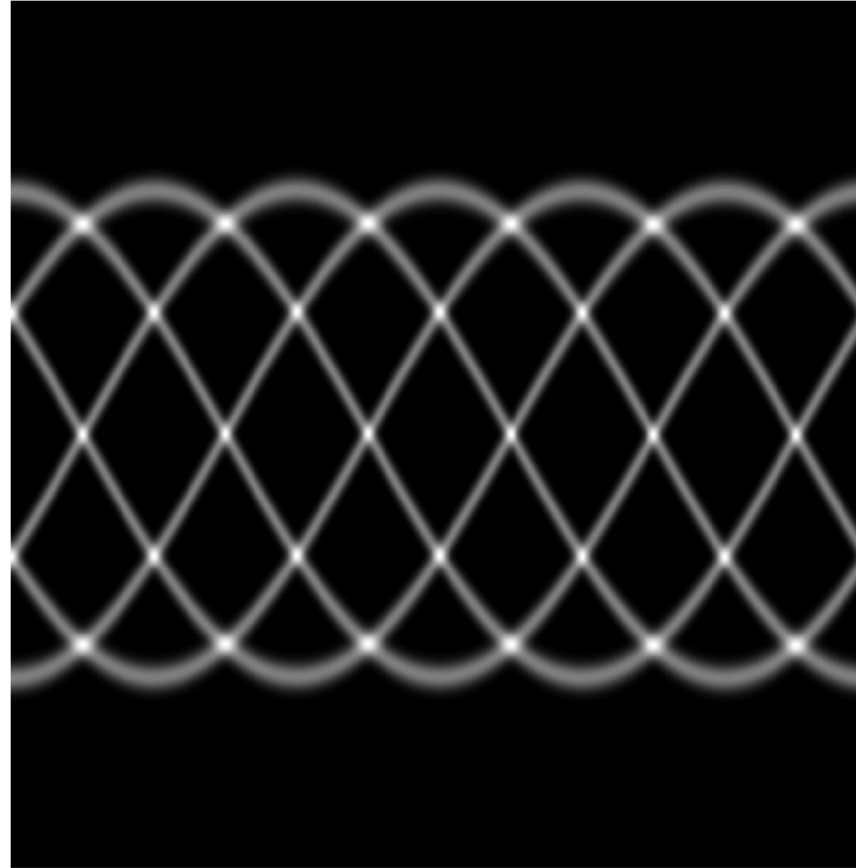
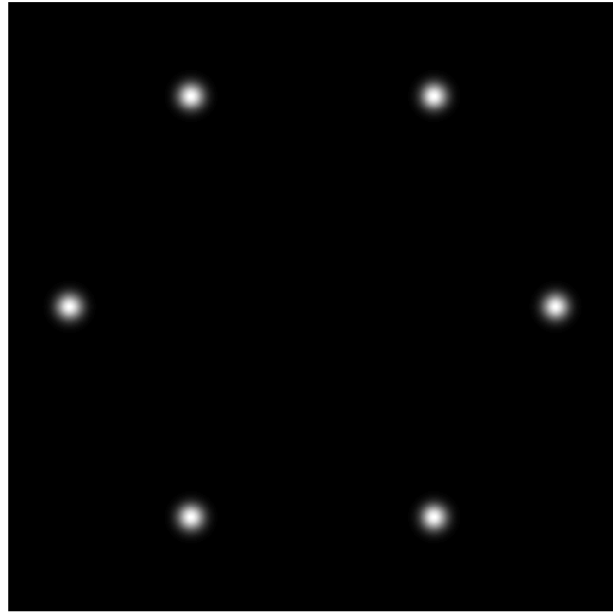
[Images: J. Kukal, 2009]

Shifted 2D Gaussian in RT



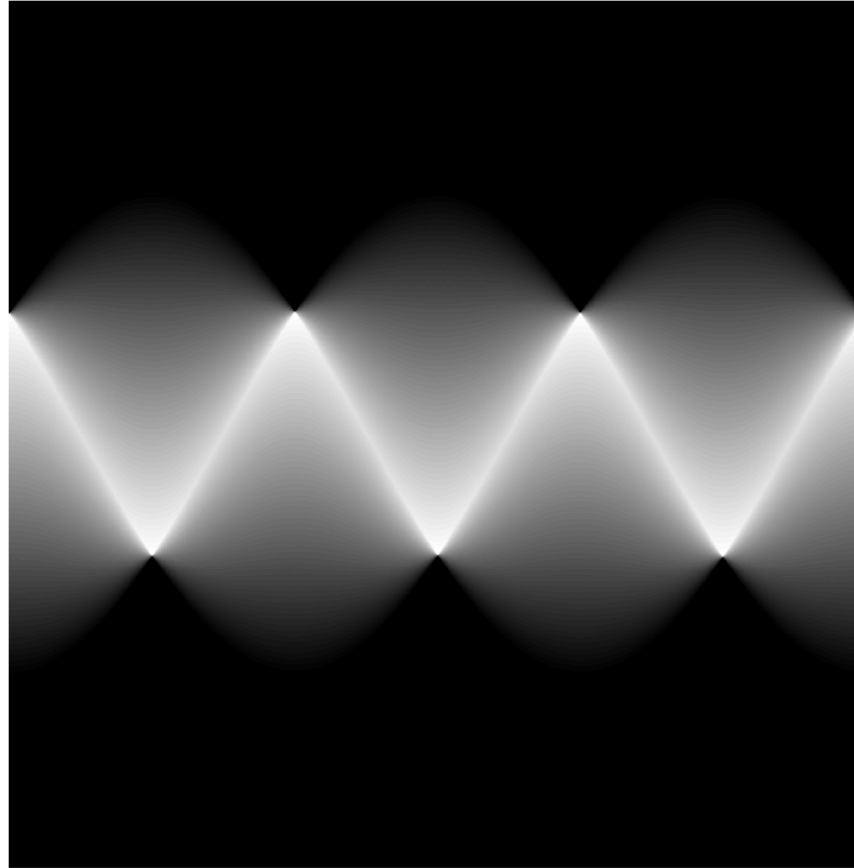
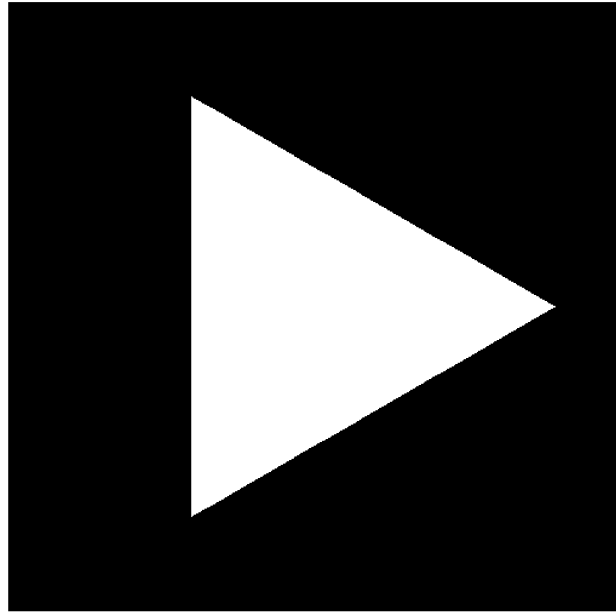
[Images: J. Kukal, 2009]

Six 2D Gaussians in RT



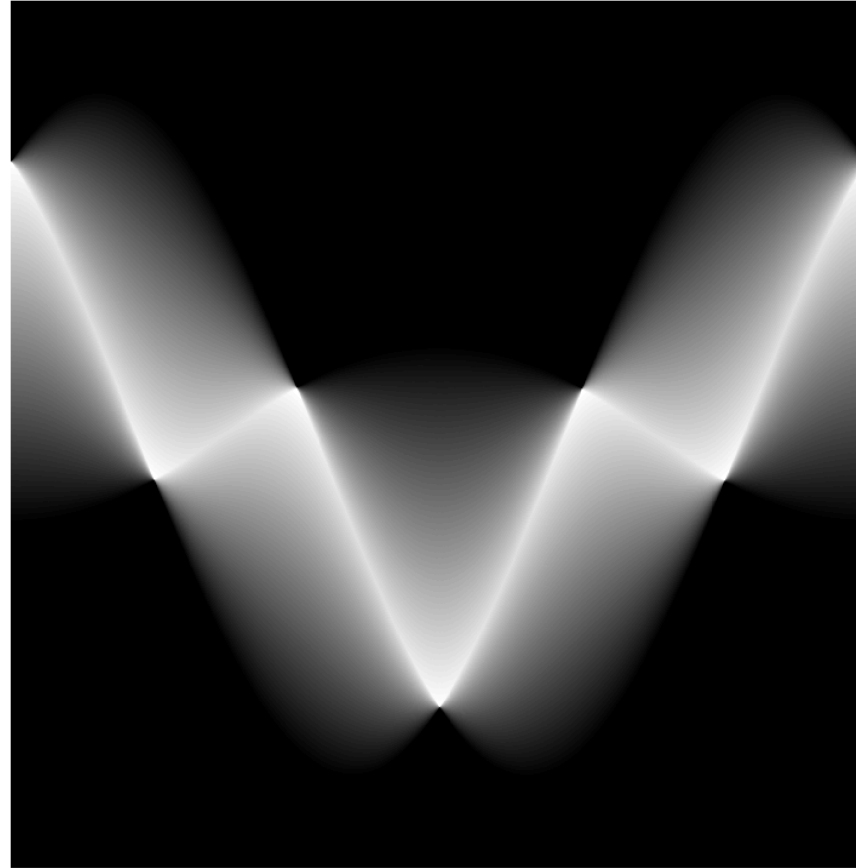
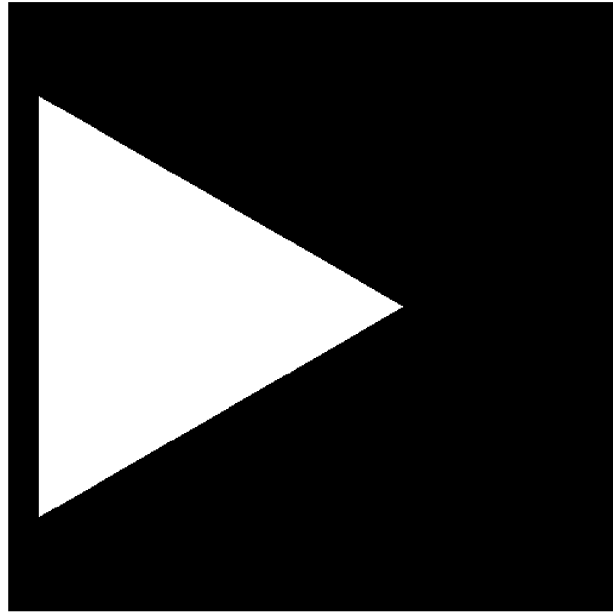
[Images: J. Kukal, 2009]

Full triangle in RT



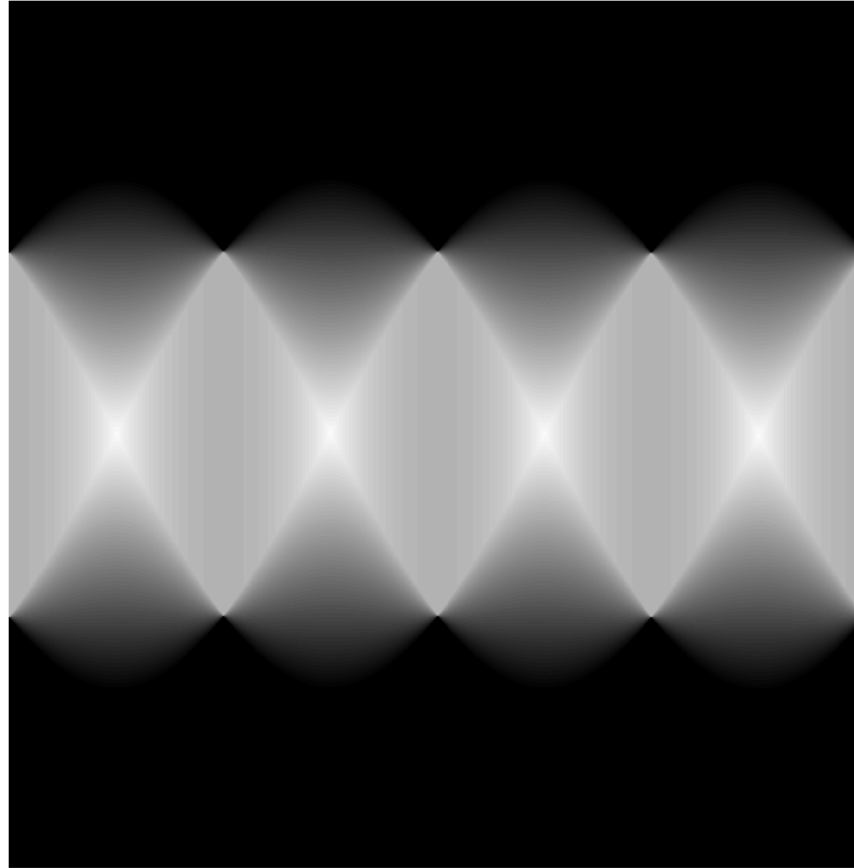
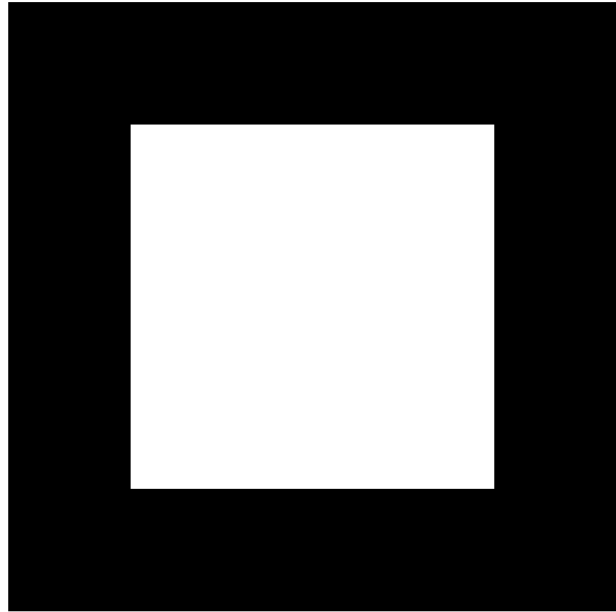
[Images: J. Kukal, 2009]

Shifted full triangle in RT



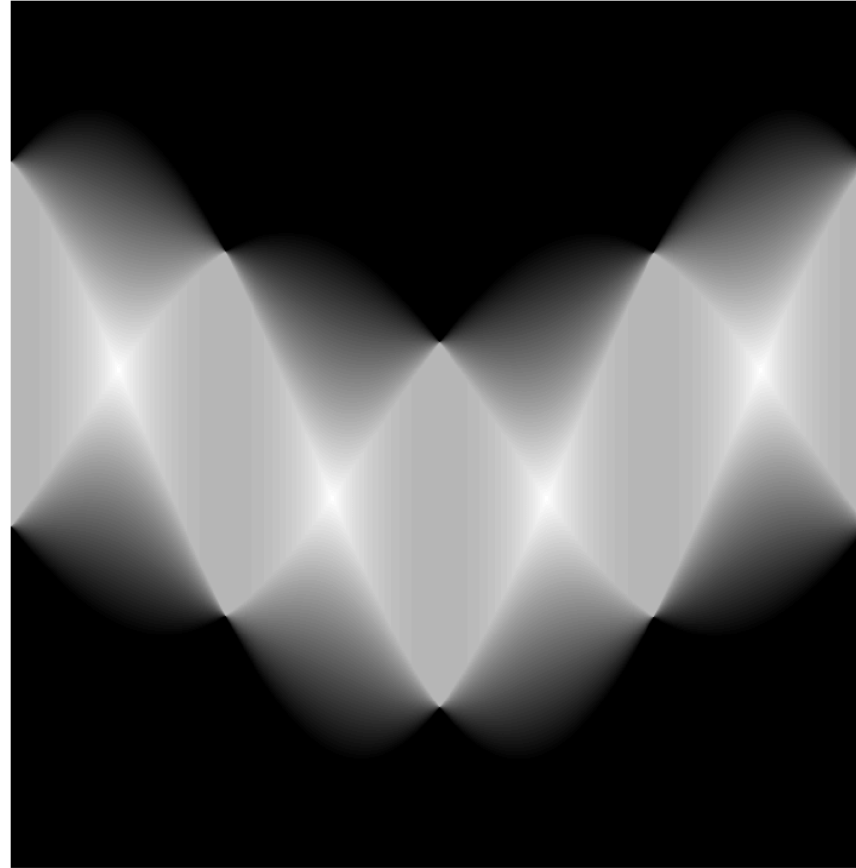
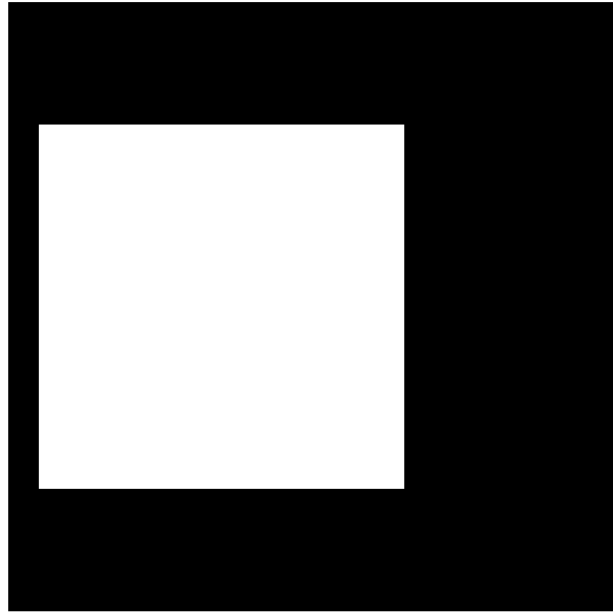
[Images: J. Kukal, 2009]

Full square in RT



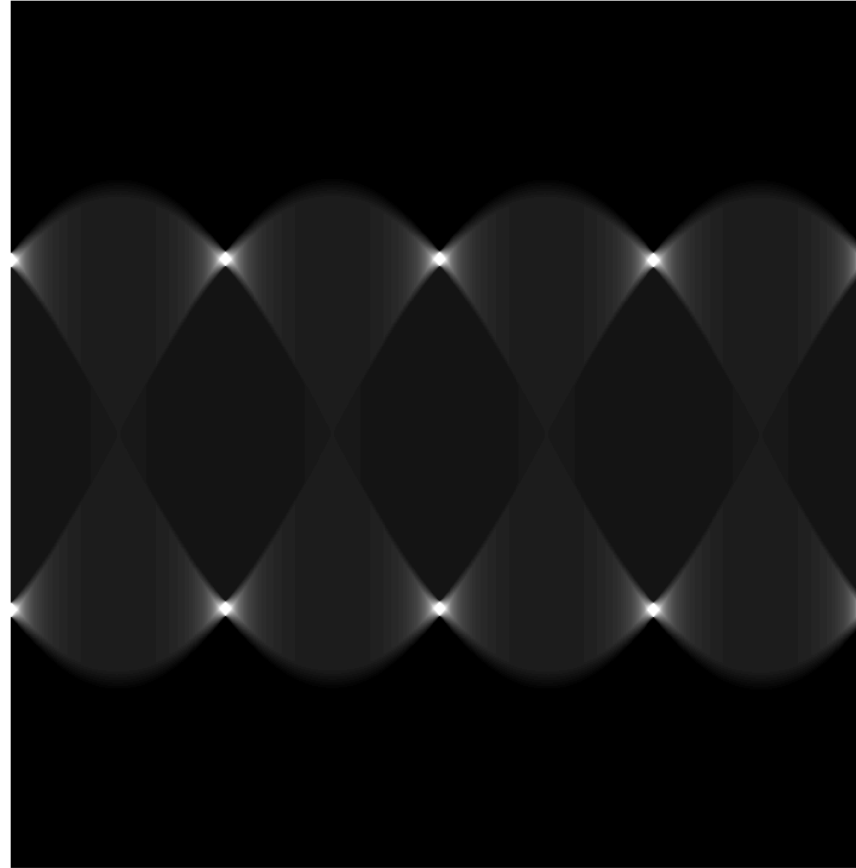
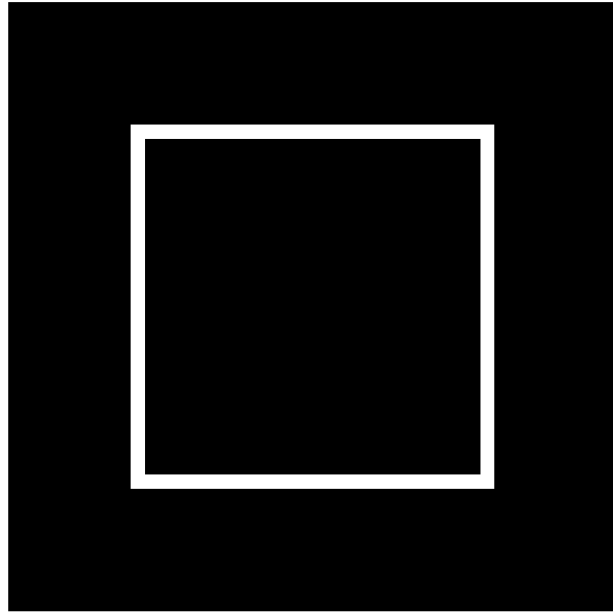
[Images: J. Kukal, 2009]

Shifted full square in RT



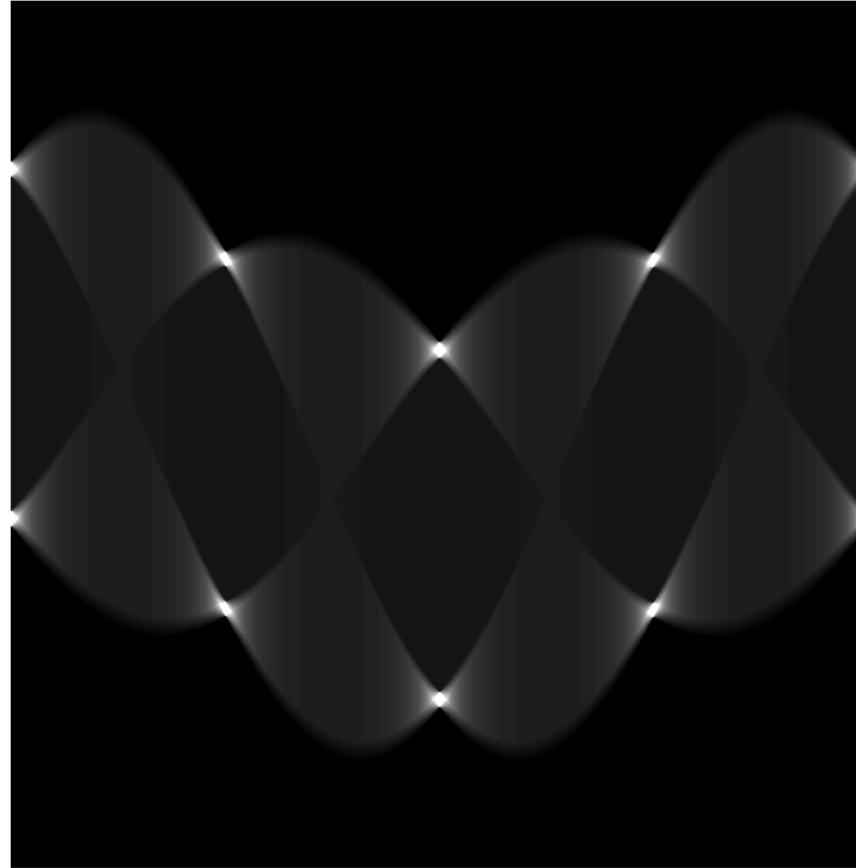
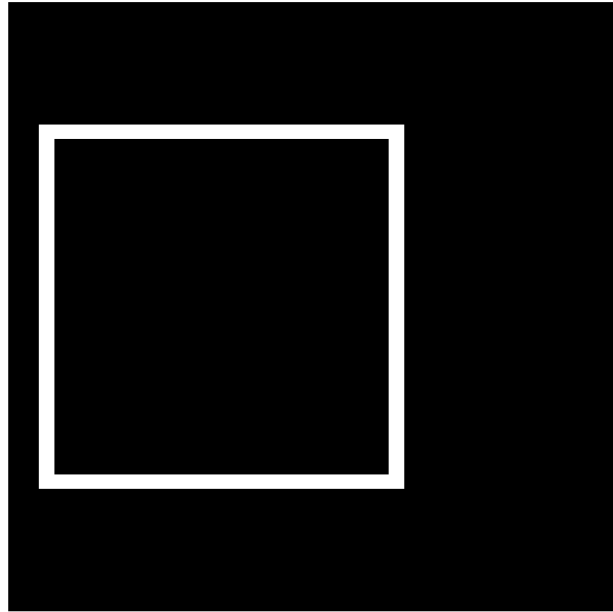
[Images: J. Kukal, 2009]

Empty square in RT



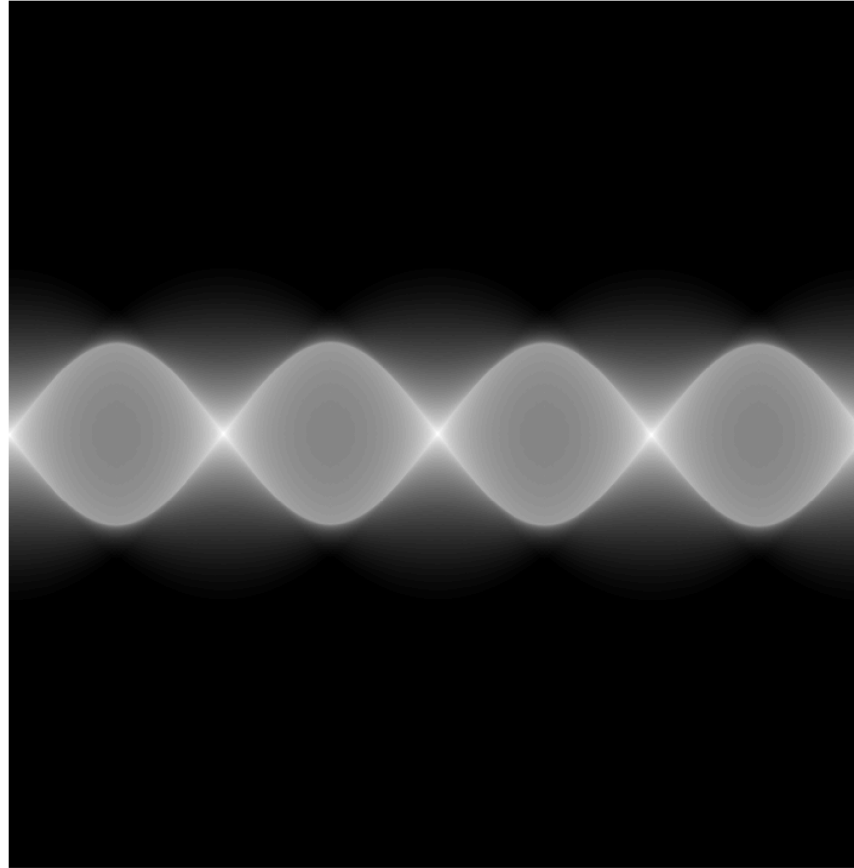
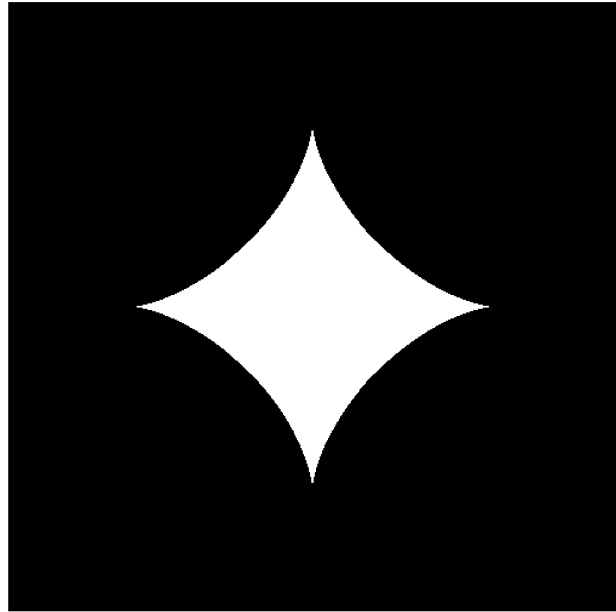
[Images: J. Kukal, 2009]

Shifted empty square in RT



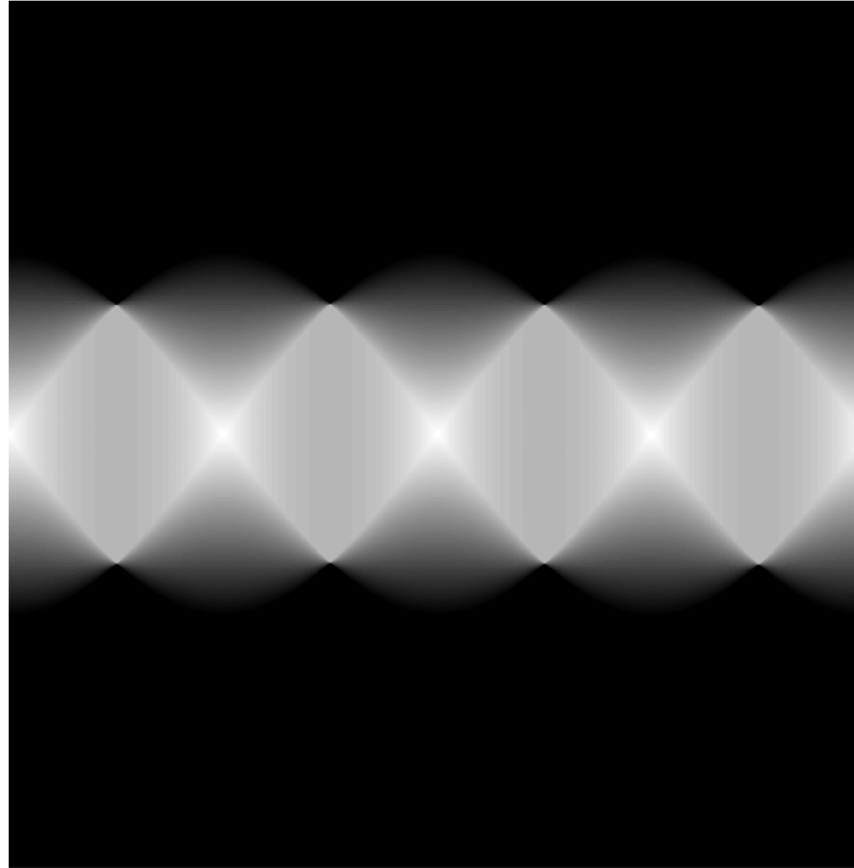
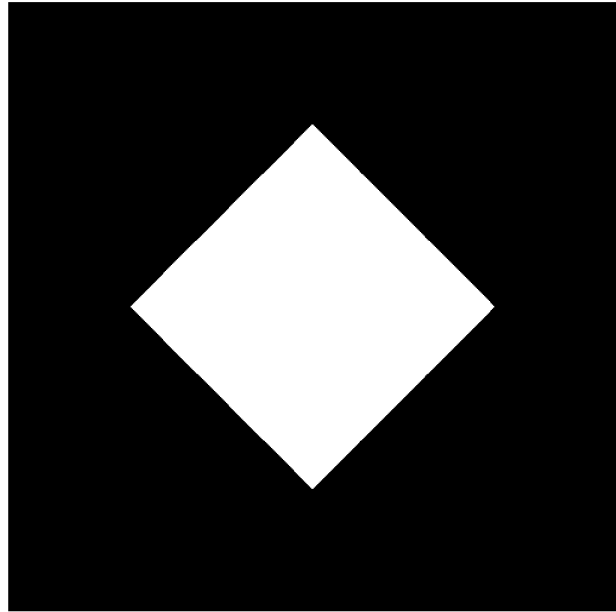
[Images: J. Kukal, 2009]

$$|x|^{2/3} + |y|^{2/3} \leq 1 \text{ in RT}$$



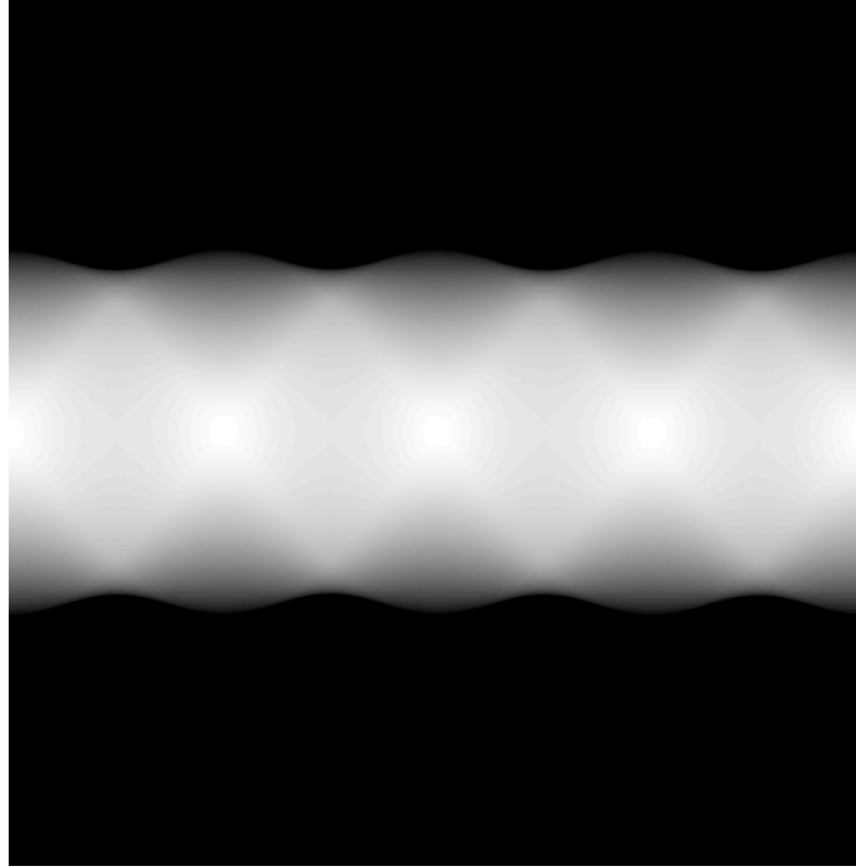
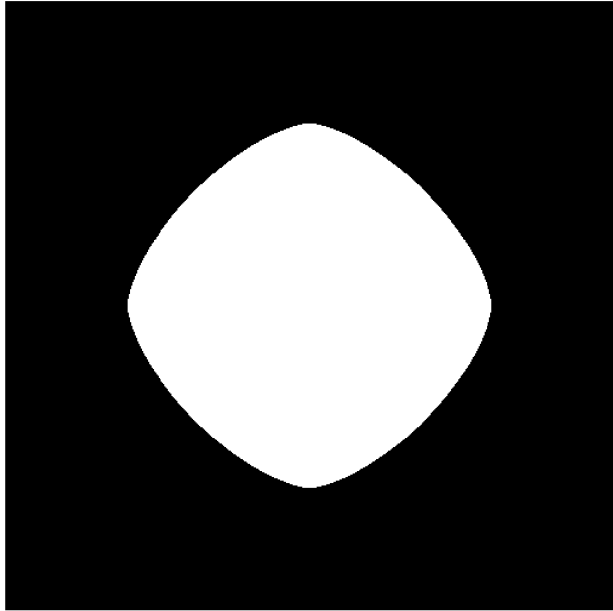
[Images: J. Kukal, 2009]

$$|x| + |y| \leq 1 \text{ in RT}$$



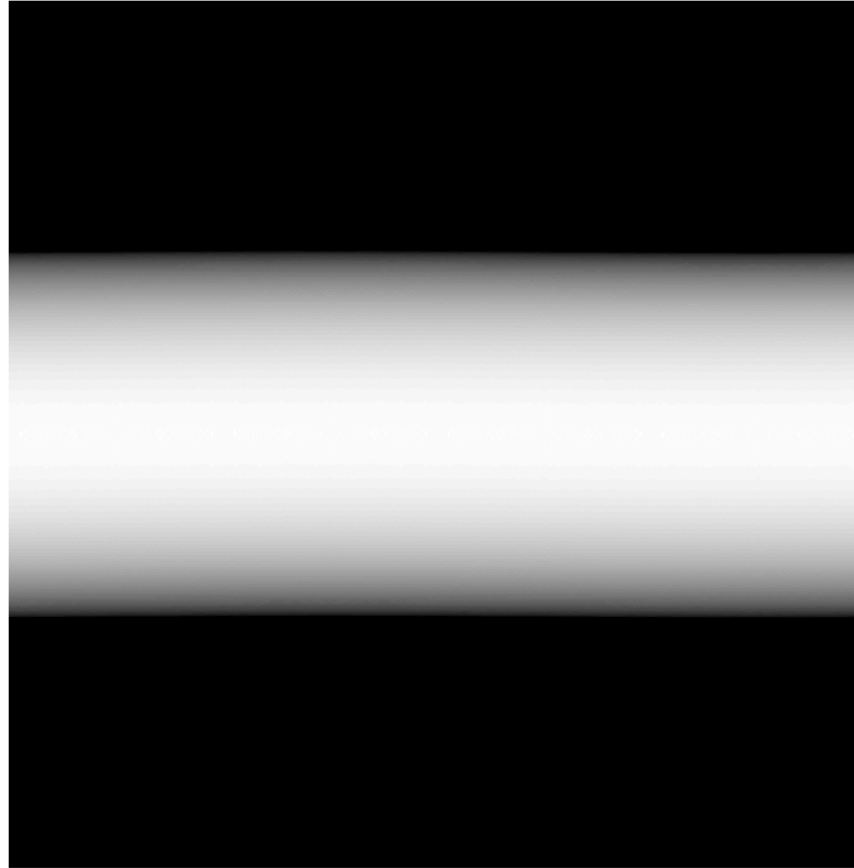
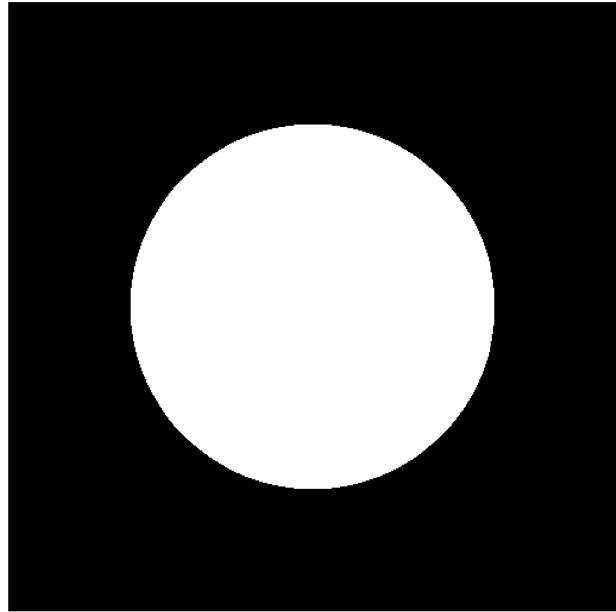
[Images: J. Kukal, 2009]

$$|x|^{3/2} + |y|^{3/2} \leq 1 \text{ in RT}$$



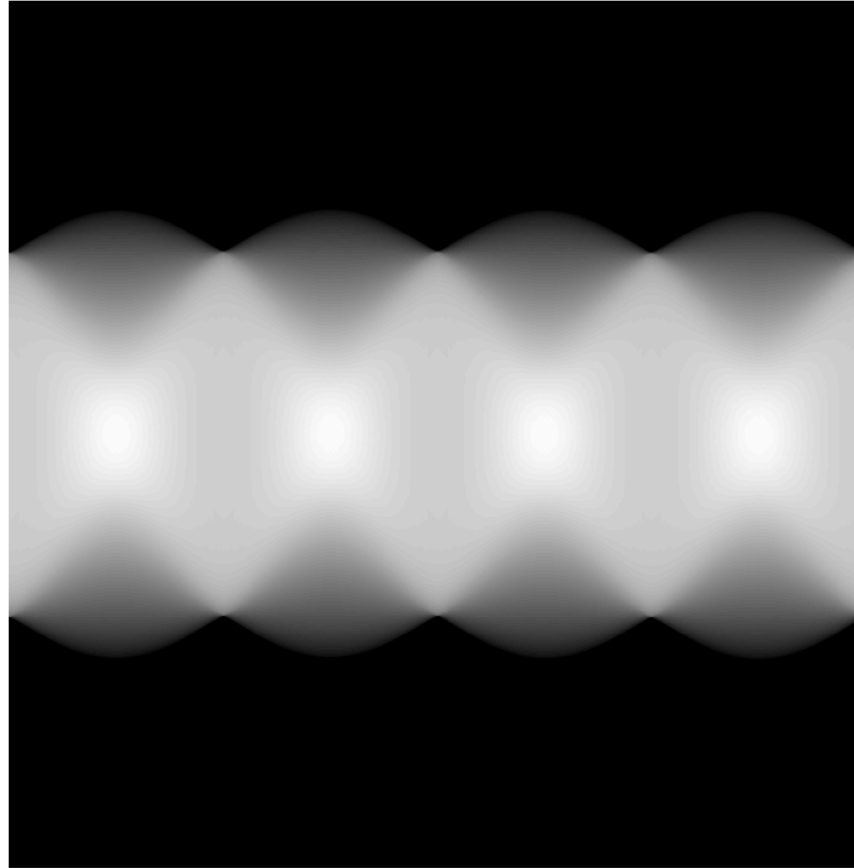
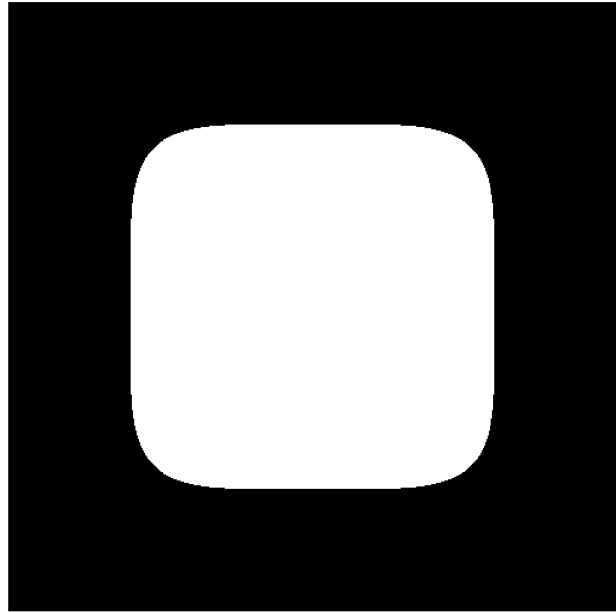
[Images: J. Kukal, 2009]

$$|x|^2 + |y|^2 \leq 1 \text{ in RT}$$



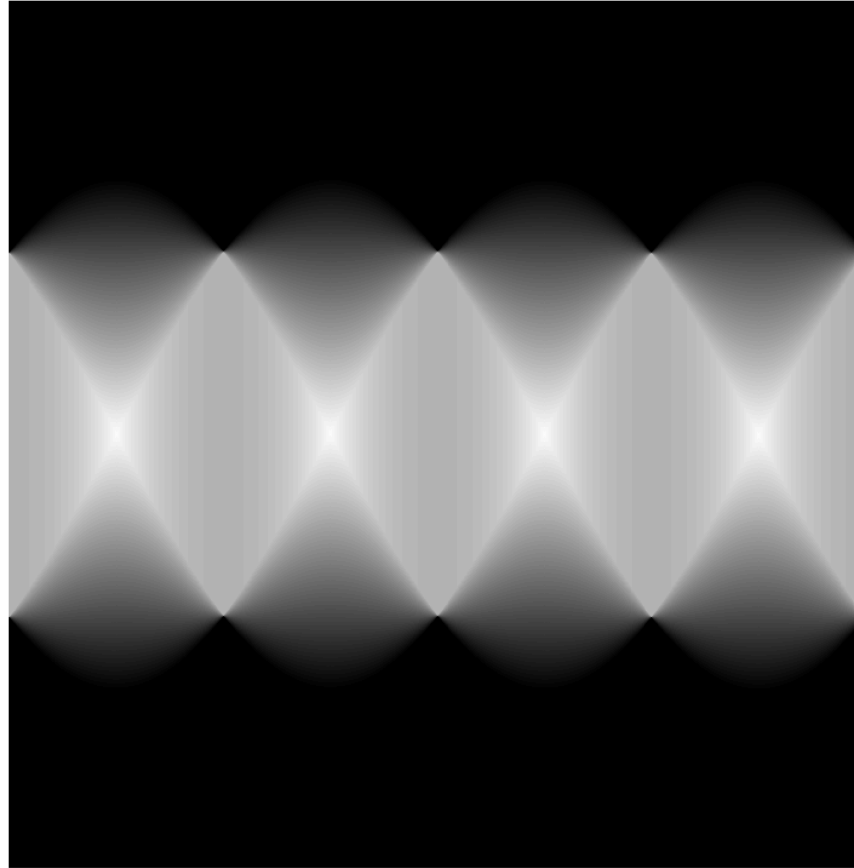
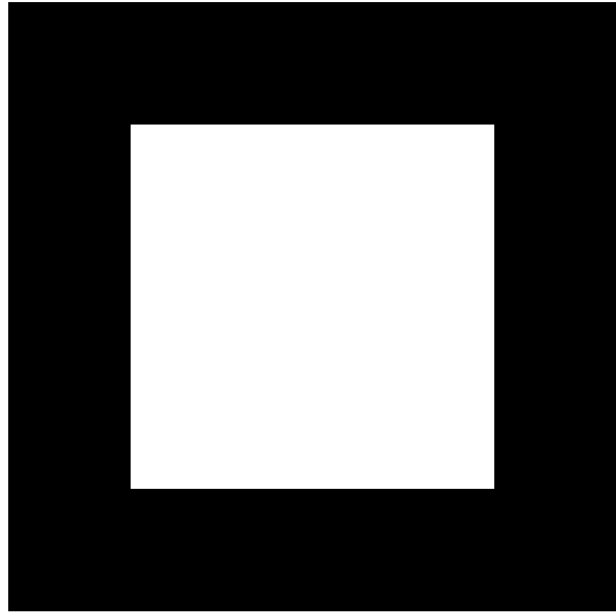
[Images: J. Kukal, 2009]

$$|x|^6 + |y|^6 \leq 1 \text{ in RT}$$



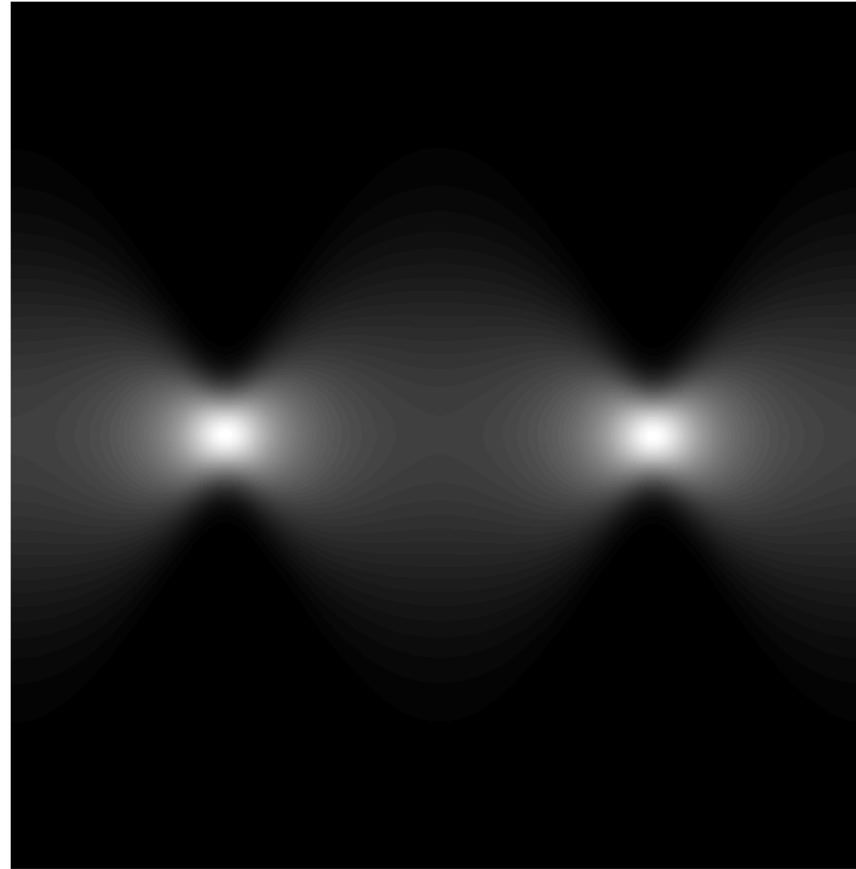
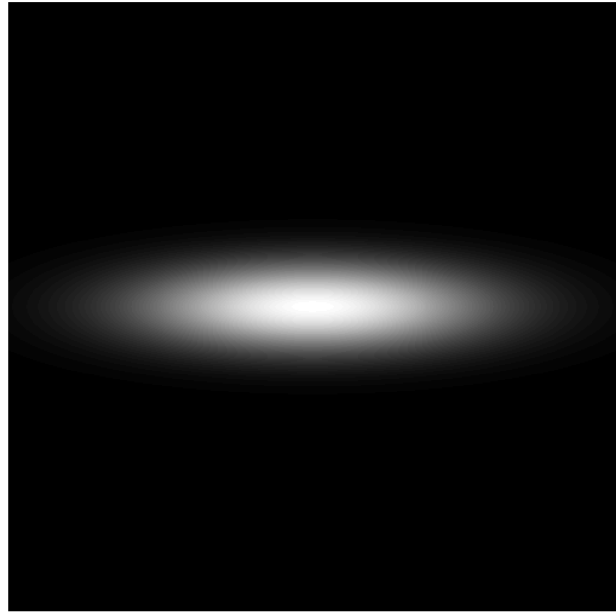
[Images: J. Kukal, 2009]

$$|x|^n + |y|^n \leq 1 \text{ for } n \rightarrow \infty \text{ in RT}$$



[Images: J. Kukal, 2009]

Smooth elliptic object in RT



[Images: J. Kukal, 2009]



Radon Transform Properties

- Image of any $f + g$ is $F + G$
- Image of cf is cF for any real c
- Rotation of f causes translation of F in ζ
- Scaling of f in (x,y) causes scaling of F in s
- Image of a point (2D Dirac function) is sine wave line
- Image of n points is a set of n sine wave lines
- Image of a line is a point (2D Dirac function)
- Image of polygon contour is a point set

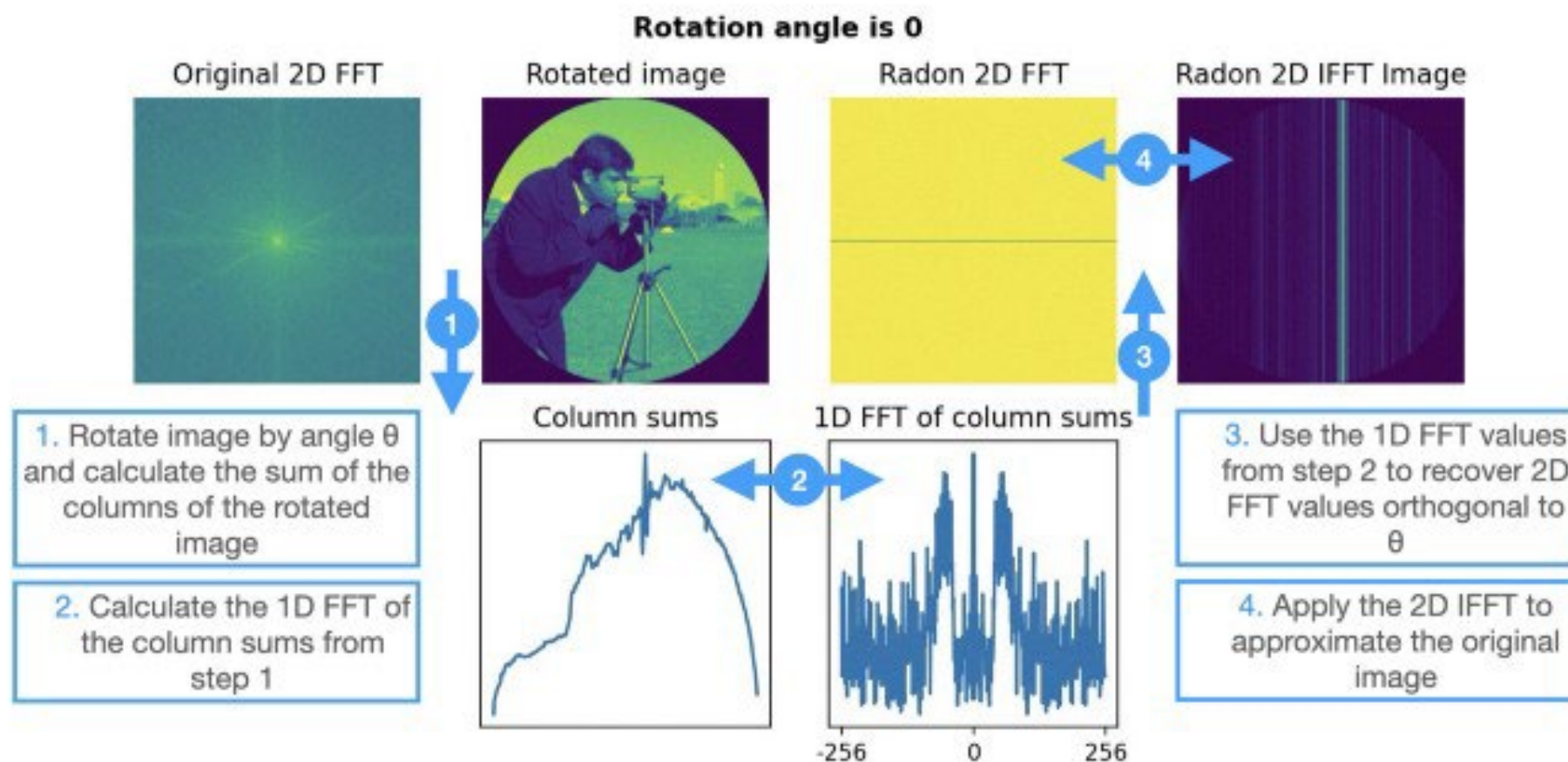


Radon Transform

- Often used to reconstruct a 3D volume from 2D slices (in medical applications)
- Why? How?
- Lets jump down to 2D from 1D slices...

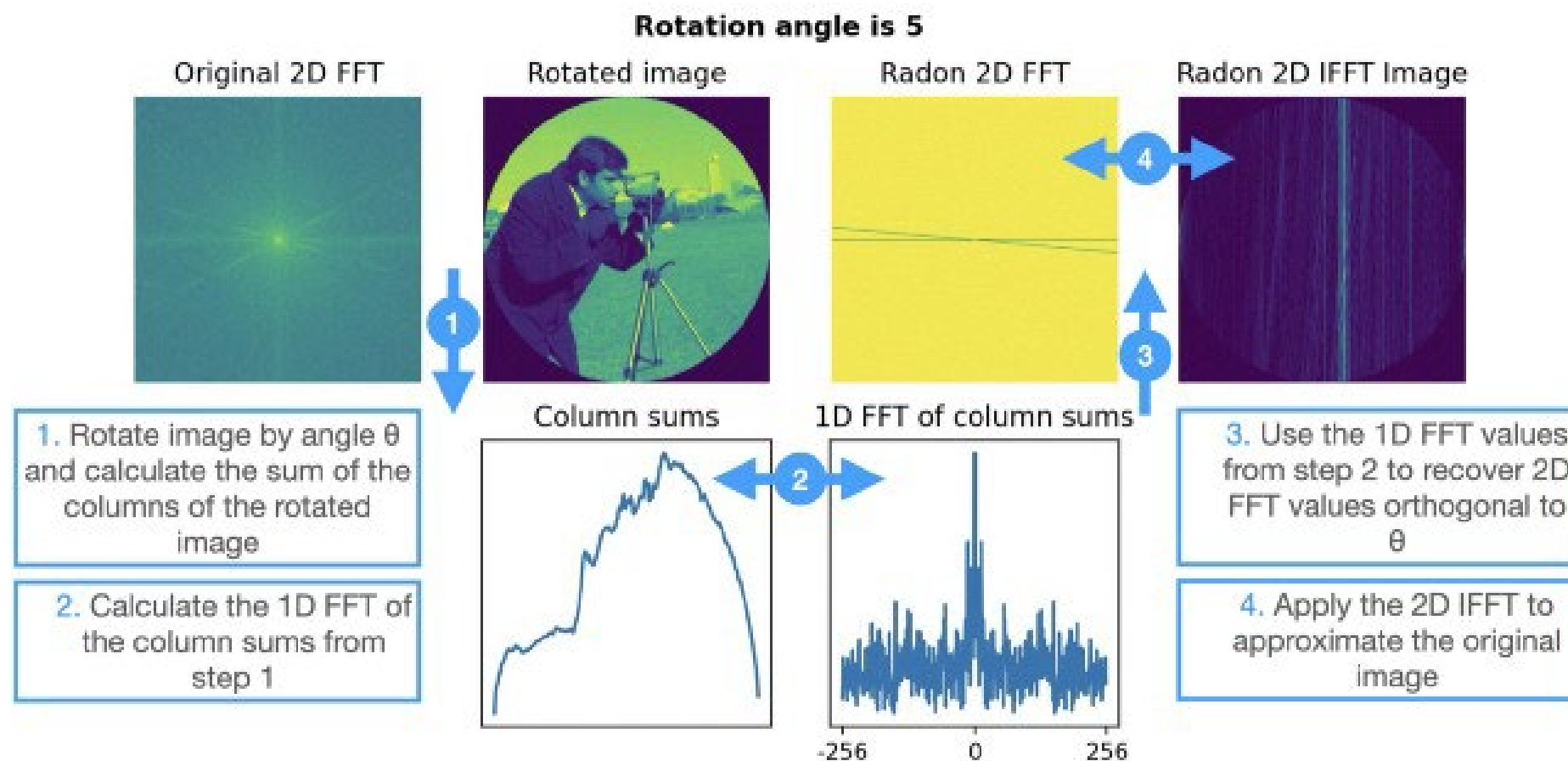


Radon Transform Based Reconstruction





Radon Transform Based Reconstruction

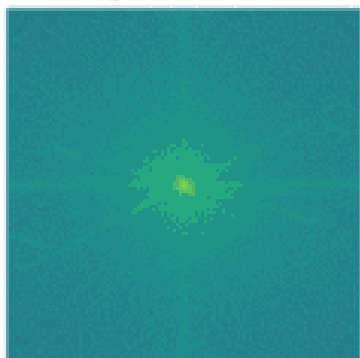




Radon Transform Based Reconstruction

Rotation angle is 0

Original 2D FFT



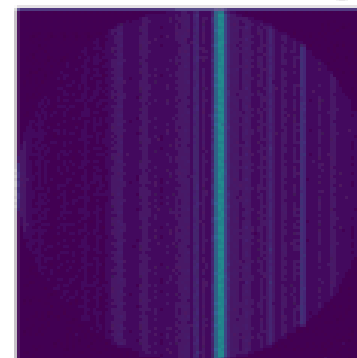
Rotated image



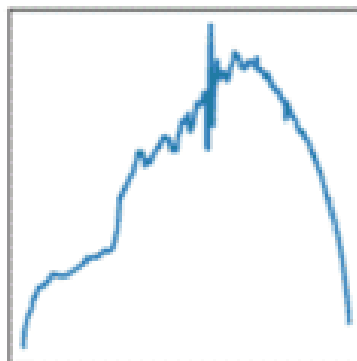
Radon 2D FFT



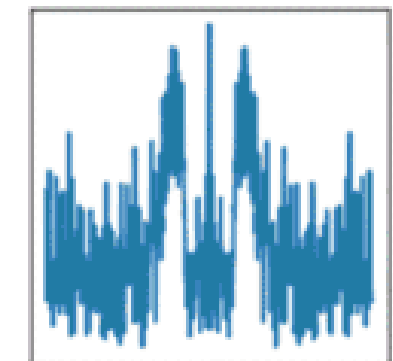
Radon 2D IFFT Image



Column sums

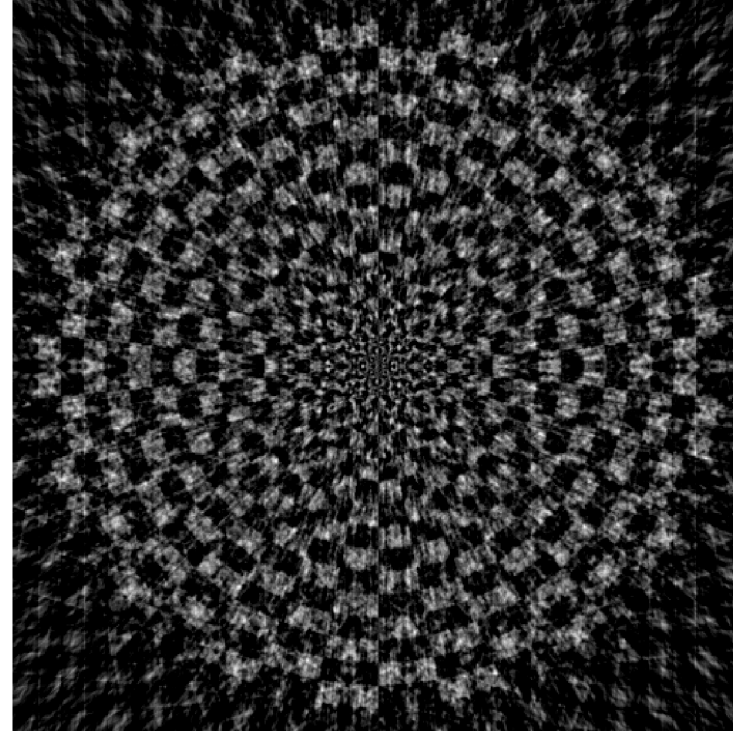
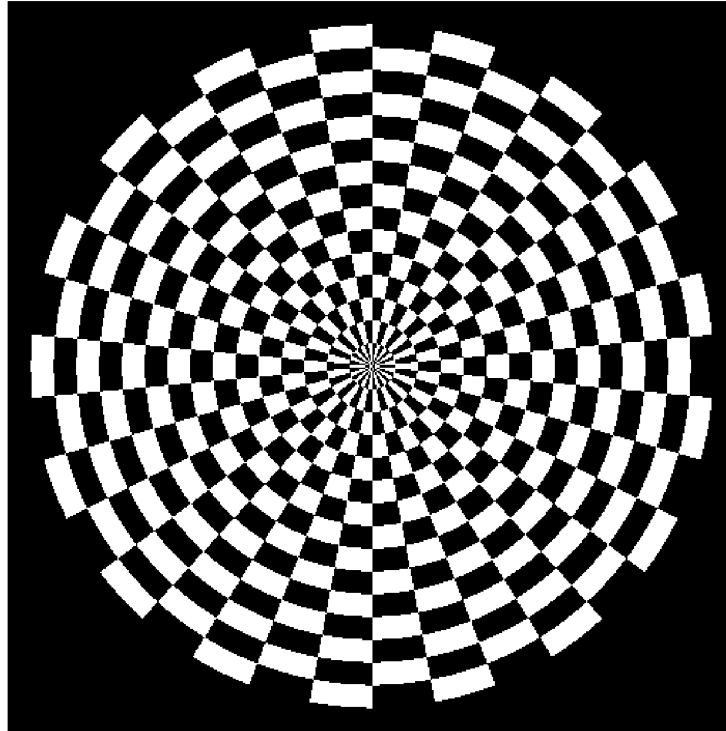


1D FFT of column sums



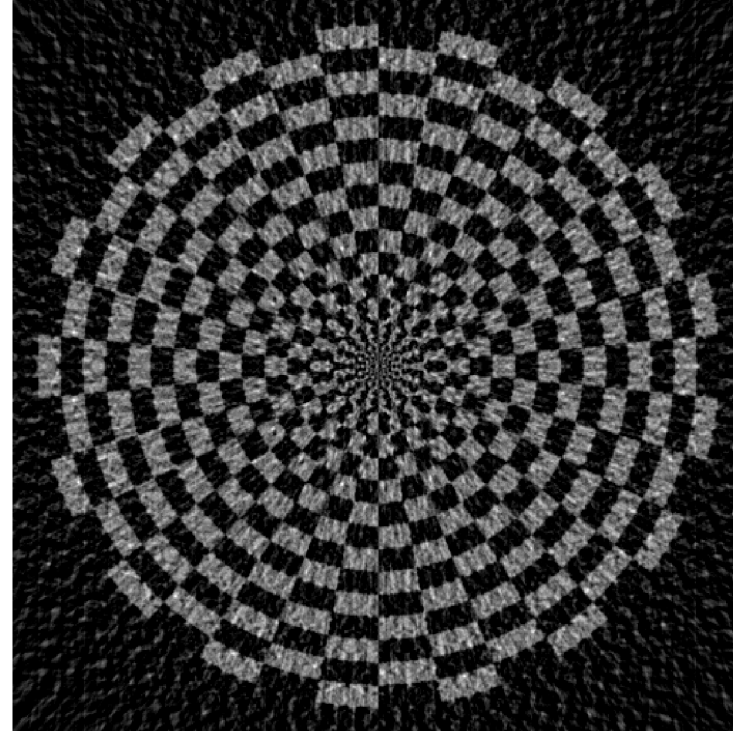
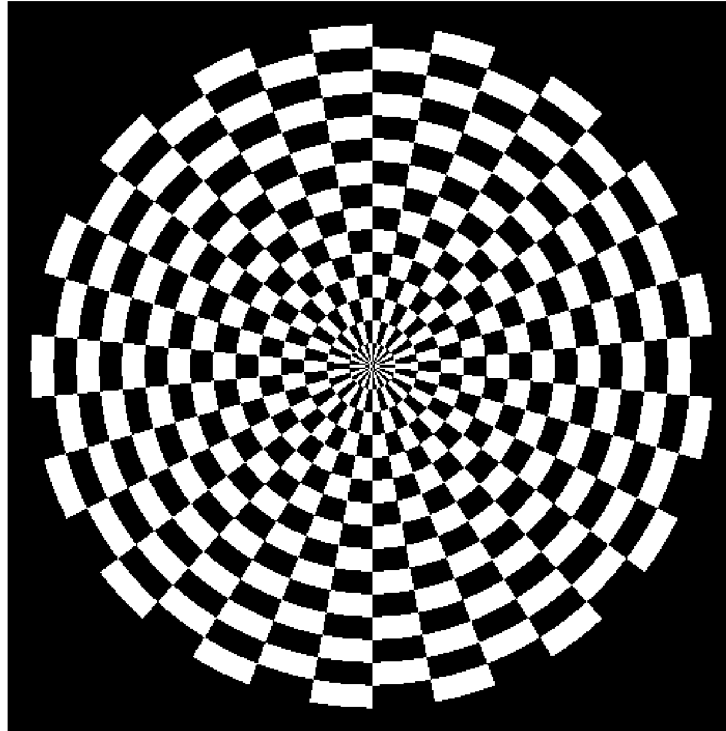
-256 0 256

Reconstruction from 32 angles



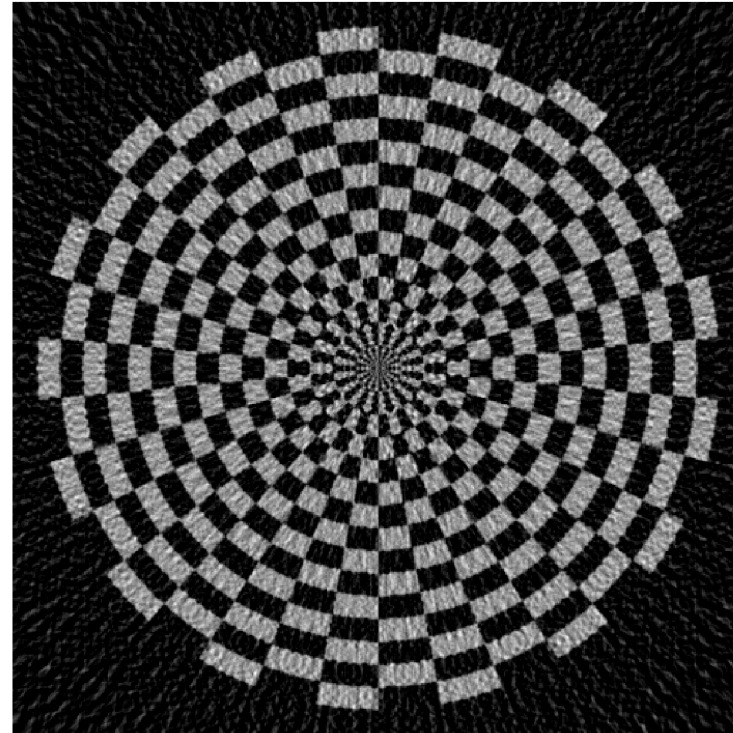
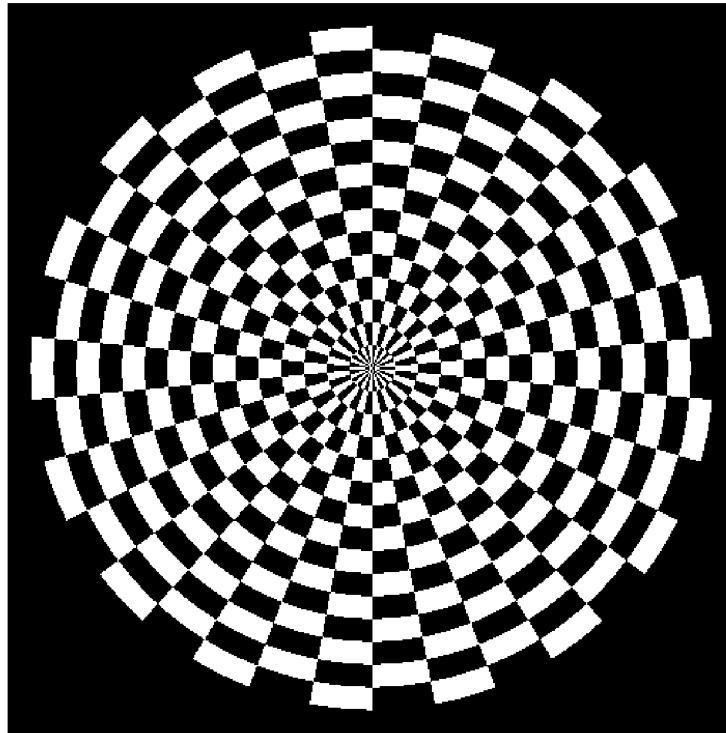
[Images: J. Kukal, 2009]

Reconstruction from 64 angles



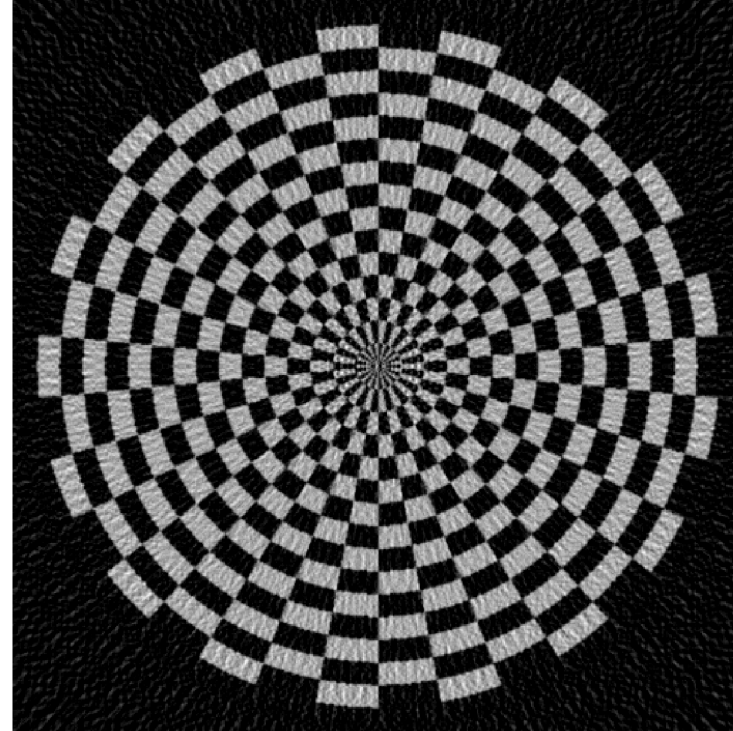
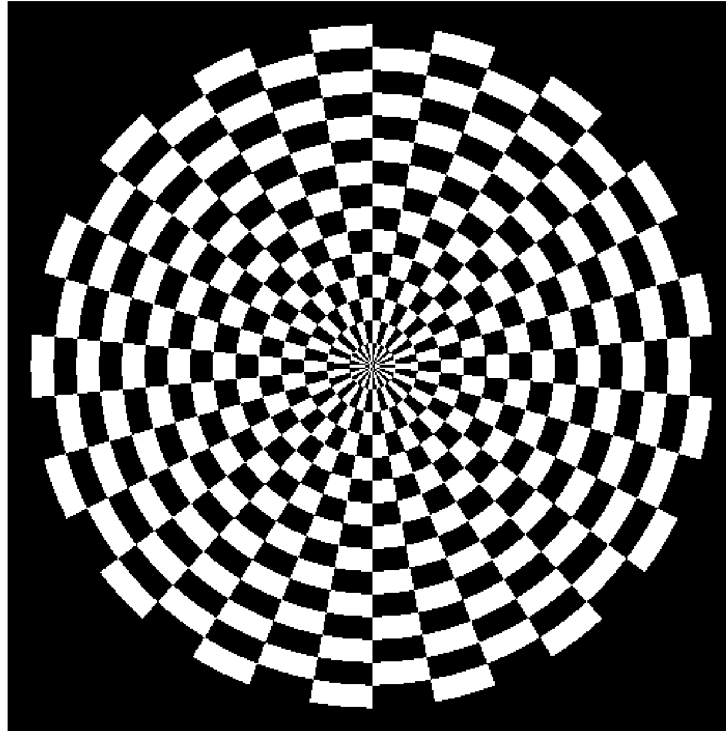
[Images: J. Kukal, 2009]

Reconstruction from 96 angles



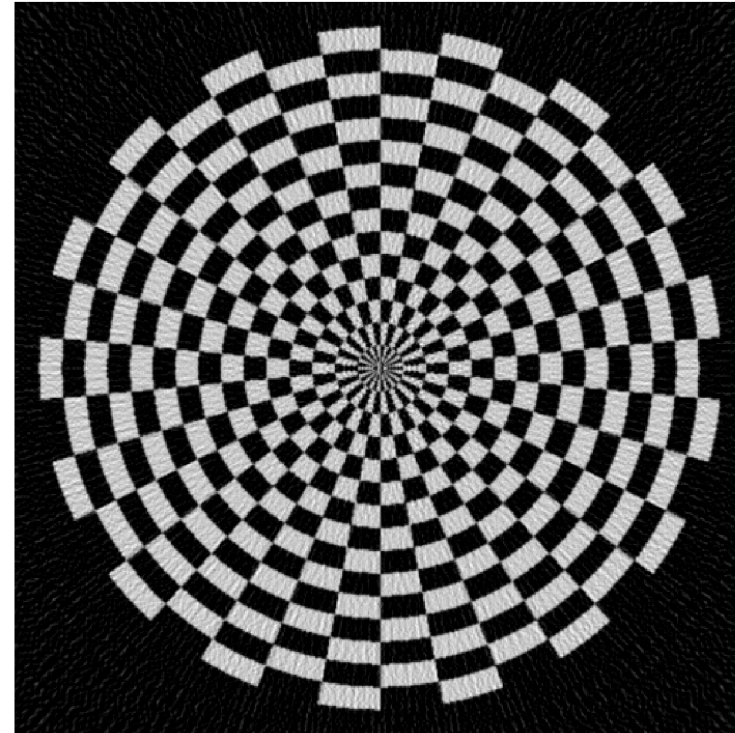
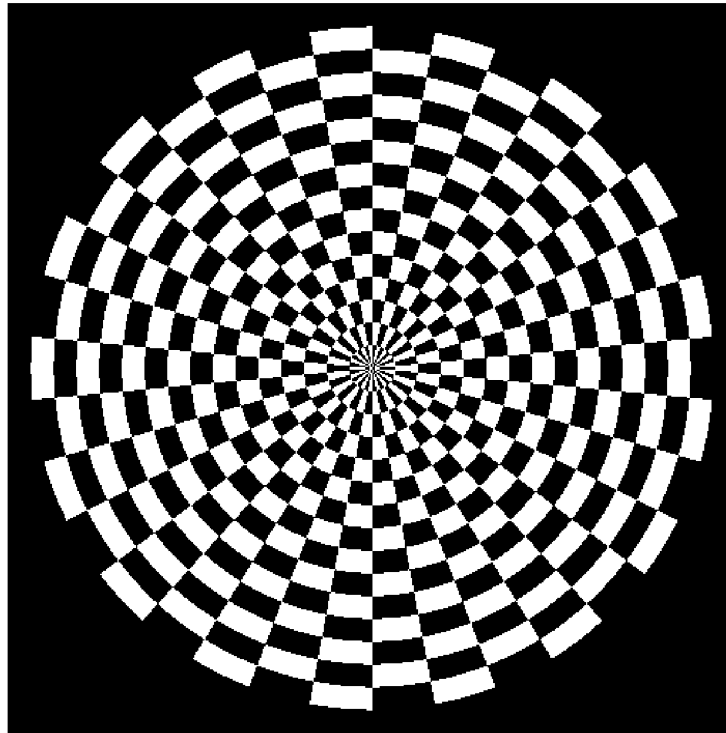
[Images: J. Kukal, 2009]

Reconstruction from 128 angles



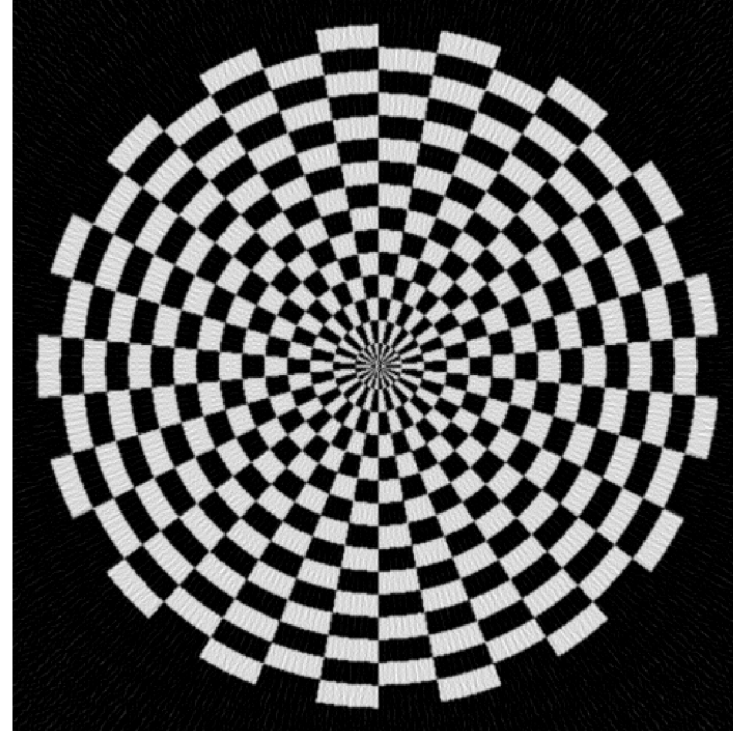
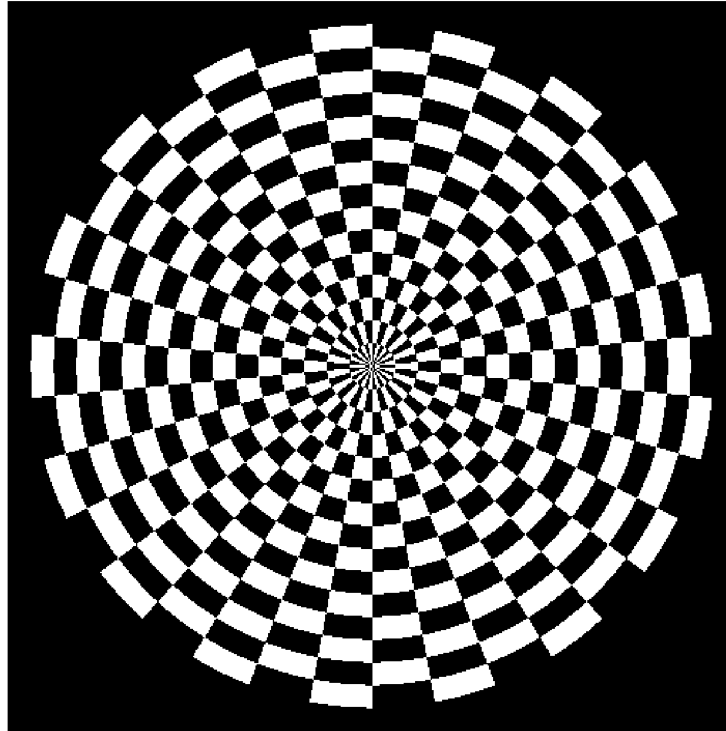
[Images: J. Kukal, 2009]

Reconstruction from 180 angles



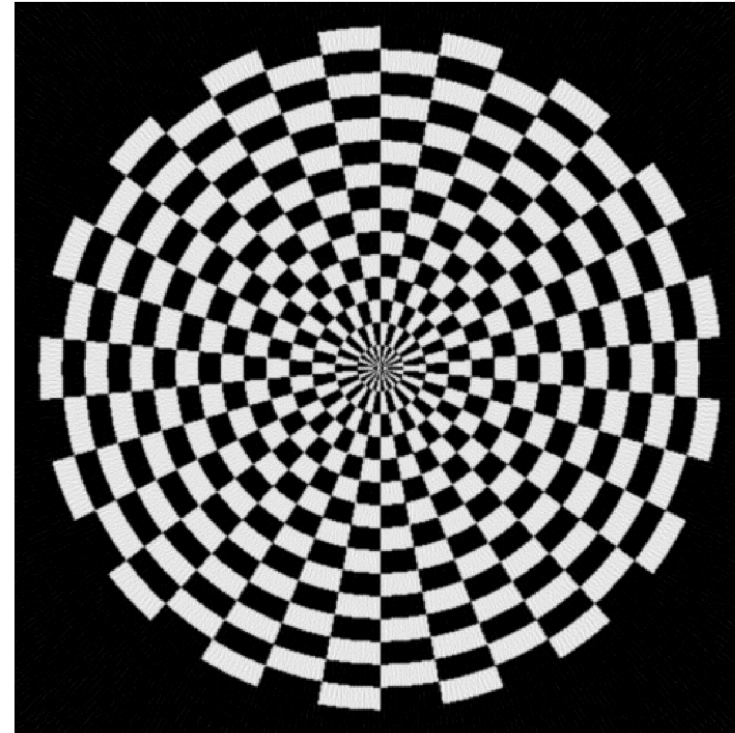
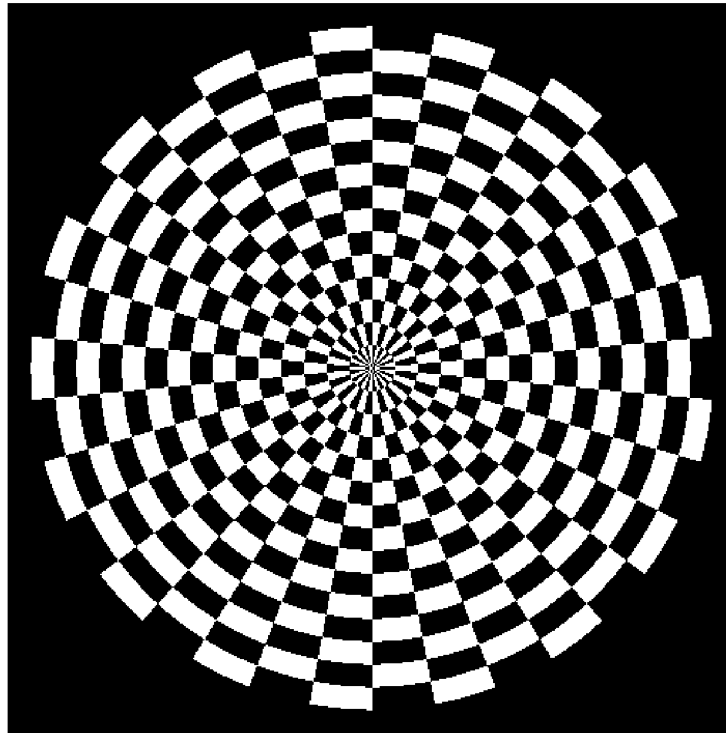
[Images: J. Kukal, 2009]

Reconstruction from 256 angles



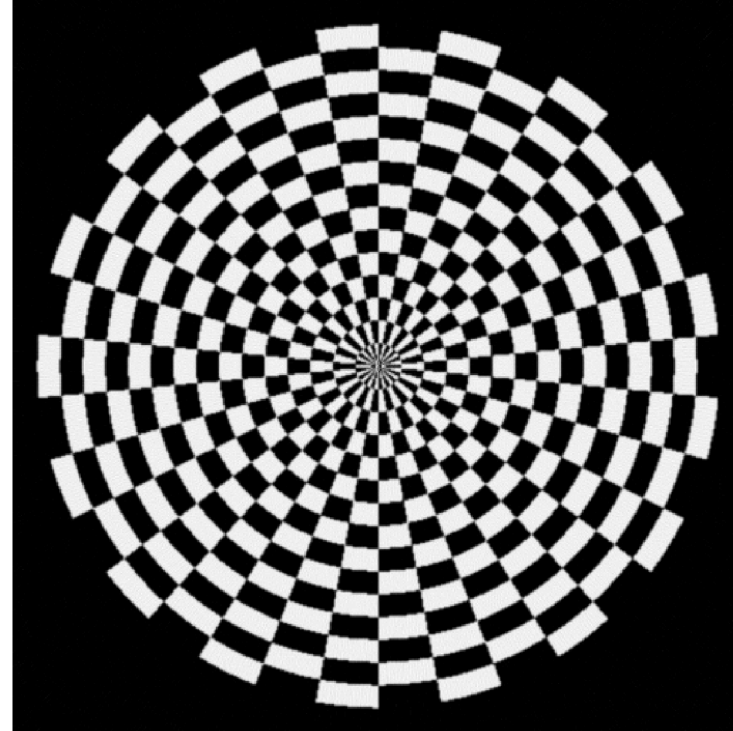
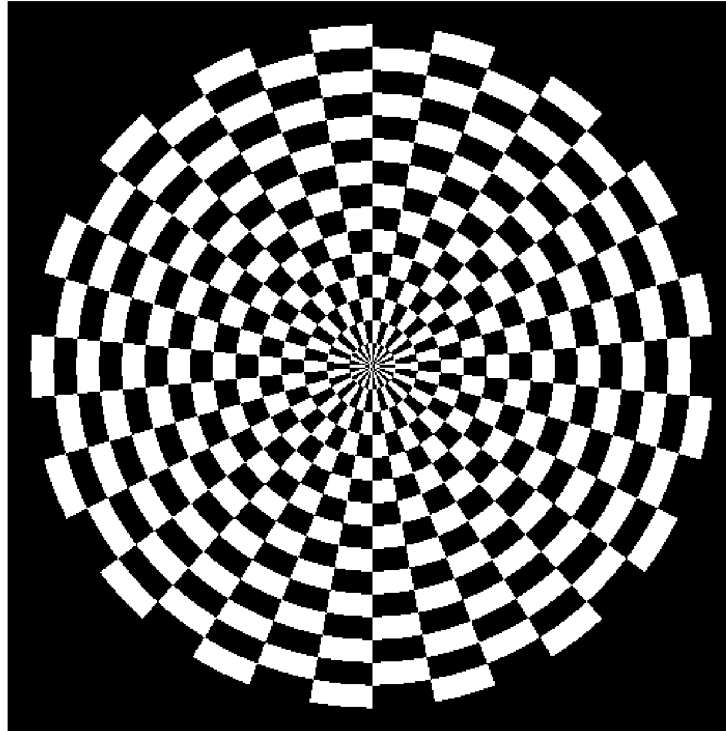
[Images: J. Kukal, 2009]

Reconstruction from 360 angles



[Images: J. Kukal, 2009]

Reconstruction from 512 angles

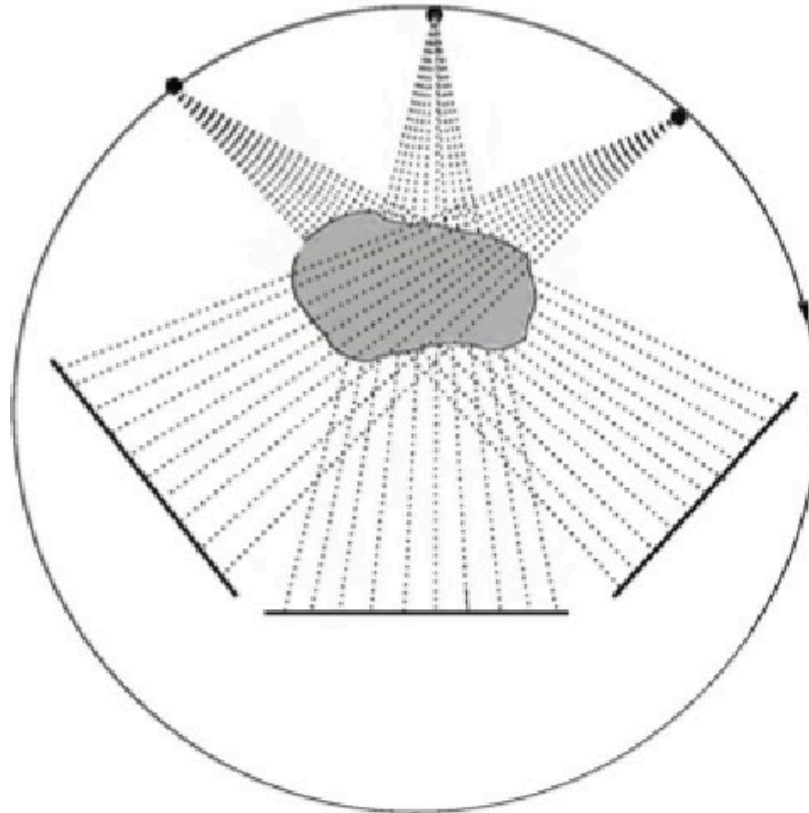


[Images: J. Kukal, 2009]

Medical Tomography



- Upgrade to 3D reconstruction from 2D images...





DL and Radon Transform

- <https://ieeexplore.ieee.org/document/8950464>
- <https://ieeexplore.ieee.org/document/9507793>
- chrome-extension://efaidnbnmnnnibpcajpcglclefindmkaj/https://iopscience.iop.org/article/10.1088/1361-6420/aba415/pdf