

Polynomial and Piecewise Polynomial Interpolation.

Given $(n+1)$ data points

$$(x_0, y_0) \quad (x_1, y_1) \quad \dots \quad (x_n, y_n)$$

find a polynomial of degree at most n that exactly fits these points.

$$y_i = \sum_{j=0}^n c_j x_i^j \quad i = 0, 1, \dots, n$$

plugging in each of the $(n+1)$ points, we have

$$\begin{bmatrix}
 1 & x_0 & x_0^2 & \dots & x_0^n \\
 1 & x_1 & x_1^2 & \dots & x_1^n \\
 \vdots & \vdots & \vdots & \ddots & \vdots \\
 1 & x_n & x_n^2 & \dots & x_n^n
 \end{bmatrix}
 \begin{bmatrix}
 c_0 \\
 c_1 \\
 \vdots \\
 c_n
 \end{bmatrix}
 =
 \begin{bmatrix}
 y_0 \\
 \vdots \\
 y_n
 \end{bmatrix}$$

This is called the vandermonde form.

The matrix is typically ill conditioned and the system is expensive to solve.

Can we do better?

Lagrange form.

Once again, given points

$$(x_0, y_0), (x_1, y_1) \dots (x_n, y_n)$$

What is a polynomial that is nonzero only at x_0 but zero at $x_1, x_2 \dots x_n$?

$$(x-x_1)(x-x_2)(x-x_3) \dots (x-x_n)$$

What is the polynomial that is 1 at x_0 and zero everywhere else ?

$$\frac{(x-x_1)(x-x_2)(x-x_3) \dots (x-x_n)}{(x_0-x_1)(x_0-x_2) \dots (x_0-x_n)}$$

What is the polynomial that is y_0 at x_0 and zero at all other points ?

$$\frac{(x-x_1)(x-x_2) \dots (x-x_n)}{(x_0-x_1)(x_0-x_2) \dots (x_0-x_n)} \cdot y_0$$

Do the same for all the other points and add the polynomials to get the answer !

$$\phi_i(x) = \prod_{j \neq i} \frac{x - x_j}{x_i - x_j}$$

$$p(x) = \sum_{i=0}^n y_i \phi_i(x)$$

This is called the Lagrange form.

Easy to write, but it takes n^2 time to evaluate.

It has $O(n)$ terms, each requiring $O(n)$ operations.

Example. Find a degree 2 polynomial that goes through

$(1, 2), (2, 3), (3, 6)$

$$\phi_0(x) = \frac{(x-2)(x-3)}{(1-2)(1-3)} \quad \phi_1(x) = \frac{(x-1)(x-3)}{(2-1)(2-3)}$$

$$\phi_2(x) = \frac{(x-1)(x-2)}{(3-1)(3-2)}$$

$$P(x) = 2 \cdot \phi_0(x) + 3 \cdot \phi_1(x) + 6 \cdot \phi_2(x)$$

This is $x^2 - 2x + 3$.

Newton form.

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Consider the form

$$p(x) = a_0 + a_1 (x-x_0) + a_2 (x-x_0)(x-x_1) + \dots + a_n (x-x_0)(x-x_1)\dots(x-x_{n-1})$$

What happens when $x = x_0$?

$$p(x_0) = a_0 = f(x_0) = y_0$$

$$p(x_1) = a_0 + a_1 (x_1 - x_0) = y_1$$

$$p(x_2) = a_0 + a_1 (x_2 - x_0) + a_2 (x_2 - x_0)(x_2 - x_1) = y_2$$

⋮

$$A = \begin{bmatrix} 1 & & & & & \\ 1 & (x_1 - x_0) & & & & \\ 1 & (x_2 - x_0) & (x_2 - x_0)(x_2 - x_1) & & & \\ \vdots & \vdots & \vdots & \vdots & \vdots & \\ 1 & (x_n - x_0) & (x_n - x_0)(x_n - x_1) & \dots & \dots & (x_n - x_0)(x_n - x_1) \dots (x_n - x_{n-1}) \end{bmatrix}$$

$$A \cdot \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ \vdots \\ y_n \end{bmatrix}$$

Example.

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Consider again $(1, 2), (2, 3), (3, 6)$

In newton form, we get

$$\begin{pmatrix} 1 & & & \\ 1 & 1 & & \\ 1 & 2 & 2 & \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \\ 6 \end{pmatrix}$$

$$a_0 = 2, \quad a_1 = 1, \quad a_2 = 1$$

We get $p(x) = x^2 - 2x + 3$ again.

Example

Say we now add another point $(5, 7)$

The system becomes

$$\begin{pmatrix} 1 & & & & \\ 1 & 1 & & & \\ 1 & 2 & 2 & & \\ 1 & 4 & 12 & 24 & \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \\ 6 \\ 7 \end{pmatrix}$$

The values of a_0, a_1, a_2 do not change

We can immediately substitute and find

$$a_3 = -\frac{11}{24}$$

Divided difference form.

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Say you are given two points

$$(x_0, y_0), (x_1, y_1)$$

and you want to fit a line using newtons form

$$P(x) = a_0 + a_1(x - x_0) =$$

$$\text{At point } x = x_0, P(x_0) = f(x_0)$$

$$\therefore f(x_0) = a_0$$

$$\text{At point } x = x_1, P(x_1) = f(x_1)$$

$$f(x_1) = f(x_0) + a_1(x_1 - x_0)$$

$$a_1 = \frac{f(x_1) - f(x_0)}{x_1 - x_0} = F[x_1, x_0]$$

$$P(x) = f(x_0) + F[x_1, x_0] \cdot (x - x_0)$$

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Now consider a quadratic.

$$(x_0, y_0) \quad (x_1, y_1) \quad (x_2, y_2)$$

$$P(x) = f(x_0) + \frac{f(x_1) - f(x_0)}{(x_1 - x_0)} \cdot (x - x_0) \\ + a_2 (x - x_0)(x - x_1)$$

We just added (x_2, y_2) and we had noted that this does not change prev. coefficients.

At (x_2, y_2) we have

$$f(x_2) = f(x_0) + \frac{f(x_1) - f(x_0)}{(x_1 - x_0)} \cdot (x_2 - x_0) \\ + a_2 (x_2 - x_0)(x_2 - x_1)$$

Solving for a_2 , we get

$$a_2 = \frac{\frac{f(x_2) - f(x_1)}{x_2 - x_1} - \frac{f(x_1) - f(x_0)}{x_1 - x_0}}{x_2 - x_0} \\ = \frac{F[x_2, x_1] - F[x_1, x_0]}{x_2 - x_0} = F[x_2, x_1, x_0]$$

In general,

$$a_0 = f(x_0)$$

$$a_1 = f[x_1, x_0]$$

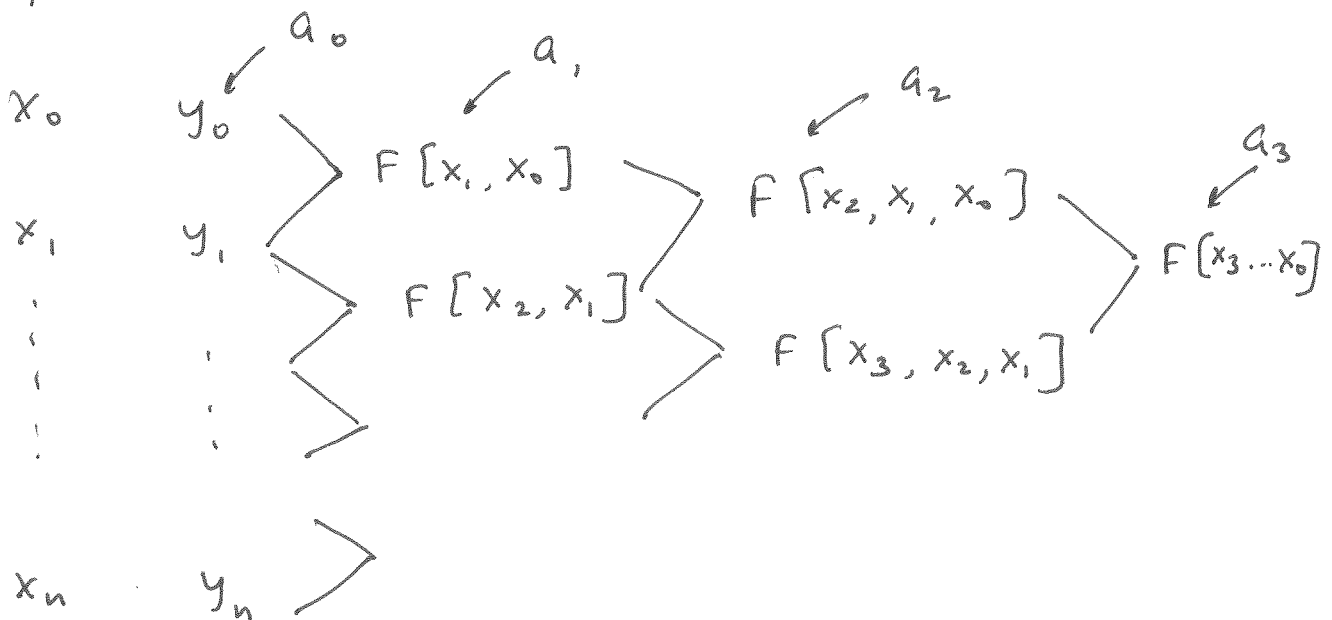
$$a_2 = f[x_2, x_1, x_0]$$

⋮

$$a_m = f[x_m \dots x_0] \quad 1 \leq m \leq n$$

$$f[x_m \dots x_0] = \frac{f[x_m \dots x_1] - f[x_{m-1} \dots x_0]}{x_m - x_0}$$

Computing these divided differences.



Divided Difference Example

(1, 2) (2, 3) (3, 6)

x	y	$F[x_i, x_{i+1}]$	$F[x_i, x_{i+2}]$
1	2	$\leftarrow a_0$	
2	3	1	$\leftarrow a_1$
3	6	3	1 $\leftarrow a_2$

$$\therefore p(x) = 2 + 1(x-1) + 1(x-1)(x-2)$$