

# SOLVING NONLINEAR EQUATIONS

David F. Gleich · CS 314 · Purdue University

November 27, 2016

## 1 MOTIVATION

Consider launching a projectile from a cannon. The *artillery problem* is to determine where to aim the cannon such that the projectile launched at a fixed velocity will reach a target at a given distance. The height of the projectile, as a function of time  $t$ , follows the equation:

$$\begin{aligned}
y''(t) &= -g - ky'(t), \text{ where} \\
y'(0) &= v_0 \sin \theta \quad \text{initial velocity} \\
y(0) &= 0 \quad \text{initial position.}
\end{aligned}$$

In this case,  $\theta$  is the angle of the cannon and  $v_0$  is the total velocity of the projectile, so The coefficient  $g$  models the effect of gravity. The coefficient  $k$  models the air resistance, which is proportional to velocity. The solution of this differential equation can be found analytically:

$$y(t) = -\frac{1}{k}e^{-kt}v_0 \sin \theta - \frac{g}{k}\left(t + \frac{1}{k}e^{-kt}\right) + \frac{1}{k}v_0 \sin \theta + \frac{g}{k^2}.$$

The projectile hits the ground when  $y(t) = 0$  and  $t > 0$  (since it starts on the ground). Let  $t_{\text{impact}}$  be this time. The horizontal position satisfies the equation:

$$x''(t) = -kx'(t), x'(0) = v_0 \cos \theta, x(0) = 0.$$

Notice that this has an identical form with  $g = 0$ , thus, we have:

$$x(t) = \left(\frac{1}{k} - \frac{1}{k}e^{-kt}\right)v_0 \cos \theta.$$

The horizontal distance the projectile travels is:

$$x(t_{\text{impact}}).$$

**The problem** Given that we want  $x(t_{\text{impact}}) = d$  (the distance to a target),  $v_0, k, g$ , how do we choose  $\theta$ ?

**General form** Note that  $x(t_{\text{impact}})$  can be computed by a computer function that depends on  $d, v_0, k, g, \theta$ . Let  $f(\theta)$  be this function as  $\theta$  varies. We want to find  $\theta$  such that  $f(\theta) = d$ .

**Why is this form general?** In both of the previous two examples, we wanted to solve  $f(x) = c$  for some value of  $c$ . In the artillery problem, this was  $f(\theta) = d$ ; and in the backward Euler example, this was  $f(a) = (0.1)(0.1 + 1)$ .

**Quiz** Why do you think we state the problem in the form  $f(x) = 0$  instead of  $f(x) = c$ ?

Consider the nonlinear ordinary differential equation:

$$y'(t) = (t + 1)e^{-y}, y(0) = 0$$

If we apply the backwards Euler method with timestep  $h = 0.1$ , then we need to solve:

$$\frac{y(h) - y(0)}{h} = f(h, y(h)),$$

or, with all the variables substituted:

$$\frac{y(0.1) - 0}{0.1} = (0.1 + 1)e^{-y(0.1)}.$$

Let  $y(0.1) = a$  be the unknown we are trying to solve for. Then:

$$ae^a = (0.1)(0.1 + 1).$$

**The problem** There is no analytic formula for solutions of such equations. By convention, solutions are referred to through the product-log function or Lambert's W function. We need a way to solve this function in order to use our backwards Euler method!

**General form** Again, note that this problem can be written

$$\text{find } a \text{ such that } f(a) = c.$$

## 2 NONLINEAR EQUATIONS

The general problem of solving nonlinear equations is to find  $x$  such that:

$$f(x) = 0.$$

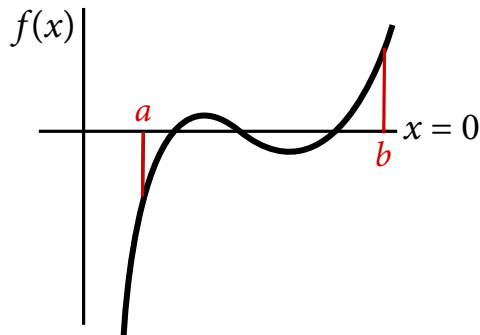
The function  $f$  may be a scalar function  $f : \mathbb{R} \mapsto \mathbb{R}$  or a multivariate function  $f : \mathbb{R}^m \mapsto \mathbb{R}^n$ . In this class, we'll only briefly mention the multivariate case.

### 3 THE BISECTION ALGORITHM

**Assumptions** The function  $f$  is continuous, scalar ( $f : \mathbb{R} \mapsto \mathbb{R}$ ).

In this case, then the function's behavior is not arbitrary. If  $f$  is continuous, and we have two values  $a$  and  $b$  of  $x$  such that  $f(a)$  and  $f(b)$  have different signs, then the function  $f$  must have a point where  $f(x) = 0$  between  $a$  and  $b$ .<sup>1</sup>

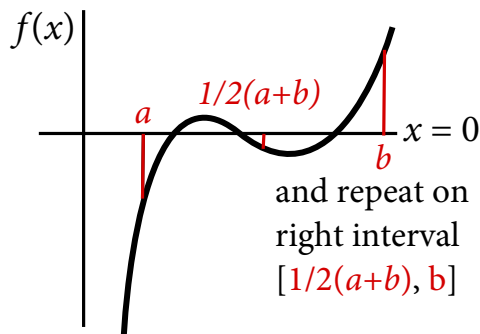
<sup>1</sup> This is a corollary of the intermediate value theorem if you like such things!



In this example, it has three such points! So these points need not be unique. But, if we evaluate  $f((a+b)/2)$ , then one of three things can happen:

1.  $f((a+b)/2)$  has the same sign as  $f(a)$
2.  $f((a+b)/2)$  has the same sign as  $f(b)$
3.  $f((a+b)/2) = 0$ .

If  $f((a+b)/2)$  has the same sign as  $f(a)$ , then we know that  $[(a+b)/2, b]$  is a smaller subinterval that must contain a value of  $x$  where  $f(x) = 0$ . Likewise, if  $f((a+b)/2)$  has the same sign as  $f(b)$ , then we know that  $[a, (a+b)/2]$  is a smaller subinterval that must contain a value of  $x$  where  $f(x) = 0$ . Finally, if  $f((a+b)/2) = 0$ , then we are done and can just return that value of  $x$ .



In this case  $f((a+b)/2)$  has the same sign as  $f(a)$ .

```

1 function x0 = bisection(f, a, b, Δ)
2 % BISECTION Find a point where f(x) = 0 through bisection
3 % x0 = bisection(f, a, b, Δ) does an interval bisection search
4 % to find a region of size Δ that contains a zero of
5 % the function f, by default Δ = 2.2e-16, the machine eps.
6 fa = f(a); fb = f(b); assert(sign(fa*fb) ≤ 0); maxit = 52;
7 for i=1:maxit
8     ab2 = 0.5*a + 0.5*b; fab2 = f(ab2); if abs(fab2) < eps, break; end
9     if abs(b-a) ≤ Δ, break; end
10    if sign(fab2*fb) ≤ 0, a = ab2; fa = fab2;
11    else b = ab2; fb = fab2; end
12 end
13 x0 = ab2;

```

## NEWTON'S METHOD

The bisection method has one key problem: it requires  $a$  and  $b$  such that  $f(a)$  and  $f(b)$  have different signs. So we could never use it to solve  $f(x) = x^2 = 0$ . Newton's method is an alternative based on the following picture:

In words, if we know the derivative at the current point  $x$ , then we can use a linear approximation based on the gradient to find a point  $y$  that should be closer to a zero of the function  $f$ . This gives rise to the *iteration*

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}.$$

We can also derive Newton's method from Taylor's theorem. Recall that for a twice continuously differentiable function  $f$ , that

$$f(x+h) = f(x) + hf'(x) + \frac{1}{2}h^2 f''(\xi).$$

**Notation** We often write the solution of  $f(x) = 0$  as  $x^*$ . So  $f(x^*) = 0$ .

**Notation** Writing  $x_k$  means the  $k$ th choice of  $x$  in the sequence generated by our algorithm.

**Notation** The variable  $x_0$  is usually the starting point of our iteration. In most computer implementations, the user needs to provide this choice.

**Theorem 4.3.1** If  $x_0$  is *sufficiently close* to  $x^*$ , then the sequence of iterates generated by Newton's method converges to a solution *quadratically fast*.

**Interpretation** For each root of the equation  $x^*$ , there is some region around  $x^*$  where if we start Newton's method, then it'll get to the solution  $x^*$ . The precise form of this region is really hard to state as it involves the term  $\xi$  from Taylor's theorem and a bunch of approximations on *continuous functions* that are easy to state and hard to quantify. The term *quadratically fast* means *really fast!*. Here's an example. If  $x_k \rightarrow 0$ , then a quadratic sequence looks like:

0.1 0.01 0.0001 0.00000001 0.0000000000000001 0.00000000000000000000000000000001

**Note** Since Newton's method may diverge, *if* you ever detect that the sign of the function changes as you are running Newton's method, *then* you can combine Newton and bisection in order to guarantee convergence.

## 4 FUN WITH NEWTON'S METHOD

There are many really interesting things you can do with Newton's method. Suppose someone gave you a calculator with a broken "division" key. If you are familiar with Newton's method, you can still compute  $a/b$  with ease!

*Idea 1* The term  $a/b$  is the solution of  $bx - a = 0$ . So maybe we should apply Newton's method here, but that just leads to  $x_{k+1} = x_k - \frac{bx_k - a}{b} = a/b$ . While it's nice that this is correct, we can't evaluate this term without the division symbol.

If you had enough time, you'd all come up with this idea, I promise! Consider:

$$f(x) = \frac{1}{x} - b.$$

Then  $f(x) = 0$  when  $x = 1/b$ ; and so we can multiply the resulting answer by  $a$ . If we apply Newton's method, then

$$x_{k+1} = x_k - \frac{\frac{1}{x_k} - b}{-\frac{1}{x_k^2}} = x_k + x_k^2 \left( \frac{1}{x_k} - b \right) = x_k(2 - bx_k).$$

To continue with this idea, we'd need show whether or not this idea converges for all values  $b$  or not. But this illustrates one of the most common uses of Newton's method! You can compute complicated functions through much more simple operations.

## 5 THE SECANT METHOD

One annoying feature of Newton's method is that we need a function to evaluate  $f'(x)$  as well as  $f(x)$ . This requires more work for people to use (bad), and is often a source of bugs that lead to the method failing (double-bad!). In the secant method, we do the *lazy* thing and approximate  $f'(x) \approx \frac{1}{h}(f(x+h) - f(x))$ . But, we can be even smarter! Since we have a sequence of iterations  $x_k$ , just use the approximation

$$f'(x) \approx \frac{f(x_k) - f(x_{k-1})}{x_k - x_{k-1}}.$$

Thus, secant method is:

$$x_{k+1} = x_k - \frac{f(x_k)(x_k - x_{k-1})}{f(x_k) - f(x_{k-1})}.$$

To start the Secant method, we need either,  $x_0$  and  $x_1$  or we can approximate  $f'(x_0)$  via a finite difference formula for the first step. (Your book doesn't discuss this, but it's a reasonable idea.)

See Lemma 4.4.1 for a proof of convergence.

## 6 FIXED POINT METHODS

There is another class of methods to solve  $f(x) = 0$ , or non-linear equations in general. These are called *fixed point methods* and they study solutions of:

$$g(x) = x.$$

These *fixed points* come up so often that they get their own name. The PageRank method is an example of a linear fixed point equation (for a matrix!).

### 6.1 FIXED POINTS ARE EQUIVALENT TO NONLINEAR EQUATIONS

If  $g(x) = x$ , then  $f(x) = g(x) - x = 0$  is an equivalent problem.

If  $f(x) = 0$ , then  $g(x) = f(x) + x = x$  is an equivalent problem. So is  $g(x) = -f(x) + x$ .

The fixed point statement implies an algorithm:

$$x_{k+1} = g(x_k).$$

See Theorem 4.5.2 for a convergence statement.