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Summary

- We describe an autonomous Artificial Intelligence (AI) system to analyze burns using multiple modalities including ultrasound and RGB images.
- We assess the system's ability to predict burn depth and relative surface area.
- Classification is implemented as a deep convolutional network that makes use of GLCM texture features_[4].
- Segmentation for burn area prediction is accomplished using a modified U-net convolutional autoencoder.
- Classification results are further visualized and explained via a LIME-based_[2] Explainable AI (XAI) subsystem. This information is used to improve the system's accuracy and reliability.



Background



XAI algorithms can be split into global and local – explaining a whole model or a single data point prediction – or into model/algorithm agnostic and specific.

- The outcome for any burn patient is determined greatly by the percent total body surface area (%TBSA) and the depth of the burn.
- In the military setting, burn casualties correspond to roughly 8% of combatrelated injuries.
- Four classes of burn depth determine the treatment options for the patient.
- Explainable AI (XAI) is often used to understand and validate AI decisionmaking in the medical domain.



Results

Burn Image Prediction Target

Some segmentation results. The U-net prediction closely matches the ground truth target. This can be used to calculate the burn area of the displayed skin.

- Classify burn wounds with a mean accuracy greater than 90% Segment burn wounds with a mean global accuracy greater
- 0.87, and a mean intersection-over-union (IoU) score of ~0.

| Classification Results at 3 Time Points | | | | | Classification Results Algorithm Comparison | | | | | | | |
|--|----------|-----------|--------|-------------|--|----------|--------------------|--------------|---------------|---------------|---------------|---------------|
| Days | Accuracy | Precision | Recall | F1 Score | | Method | Featur (img, te | es x) | Accuracy | Precision | Recall | F1 Score |
| Day 0 | 0.9379 | 0.9474 | 0.9403 | 0.9414 | | RBF SVM | × | \checkmark | 0.4830 | 0.5433 | 0.4654 | 0.4745 |
| Day 3 | 0.8821 | 0.9072 | 0.8714 | 0.8787 | | VGG16 | ✓ | X | 0.8898 | 0.9217 | 0.8790 | 0.8837 |
| Day 7 | 0.9497 | 0.9466 | 0.9412 | 0.9397 | | ResNet34 | ~ | X | 0.8963 | 0.9219 | 0.8860 | 0.8933 |
| Total | 0.9252 | 0.9373 | 0.9172 | 0.9235 | | Ours | ~ | ✓ | <u>0.9257</u> | <u>0.9374</u> | <u>0.9182</u> | <u>0.9242</u> |
| | | | | | | | | | | | | |

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Burn Classification & Explanation

- We use convolutional neural networks (CNNs) to learn progressively richer features from the data and then use these features to train task-specific networks.
- Pre-trained models are used as a base, and then finetuned to our task. This reduces the number of training samples needed.
- We further enhance our classifier using traditional computer vision features (GLCM texture) that have been shown to be effective on ultrasound data.
- We make use of a human-in-the-loop system that utilizes explainable AI to improve our prediction models and verify our results.





Our classification model. This makes use of a pre-trained ResNet34 Output information after classification and explanation. Blue component modified with dropout to reduce overfitting to our small features in heatmap indicate support for prediction. Red features dataset. GLCM texture features are extracted and included as indicate contradiction of prediction. features in the final stage of the classifier.



| | Segmentation Results | | | | | | | | |
|-----------|----------------------|--------------|------------------------------|--------------------------------|-------|--|--|--|--|
| | Metric | Stoc (Mea | k U-Net n, Stddev) | Custom U-Net (Mean, Stddev) | | | | | |
| , | Global Accuracy | 0.783 | 0.033 | <u>0.872</u> | 0.008 | | | | |
| %. han | loU | 0.664 | 0.041 | <u>0.784</u> | 0.012 | | | | |



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To predict the surface area of the burn, we must segment the body and the burned region. • We used a modified U-net₁₃₁ to learn burn segmentation.</sub> The general U-net architecture has shown consistently good results on medical image segmentation tasks_[1]. Batch normalization and dropout operations were added to reduce the risk of overfitting given our small dataset.



Burn Segmentation



Our segmentation U-net model. Each convolutional block is composed of a 2D convolutional layer, a batch normalization, and a ReLU activation. The final block omits the normalization and activation.

Data

- In-vivo B-mode ultrasound and Tissue Doppler Imaging (TDI) scans collected from porcine subjects.
- The GE Logiq E9 device was used to generate HUSD B-mode and Tissue Doppler elastography Imaging videos simultaneously.
- RGB images for segmentation were manually collected from Google Images, and hand-annotated with the supervision of clinicians.

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